GigaDevice Semiconductor Inc.

Arm[®] Cortex[®]-M3 32-bit MCU

应用笔记 AN028



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1. Hard fault 产生原因

1.1 硬件方面常见原因:

- 电源设计有错误,造成器件供电不稳;
- 电源质量不好, 文波, 噪声过大;
- 器件接地不良;
- 对于带有 Vcap 引脚的器件,管脚处理不当;
- 电路中有强干扰源,对器件造成干扰;

1.2 软件方面常见原因:

- 使用了空指针;
- 对地址偏移量的计算有误;
- 数组越界导致程序出错;
- 动态内存使用不当,导致访问了已释放的内存地址;
- 通过地址访问了已失效的局部变量;

一般因为硬件造成 Hard Fault 错误的可能性较低,大多数都是软件原因造成的。所以遇到硬件中断错误,基本就是通过软件来排查。



2. Cortex-M3 内核 HardFault 错误定位方法

2.1 更改 startup.s 的启动文件

首先更改 startup.s 的启动文件,把里面的 HardFault_Handler 代码段换成下面的代码:

lardFault_Handler\				
	PROC			
	IMPORT hard_fault_handler_c			
	TST LR, #4			
	ITE EQ			
	MRSEQ R0, MSP			
	MRSNE R0, PSP			
	B hard_fault_handler_c			
	ENDP			

2.2 hard_fault_handler_c 函数

然后把 hard_fault_handler_c 函数放在 c 文件的代码中。代码如下:

void	hard_fault_handler_c(unsigned int * hardfault_args)
{	
	static unsigned int stacked_r0;
	static unsigned int stacked_r1;
	static unsigned int stacked_r2;
	static unsigned int stacked_r3;
	static unsigned int stacked_r12;
	static unsigned int stacked_lr;
	static unsigned int stacked_pc;
	static unsigned int stacked_psr;
	static unsigned int SHCSR;
	static unsigned char MFSR;
	static unsigned char BFSR;



static unsigned short int UFSR; static unsigned int HFSR; static unsigned int DFSR; static unsigned int MMAR; static unsigned int BFAR; stacked_r0 = ((unsigned long) hardfault_args[0]); stacked_r1 = ((unsigned long) hardfault_args[1]); stacked r2 = ((unsigned long) hardfault args[2]); stacked r3 = ((unsigned long) hardfault args[3]);stacked_r12 = ((unsigned long) hardfault_args[4]); /*异常中断发生时,这个异常模式特定的物理寄存器 R14,即 lr 被设置成该异常模式将要 返回的地址*/ stacked_lr = ((unsigned long) hardfault_args[5]); stacked_pc = ((unsigned long) hardfault_args[6]); stacked_psr = ((unsigned long) hardfault_args[7]); SHCSR = (*((volatile unsigned long *)(0xE000ED24))); //系统 Handler 控制及状态寄存 器 MFSR = (*((volatile unsigned char *)(0xE000ED28))); //存储器管理 fault 状态寄存器 BFSR = (*((volatile unsigned char *)(0xE000ED29))); //总线 fault 状态寄存器 UFSR = (*((volatile unsigned short int *)(0xE000ED2A)));//用法 fault 状态寄存器 HFSR = (*((volatile unsigned long *)(0xE000ED2C))); //硬 fault 状态寄存器 DFSR = (*((volatile unsigned long *)(0xE000ED30))); //调试 fault 状态寄存器 MMAR = (*((volatile unsigned long *)(0xE000ED34))); //存储管理地址寄存器 BFAR = (*((volatile unsigned long *)(0xE000ED38))); //总线 fault 地址寄存器 while (1);

执行程序后,若发生内核错误,则程序会运行到最后的 while(1)处。此时观察相应的堆栈和故



Cortex-M3 内核 HardFault 错误调试定位方法

障寄存器值, stacked Ir 即为故障发生时进入故障中断前 pc 的值, 在 MDK 软件调试状态下, 假如 stacked_lr 的值为 0x1A002D08,在左下方的命令窗口输入"pc = 0x1A002D08",回车, 即可定位发生错误的代码位置。

