

**GigaDevice Semiconductor Inc.**

**Arm<sup>®</sup> Cortex<sup>®</sup>-M4 32-bit MCU**

**Application Note**

**AN029**

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## 1. Introduction

GD32F3xx and GD32F403 with Cortex-M4 kernel are launched by GD in recent years. These two series products can run 103 program directly. But the 103 program doesn't have the DSP instruction set. Is there a way to let the users to use the DSP instruction set and FPU when the program is based on 103? The answer is yes. The detailed method is show as below.

## 2. Operation steps

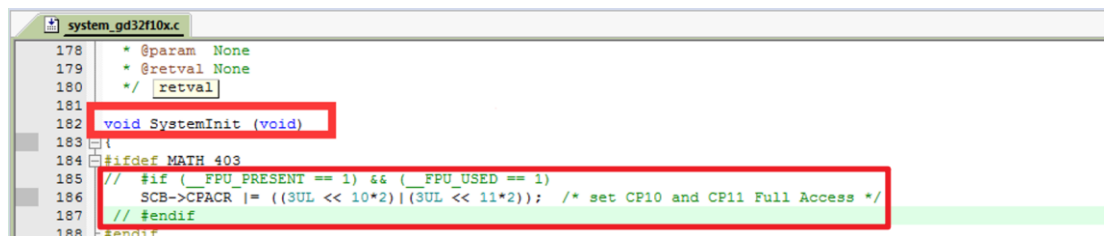
The following steps use Keil4 as an example, and the configuration method of Keil5 is exactly the same.

### 2.1 Turn on FPU

The 303 and 403 series have the FPU function. Some particular configuration need to be set as below.

1. Enable FPU before executing code

**Figure 2-1. Enable FPU**

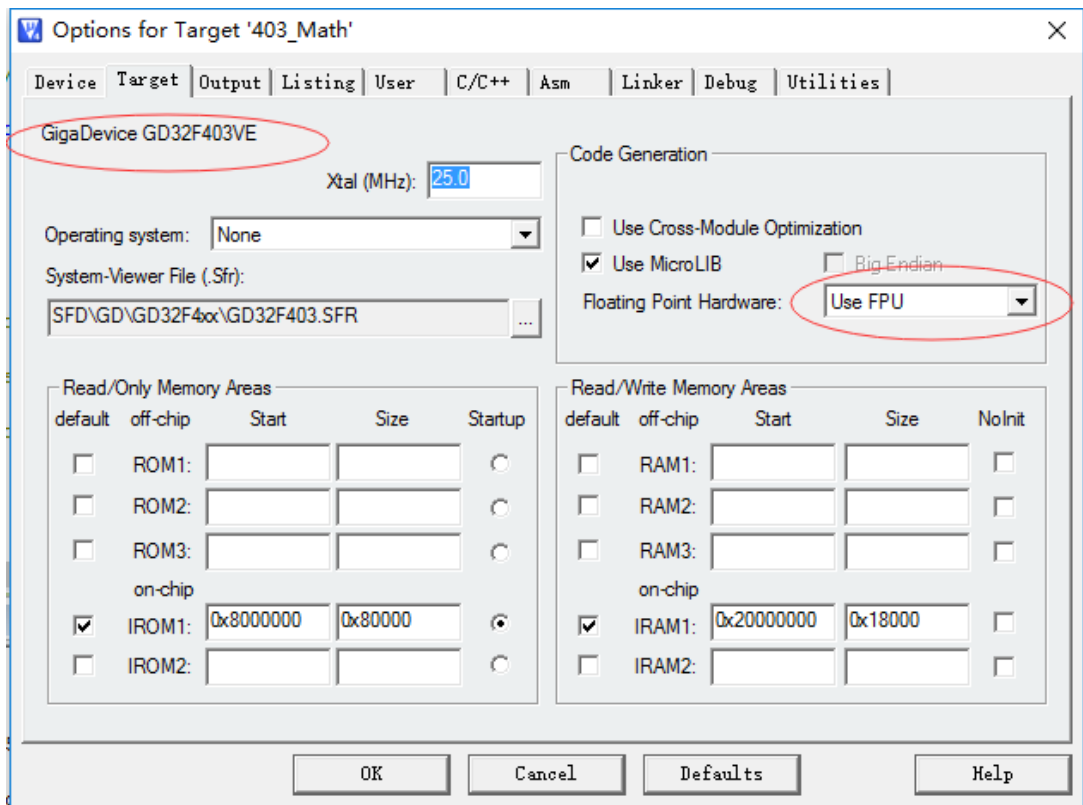


```

178  * @param None
179  * @retval None
180  */
181  [retval]
182  void SystemInit (void)
183  {
184  #ifdef MATH_403
185  // #if (__FPU_PRESENT == 1) && (__FPU_USED == 1)
186  SCB->CPACR |= ((3UL << 10*2) | (3UL << 11*2)); /* set CP10 and CP11 Full Access */
187  // #endif
188  #endif
  