Cortex-M3 内核错误寄存器说明 2.3

根据内核错误状态寄存器的值,对应下面的说明,也可以看出是发生了何种内核错误。

附录: Cortex-M3 内核错误寄存器说明

表D.17 系统Handler控制及状态寄存器SHCSR 0xE000_ED24

位段	名称	类型	复位值	描述
18	USGFAULTENA	R/W	0	用法 fault 服务例程使能位
17	BUSFAULTENA	R/W	0	总线 fault 服务例程使能位
16	MEMFAULTENA	R/W	0	存储器管理 fault 服务例程使能位
15	SVCALLPENDED	R/W	0	SVC 悬起中。本来已经要 SVC 服务例程,但
				是却被更高优先级异常取代
ូ14	BUSFAULTPENDED	R/W	0	总线 fault 悬起中,细节同上。
ូ13	MEMFAULTPENDED	R/W	0	存储器管理 fault 悬起中,细节同上
ូ12	USGFAULTPENDED	R/W	0	用法 fault 悬起中,细节同上
"11	SYSTICKACT	R/W	0	SysTick 异常活动中
,10	PENDSVACT	R/W	0	PendSV 异常活动中
J <mark>9</mark>	-	-	-	-
"8	MONITORACT	R/W	0	Monitor 异常活动中
. 7	SVCALLACT	R/W	0	SVC 异常活动中
.6:4	-	-	-	-
"3	USGFAULTACT	R/W	0	用法 fault 异常活动中
"2	-	-	-	-
1	BUSFAULTACT	R/W	0	总线 fault 异常活动中
0	MEMFAULTACT	R/W	0	存储器管理 fault 异常活动中

表 D.18 存储器管理 fault 状态寄存器(MFSR)

0xE000_ED28

位段	名称	类型	复位值	描述
7	MMARVALID	-	0	=1 时表示 MMAR 有效
6:5	-	-	-	-
4	MSTKERR	R/Wc	0	入栈时发生错误
3	MUNSTKERR	R/Wc	0	出栈时发生错误
2	-	-	-	-
1	DACCVIOL	R/Wc	0	数据访问违例
0	IACCVIOL	R/Wc	0	取指访问违例

表 D.19 总线 fault 状态寄存器(BFSR)

0xE000_ED29

位段	名称	类型	复位值	描述
7	BFARVALID	-	0	=1 时表示 BFAR 有效
6:5	-	-	-	-
4	STKERR	R/Wc	0	入栈时发生错误
3	UNSTKERR	R/Wc	0	出栈时发生错误
2	IMPRECISERR	R/Wc	0	不精确的数据访问违例(violation)
1	PRECISERR	R/Wc	0	精确的数据访问违例
0	IBUSERR	R/Wc	0	取指时的访问违例

表 D.20 用法 fault 状态寄存器(UFSR),地址:0xE000_ED2A

位段	名称	类型	复位值	描述
9	DIVBYZERO	R/Wc	0	表示除法运算时除数为零(只有在 DIV_0_TRP 置位时才会发生)
8	UNALIGNED	R/Wc	0	未对齐访问导致的 fault
7:4	-	-	-	-
3	NOCP	R/Wc	0	试图执行协处理器相关指令
2	INVPC	R/Wc	0	在异常返回时试图非法地加载EXC_RETURN到 PC。包括非法的指令,非法的上下文以及非法 的值。The return PC 指向的指令试图设置 PC 的值(要理解此位的含义,还需学习后面的讨 论中断级异常的章节)
1	INVSTATE	R/Wc	0	试图切入 ARM 状态
0	UNDEFINSTR	R/Wc	0	执行的指令其编码是未定义的——解码不能

表 D.21 硬 fault 状态寄存器

0xE000_ED2C

位段	名称	类型	复位值	描述
31	DEBUGEVT	R/Wc	0	硬 fault 因调试事件而产生
30	FORCED	R/Wc	0	硬 fault 是总线 fault,存储器管理 fault 或是 用法 fault 上访的结果
29:2	-	-	-	-
1	VECTBL	R/Wc	0	硬 fault 是在取向量时发生的
0	-	-	-	-



AN028 Cortex-M3 内核 HardFault 错误调试定位方法

表 D.22 调试 fault 状态寄存器(DFSR) 0xE000 ED30

位段	名称	类型	复位值	描述
4	EXTERNAL	R/Wc	0	EDBGREQ 信号有效
3	VCATCH	R/Wc	0	发生向量加载
2	DWTTRAP	R/Wc	0	发生 DWT 匹配
1	BKPT	R/Wc	0	执行到 BKPT 指令
0	HALTED	R/Wc	0	在 NVIC 中请求 HALT

表 D.23 存储管理地址寄存器(MMAR) 0xE000_ED34

位段	名称	类型	复位值	描述	
31:0	MMAR	R	-	触发存储管理 fault 的地址	

表 D.24 总线 fault 地址寄存器(BFAR) 0xE000_ED38

位段	名称	类型	复位值	描述
31:0	BFAR	R	-	触发总线 fault 的地址



3. 通过 Jlink 排查 keil 程序的 Hard fault 错误

3.1 排查问题使用到的工具:

Jlink, Segger (Jlink 上位机), Keil。

3.2 排查步骤

3.2.1 使用 keil 生成 map 和 lst 文件

Map 文件是 keil 自动生成的,他被放在工程路径下。里面能标明每个函数、每个变量的位置。 lst 文件反映的是每一个函数,每一条指令的 PC 指针,在 keil 中需要调用 USER 命令生成。 如<u>*图* 3-1. Keil 生成 map 和 lst 文件</u>所示。

图 3-1. Keil 生成 map 和 lst 文件

🛚 Options for Target 'HID'							
Device Target Output Listing User C/C++ Asm Linker Debug Utilities							
Run User Programs Before Compilation of a C/C++ File							
🗖 Run #1: 🗌 🗖 DOS16							
Stop Build/Rebuild #1 on Exit Code: Not Specified							
🗆 DOS16							
Stop Build/Rebuild #2 on Exit Code: Not Specified							
Bun Liser Programs Before Build/Behuild							
□ Run #1:							
□ Run #2: □ □ DOS16							
Run User Program tiver Build/Rebuild							
Run # D:\Keil\ARM\ARMCC\bin\fromelf.exe -coutput ./project.lst ./obj/project.axf DOS16							
Run #2: D:\Keil\ARM\ARMCC\bin\fromelf.exebin -o ./project.bin ./obj/project.axf DOS16							
Image: When Complete Image: Complete Imag							
OK Cancel Defaults Help							

D:\Keil\ARM\ARMCC\bin\fromelf.exe -c --output ./project.lst ./obj/project.axf D:\Keil\ARM\ARMCC\bin\fromelf.exe 表示的是 fromelf.exe 的路径;

./obj/project.axf 表示生成的 axf 文件位置,可能需要根据实际情况调整;

3.2.2 保存出问题时候的 RAM

出问题的时候调用。别断电,接上 Jlink,调用 Segger 里面的 Jlink command 来获取现场:

1、先输入一个"USB"让 Jlink 接上设备, 然后输入 halt 来停住内核, 如<u>图 3-2. 输入 halt 来停</u> <u>住内核</u>所示;