```

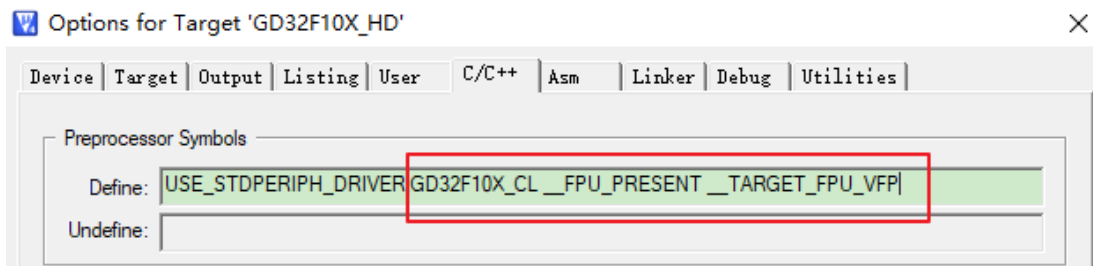
2. Select 303 or 403 model and use FPU

**Figure 2-2. Select 303 or 403 and enable FPU**



3. Fill in the corresponding compilation macro definition.

**Figure 2-3. Add the corresponding compilation macro**



**Note:** GD32F10X\_CL must be configured for F403, and F303 and F103 must be the same.

## 2.2 Check whether the FPU is turned on successfully

In the JLINK debugging control interface, enter the command:

```
mem32 0xE000ED88 1
```

See the following figure for detailed operation. After entering the command, 00f00000 indicates that the FPU has been turned on. If it is 00000000, it indicates that the FPU has not been turned on.

**Figure 2-4. Check whether the FPU is turned on**

```

T) cJTAG
TIF>swd
Specify target interface speed [kHz]. <Default>: 4000 kHz
Speed>
Device "GD32F303RE" selected.

Connecting to target via SWD
Found SW-DP with ID 0x2BA01477
Scanning AP map to find all available APs
AP[1]: Stopped AP scan as end of AP map has been reached
AP[0]: AHB-AP (IDR: 0x24770011)
Iterating through AP map to find AHB-AP to use
AP[0]: Core found
AP[0]: AHB-AP ROM base: 0xE00FF000
CPUID register: 0x410FC241. Implementer code: 0x41 (ARM)
Found Cortex-M4 r0p1, Little endian.
FPUUnit: 6 code (BP) slots and 2 literal slots
CoreSight components:
ROMTbl[0] @ E00FF000
ROMTbl[0][0]: E000E000, CID: B105E00D, PID: 000BB00C SCS-M7
ROMTbl[0][1]: E0001000, CID: B105E00D, PID: 003BB002 DWT
ROMTbl[0][2]: E0002000, CID: B105E00D, PID: 002BB003 FPB
ROMTbl[0][3]: E0000000, CID: B105E00D, PID: 003BB001 ITM
ROMTbl[0][4]: E0040000, CID: B105900D, PID: 000BB9A1 TPIU
ROMTbl[0][5]: E0041000, CID: 00000000, PID: 00000000 ???
Cortex-M4 identified.
J-Link>mem32 0xE000ED88 1
E000ED88 = 00F00000
J-Link>