图 3-2. 输入 halt 来停住内核

J-Link Commander	- 🗆 🗙
VTarget = 3.285V	
Info: Found SWD-DP with ID 0x1BA01477	
Info: Found Cortex-M3 r2p1, Little endian.	
Info: FPUnit: 6 code (BP) slots and 2 literal slots	
Info: CoreSight components:	
Info: ROMTbl Ø @ EØØFFØØØ	
Info: ROMTb1 0 [0]: FFF0F000, CID: B105E00D, PID: 000BB000 SCS	
Info: ROMTbl 0 [1]: FFF02000, CID: B105E00D, PID: 003BB002 DWT	
Info: ROMTb1 0 [2]: FFF03000, CID: B105E00D, PID: 002BB003 FPB	
Info: ROMTbl 0 [3]: FFF01000, CID: B105E00D, PID: 003BB001 ITM	
Info: ROMTbl 0 [4]: FFF41000, CID: B105900D, PID: 003BB923 TPIU-Lite	
Found 1 JTAG device, Total IRLen = 4:	
Cortex-M3 identified.	
Target interface speed: 100 kHz	
J-Link>halt	
PC = 08000D7C, CycleCnt = 1F02CC57	
R0 = 00000001, R1 = 00000001, R2 = 0000001F, R3 = 00000083	
R4 = 400000000, R5 = 08005BE4, R6 = 000000000, R7 = 00000000	
R8 = 000000000, R9 = 2000016C, R10= 00000000, R11= 00000000	
SP(RI3) = 20000868, MSP = 20000868, PSP = 20000800, R14(LR) = 08001H4D	
$XPSR = 2100001F$: HFSR = n_2Cvq , EFSR = 0100000 , IFSR = $01F$ (INIISRIS)	
CFBP = 00000000, CUNIKUL = 00, FHULIMHSK = 00, BHSEPRI = 00, PRIMHSK = 00	

2、调用 savebin ram.bin 0x2000000 0x2000 将 RAM 中的内容全部保存下来,如<u>图 3-3.保</u> 存RAM 内容所示;

保存下来的东西被存在放 Segger 的安装目录中。

图 3-3. 保存 RAM 内容

J-Link Commander	- 🗆 🗙
Info: FPUnit: 6 code (BP) slots and 2 literal slots	
Info: CoreSight components:	
Info: ROMTbl Ø @ EØØFFØØØ	
Info: ROMTb1 0 [0]: FFF0F000, CID: B105E00D, PID: 000BB000 SCS	
Info: ROMTbl 0 [1]: FFF02000, CID: B105E00D, PID: 003BB002 DWT	
Info: ROMTb1 0 [2]: FFF03000, CID: B105E00D, PID: 002BB003 FPB	
Info: ROMTbl 0 [3]: FFF01000, CID: B105E00D, PID: 003BB001 ITM	
Info: ROMTbl 0 [4]: FFF41000, CID: B105900D, PID: 003BB923 TPIU-Lite	
Found 1 JTAG device, Total IRLen = 4:	
Cortex-M3 identified.	
Target interface speed: 100 kHz	
J-Link>halt	
PC = 08000D7C, CycleCnt = 1F02CC5?	
RØ = 00000001, R1 = 00000001, R2 = 0000001F, R3 = 00000083	
R4 = 40000000, R5 = 08005BE4, R6 = 000000000, R7 = 00000000	
R8 = 00000000, R9 = 2000016C, R10= 00000000, R11= 00000000 Data seconda	
SP(RI3) = 20000868, MSP = 20000868, PSP = 20000800, R14(LR) = 08001H4U	
$XPSR = 2100001F$: HPSR = $n_2 \cup q$, EPSR = 01000000 , IPSR = $01F$ (INIISRIS)	
CPEP = 00000000, CUNIKUL = 00, FHULIMHSK = 00, BHSEPKI = 00, PRIMHSK = 00	
J-Link/savedin ram.bin 0x20000000 0x2000	
Upening binary file for writing [ram.bin]	
Reading 8172 Dytes from addr 0x20000000 into fileV.K.	
Willing the second seco	

3.2.3 分析问题

1、查看 map 文件,找到栈的位置。如<u>图 3-4.从 map 文件中查看栈</u>所示。



图 3-4. 从 map 文件中查看栈

HID. map					
1126					
1127	STACK	0x20000490	Section 10	024	startup_stm32f0xx.o(STACK)
1128					-
1129	Global Symbols				
1130					
1131	Symbol Name	Value Ov	Type S:	ize	Object (Section)
1132					
1133	BuildAttributes\$\$THM_ISAv4\$P\$D\$K\$B\$S\$PE\$	A:L22UL41UL21	X:L11\$S22US41	US21	\$IEEE1\$IW\$USESV6\$~STKCKD\$USESV7\$~S
1134	ARM_use_no_argv	0x00000000	Number	0	main.o ABSOLUTE
1135	cpp_initializeaeabi	- Undefined	Weak Reference	2	
1136	cxa_finalize	- Undefined	Weak Reference	2	
1137	_clock_init	- Undefined	Weak Reference	2	
1138	_microlib_exit	- Undefined	Weak Reference	2	
1139	Vectors_Size	0x0000015a	Number	0	startup_stm32f0xx.o ABSOLUTE
1140	Vectors	0x08000000	Data	4	startup_stm32f0xx.o(RESET)
1141	Vectors_End	0x0800015a	Data	0	startup_stm32f0xx.o(RESET)
1142	main	0x0800015b	Thumb Code	0	entry.o(.ARM.Collect\$\$\$\$00000000)
1143	_main_stk	0x0800015b	Thumb Code	0	entry2.o(.ARM.Collect\$\$\$\$00000001
1144	main_scatterload	0x0800015f	Thumb Code	0	entry5.o(.ARM.Collect\$\$\$\$00000004

2、打开保存的 bin 文件进行分析,找到进入硬件中断前调用了哪些函数,在使用哪个变量。

图 3-5. Bin 文件分析

D:\Program Files\SEGGER\JLink_V502c\Ram.bin						×
Address: 0x20	000000 <u>×1</u>	x2 x4				
Address	0	4	8	С	ASCII	
200007B0	00000000	00000000	00000000	00000000		
200007C0	00000000	00000000	00000000	00000000		
200007D0	00000000	00000000	00000000	00000000		
200007E0	00000000	00000000	00000000	00000000		
200007F0	00000000	00000000	00000000	00000000		
20000800	00000000	00000000	00000000	FFFFFFF1		
20000810	00000004	00000002	0000006	FFFFFFF1		
20000820	0800589E	48000418	4800000	48000428	X.HHK<	
20000830	20000000	0008000	080050D6	0100001F	P	
20000840	000000B	40000000	08005BE4	000000000		
20000850	00000000	00000000	2000016C	00000000	1	
20000860	4000000	(08001A55)	08005BE4	FFFFFFF9	eUE	
20000870	40022000	CDEF89AB	00000000	01000210	e	
20000880	00000080	0800251F	0800251E	81000000		
20000890	00000000	00000000	000000000	00000000		
200008A0	00000000	00000000	00000000	00000000		
200008B0	00000000	00000000	00000000	00000000		
200008C0	00000000	00000000	00000000	00000000		
200008D0	00000000	00000000	00000000	00000000		
200008E0	00000000	00000000	00000000	00000000		_
00000080	00000000	00000000	00000000	00000000		

从栈的底部往上看,确定哪个地方的值是函数指针,然后对照 lst 文件去逐一查看,分析,就 能大致知道是在执行哪个函数,哪一条指令,或者是调用某个参数导致的硬件中断错误的。

通过 map 文件可以知道每个变量的位置,可以直接去查看我们保存下来的 ram 中变量的当前 情况来分析程序逻辑。

3.3 Jlink Command 使用方法:

f Firmware info 用来查看 Jlink 的硬件版本



图 3-6. f 命令

```
J-Link>f
Firmware: J-Link V9 compiled Sep 18 2015 19:53:12
Hardware: V9.20
```

halt 用来停止 MCU 内核,可以查看内核的 PC 指针等特殊寄存器

图 3-7.h 命令

h

```
J-Link>h

PC = 08000D7C, CycleCnt = F39B01CC

R0 = 00000001, R1 = 00000001, R2 = 0000001F, R3 = 000000083

R4 = 40000000, R5 = 08005BE4, R6 = 00000000, R7 = 00000000

R8 = 00000000, R9 = 2000016C, R10= 00000000, R11= 00000000

R12= 0000080

SP<R13>= 20000868, MSP= 20000868, PSP= 20000800, R14(LR) = 08001A4D

SP<R13>= 2100001F: APSR = nzCvq, EPSR = 01000000, IPSR = 01F (INTISR15)

CFBP = 00000000, CONTROL = 00, FAULTMASK = 00, BASEPRI = 00, PRIMASK = 00
```