```

## 2.3 Performance test comparison

Compile the code, then the performance of M4 can be tested on 103 code.

```

int main(void)
{
    float i;
    float m = 2.5f;
    float n = 4;

    /* configure systick */
    systick_config();
    /* initialize the LEDs, USART and key */
    gd_eval_led_init(LED2);
    gd_eval_led_init(LED3);
    gd_eval_led_init(LED4);
    gd_eval_com_init(EVAL_COM0);
    gd_eval_key_init(KEY_WAKEUP, KEY_MODE_GPIO);

    while(1){
        if(RESET == gd_eval_key_state_get(KEY_WAKEUP)){
            gd_eval_led_on(LED3);
            i = m * n;
            gd_eval_led_off(LED3);
        }
    }
}

```

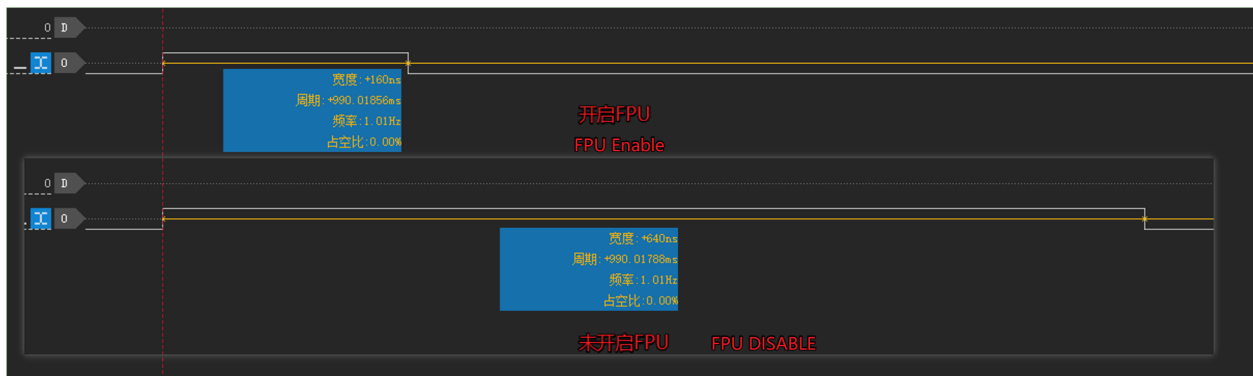
```

printf("\r\ni = %f", i);
while(RESET == gd_eval_key_state_get(KEY_WAKEUP));
    }
}
}

```

Grab the pin waveform of LED3 with the logic analyzer and check the calculation time of floating-point operation. The following is the test comparison between opening FPU and not opening FPU:

**Figure 2-5. Comparison of performance test**



If FPU is not enabled, a floating-point multiplication takes 640ns, and only 160ns after FPU is enabled.

## 2.4 Turn on DSP

1. Copy math.lib from the MDK path and add to the project. The specific document is arm\_cortexM4l\_math.lib. (If the FPU is used, arm\_cortexM4lf\_math.lib will be selected.)