g go 用来激活被 halt 的内核

Sleep Waits the given time (in milliseconds). Syntax: Sleep <delay>用来延时

s Single step the target chip 单步调试代码,可以先执行 halt, 然后再来单步调试

图 3-8. s 命令

```
J-Link>halt

PC = 08000D7C, CycleCnt = A970C614

R0 = 00000001, R1 = 00000001, R2 = 00000000, R7 = 00000000

R4 = 40000000, R5 = 08005BE4, R6 = 00000000, R7 = 00000000

R8 = 00000000, R9 = 2000016C, R10= 00000000, R11= 00000000

R12= 00000080

SP<R13>= 20000868, MSP= 20000868, PSP= 20000800, R14(LR) = 08001A4D

SPSR = 2100001F: APSR = nzCvq, EPSR = 01000000, IPSR = 01F (INTISR15)

CFBP = 00000000, CONTROL = 00, FAULTMASK = 00, BASEPRI = 00, PRIMASK = 00

J-Link>s

08000D7C: FE E7 B #-0x04
```

st Show hardware status 显示 Jlink 当前状态

图 3-9. st 命令

```
J-Link>st
VTarget=3.285V
ITarget=0mA
TCK=0 TDI=0 TDO=0 TMS=1 TRES=1 TRST=0
Supported target interface speeds:
- 12 MHz/n, <n>=1>. => 12000kHz, 6000kHz, 4000kHz, ...
- Adaptive clocking
J-Link>_
```

hwinfo Show hardware info 显示 Jlink 的硬件信息

mem Read memory. Syntax: mem [<Zone>:]<Addr>, <NumBytes> (hex)



Cortex-M3 内核 HardFault 错误调试定位方法

mem8 Read 8-bit items. Syntax: mem8 [<Zone>:]<Addr>, <NumBytes> (hex)
 mem16 Read 16-bit items. Syntax: mem16 [<Zone>:]<Addr>, <NumItems> (hex)
 mem32 Read 32-bit items. Syntax: mem32 [<Zone>:]<Addr>, <NumItems> (hex)
 读取指令:

图 3-10. 读取指令

```
J-Link>mem 0x8000000 20

08000000 = 90 08 00 20 71 01 00 08 5F 0E 00 08 7D 0D 00 08

08000010 = 5D 0E 00 08 15 02 00 08 FB 1D 00 08 00 00 00 00

J-Link>mem8 0x8000000 2

08000000 = 90 08

J-Link>mem16 0x8000000 2

08000000 = 0890 2000

J-Link>mem32 0x8000000 2

08000000 = 20000890 08000171

J-Link>
```

```
w1 Write 8-bit items. Syntax: w1 [<Zone>:]<Addr>, <Data> (hex)
```

w2 Write 16-bit items. Syntax: w2 [<Zone>:]<Addr>, <Data> (hex)

w4 Write 32-bit items. Syntax: w4 [<Zone>:]<Addr>, <Data> (hex)

■ 写指令:

图 3-11. 写指令

```
J-Link>w2 0x2000000 55
Writing 0055 -> 2000000
J-Link>mem16 0x20000000 2
20000000 = 0055 0017
J-Link>w4 0x20000000 5566
Writing 00005566 -> 20000000
J-Link>mem32 0x20000000 2
20000000 = 00005566 00040000
J-Link>
```

erase Erase internal flash of selected device. Syntax: Erase

擦除指令,先选定器件然后再来执行擦除



图 3-12. 擦除指令

loadfile Load data file into target memory.

Syntax: loadfile <filename>, [<addr>]

Supported extensions: *.bin, *.mot, *.hex, *.srec

<addr> is needed for bin files only. //用来下载文件

loadbin Load *.bin file into target memory.

Syntax: loadbin <filename>, <addr>//用来下载 bin 文件

savebin Saves target memory into binary file.//用来保存 bin 文件

Syntax: savebin <filename>, <addr>, <NumBytes>

Set PC Set the PC to specified value. Syntax: SetPC <Addr>//用来设置 PC 指针,可以 让程序从某个地方开始执行



4. 版本历史

表 4-1. 版本历史

版本号.	描述	日期
1.0	首次发布	2021年04月30日



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