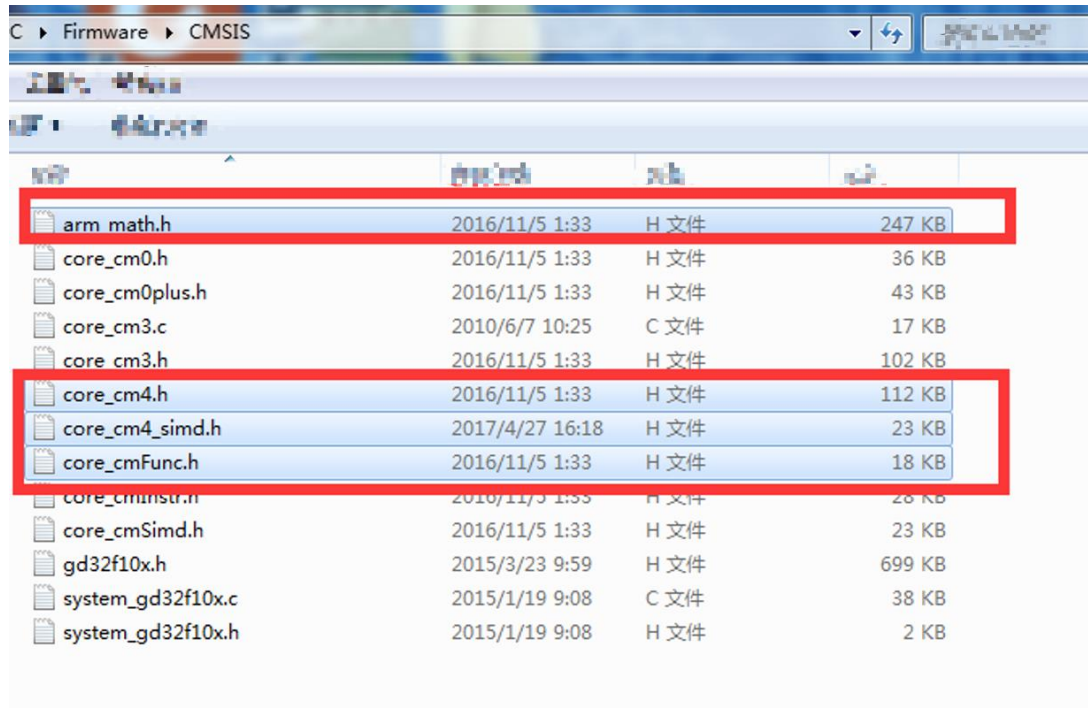
**Figure 2-6. math.lib file**

名称	修改日期	类型	大小
arm_cortexM0l_math.lib	2012/10/24 11:07	Altium Library	10,364 KB
arm_cortexM3l_math.lib	2012/10/24 11:07	Altium Library	10,656 KB
arm_cortexM4l_math.lib	2012/10/24 11:07	Altium Library	10,822 KB
arm_cortexM4lf_math.lib	2012/10/24 11:07	Altium Library	10,905 KB

2. Copy the corresponding .H file to the project. The core\_cm4.h file is needed if DSP is used.

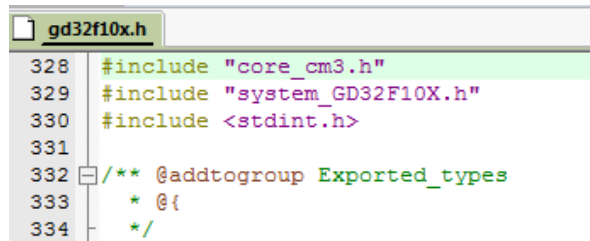


**Figure 2-7. The required .H file**



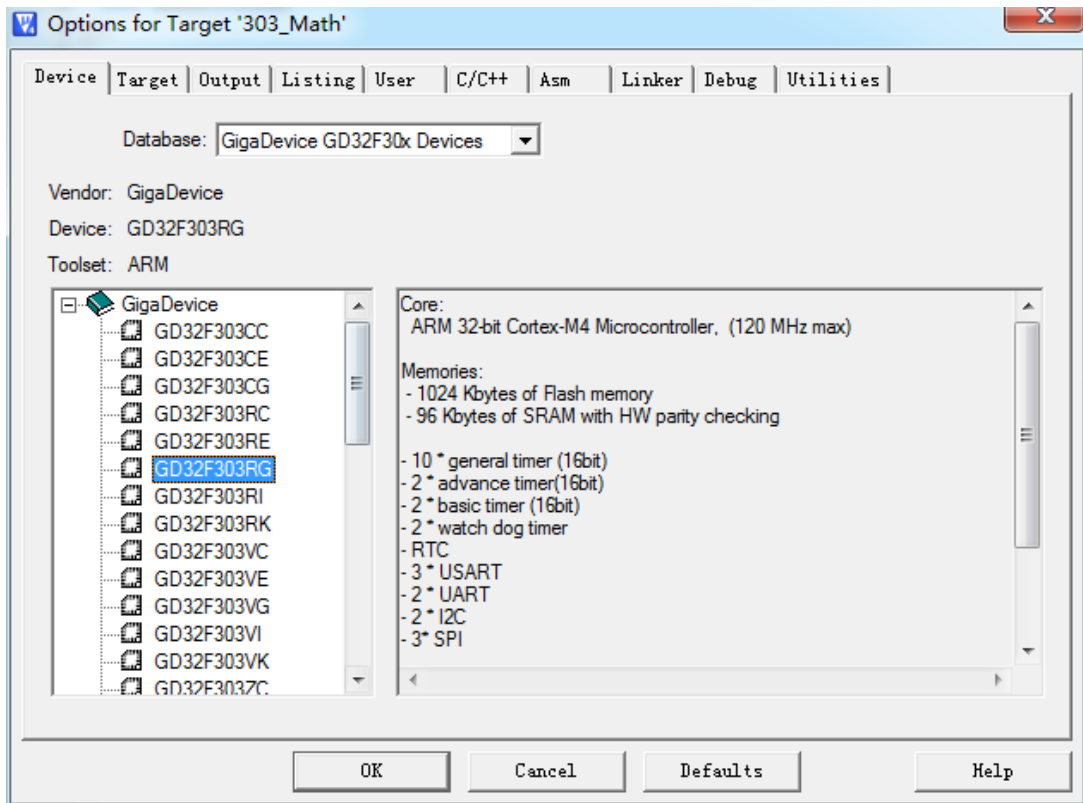
3. Change the core\_cm3.h to core\_cm4.h in gd32f10x.h file.

**Figure 2-8. Core\_cm3.h changed to core\_cm4.h**

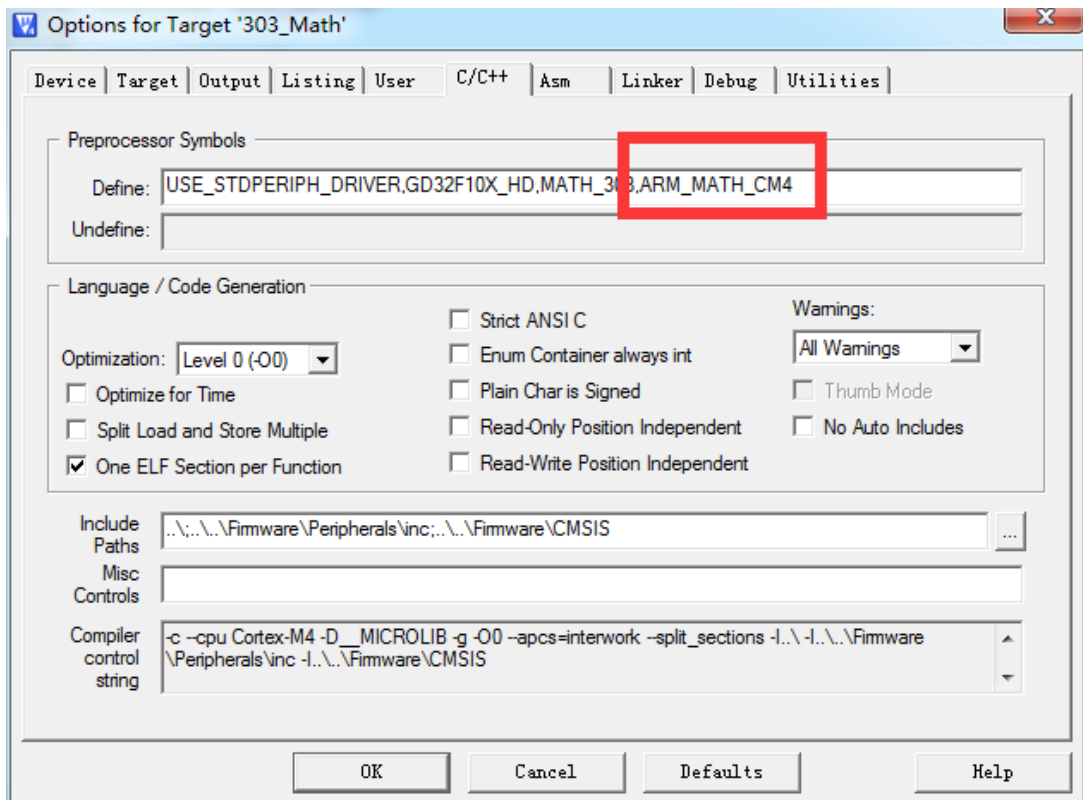


4. Modify the selection of the MCU model. 303 select the corresponding 303 model, 403 select the corresponding 403 model and the corresponding Math compilation macro.

**Figure 2-9. Modify the chip model**



**Figure 2-10. Add the corresponding Math compilation macro**





### 3. Revision history

Table 3-1. Revision history

Revision No.	Description	Date
1.0	Initial Release	Apr.30, 2021

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