

GigaDevice Semiconductor Inc.

GD32A10x
ARM® Cortex™ -M4 32-bit MCU

Firmware Library
User Guide

Revision 1.0

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1. Introduction

This manual introduces firmware library of GD32A10x devices which are 32-bit microcontrollers based on the ARM processor.

The firmware library is a firmware function package, including program, data structure and macro definitions, all the performance features of peripherals of GD32A10x devices are involved in the package. The peripheral driving code and firmware examples on evaluation board are also included in firmware library. Users need not learn each peripherals in details and it's easy to apply a peripheral by using the firmware library. Using firmware library can greatly reduce programming time, thereby reducing development costs.

The driving code of each peripheral is concluded by a group of functions, which describes all the performance features of the peripheral. Users can drive a peripheral by a group of APIs (application programming interface), all the APIs are standardized about the code structure, function name and parameter names.

All the driving source code accord with MISRA-C:2004 standard (example files accord with extended ANSI-C standard), and will not be influenced by differences of IDEs, except the startup files which are written differently according to the IDEs.

The commonly used firmware library includes all the functions of all the peripherals, so the code size and the execution speed may not be the optimal. For most applications, users can use the library functions directly, while for the applications which are strict with the code size and execution speed, the firmware library can be used as the reference resource of how to configure a peripheral, and users adjust the code according to actual needs.

The overall structure of the firmware library user manual is shown as below:

- Rules of user manual and firmware library;
- Firmware library overview;
- Functions and registers descriptions of firmware library.

1.1. Rules of User Manual and Firmware Library

1.1.1. Peripherals

Table 1-1. Peripherals

Peripherals	Descriptions
ADC	Analog-to-digital converter
BKP	Backup registers
CAN	Controller area network
CRC	CRC calculation unit
CTC	Clock trim controller
DAC	Digital-to-analog converter

Peripherals	Descriptions
DBG	Debug
DMA	Direct memory access controller
EXMC	External memory controller
EXTI	Interrupt/event controller
FMC	Flash memory controller
FWDGT	Free watchdog timer
GPIO/AFIO	General-purpose and alternate-function I/Os
I2C	Inter-integrated circuit interface
MISC	Nested Vectored Interrupt Controller
PMU	Power management unit
RCU	Reset and clock unit
RTC	Real-time Clock
SPI/I2S	Serial peripheral interface/Inter-IC sound
TIMER	TIMER
USART	Universal synchronous/asynchronous receiver /transmitter
WWDGT	Window watchdog timer
USBFS	Universal serial bus full-speed interface

1.1.2. Naming rules

The firmware library naming rules are shown as below:

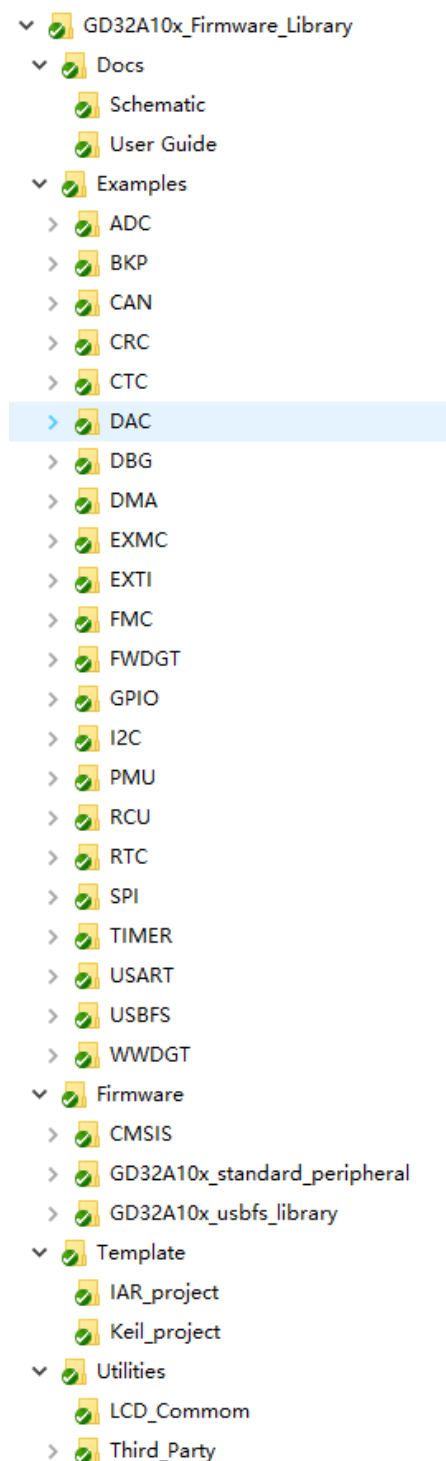
- The peripherals are shortened in XXX format, such as: ADC. More shorten information of peripherals refer to [Peripherals](#);
- The name of sourcefile and header file are started with “gd32a10x_”, such as: gd32a10x_adc.h;
- The constants used only in one file should be defined in the used file; the constants used in many files should be defined in corresponding header file. All the constants are written in uppercase of English letters;
- Registers are handled as constants. The naming of them are written in uppercase of English letters. In most cases, register names are shortened accord with the user manual;
- Variables are written in lowercase, when concluded by several words, underlines should be adapted among words;
- The naming of peripheral functions are started with the peripheral abbreviation added with an underline, when the function name is concluded by several words, underlines should be adapted among words, and all the peripheral functions are written in lowercase.

2. Firmware Library Overview

2.1. File Structure of Firmware Library

GD32A10x_Firmware_Library, the file structure is shown as below:

Figure 2-1. File structure of firmware library of GD32A10x



2.1.1. Examples Folder

Examples folder, each of GD32 peripheral has a subfolder. Each subfolder contains one or more examples of the peripheral, to show how to use the peripheral correctly. Each of the example subfolder includes the files shown as below:

- `readme.txt`: the description and using guide of the example;
- `gd32a10x_libopt.h`: the header file configures all the peripherals used in the example, included by different "DEFINE" sentences (all the peripherals are enabled by default);
- `gd32a10x_it.c`: the source file include all the interrupt service routines (if no interrupt is used, then all the function bodies are empty);
- `gd32a10x_it.h`: the header file include all the prototypes of the interrupt service routines;
- `systick.c`: the source file include the precise time delay functions by using `systick`;
- `systick.h`: the header file include the prototype of the precise time delay functions by using `systick`;
- `main.c`: example code. Note: all the examples are not influenced by software IDEs.

2.1.2. Firmware Folder

Firmware folder includes all the subfolder and files which are the core part of the firmware:

- CMSIS subfolder includes the Cortex M4 kernel support files, the startup file based on the Cortex M4 kernel processor, the global header file of GD32A10x and system configuration file;
- GD32A10x_standard_peripheral subfolder:
 - Include subfolder includes all the header files of firmware library, users need not modify this folder;
 - Source subfolder includes all the source files of firmware library, users need not modify this folder;
- GD32A10x_usbfs_library subfolder includes all the related files about USBFS peripheral: users need not modify this folder;

Note: All the codes accord with MISRA-C:2004 standard, and will not be influenced by different software IDEs.

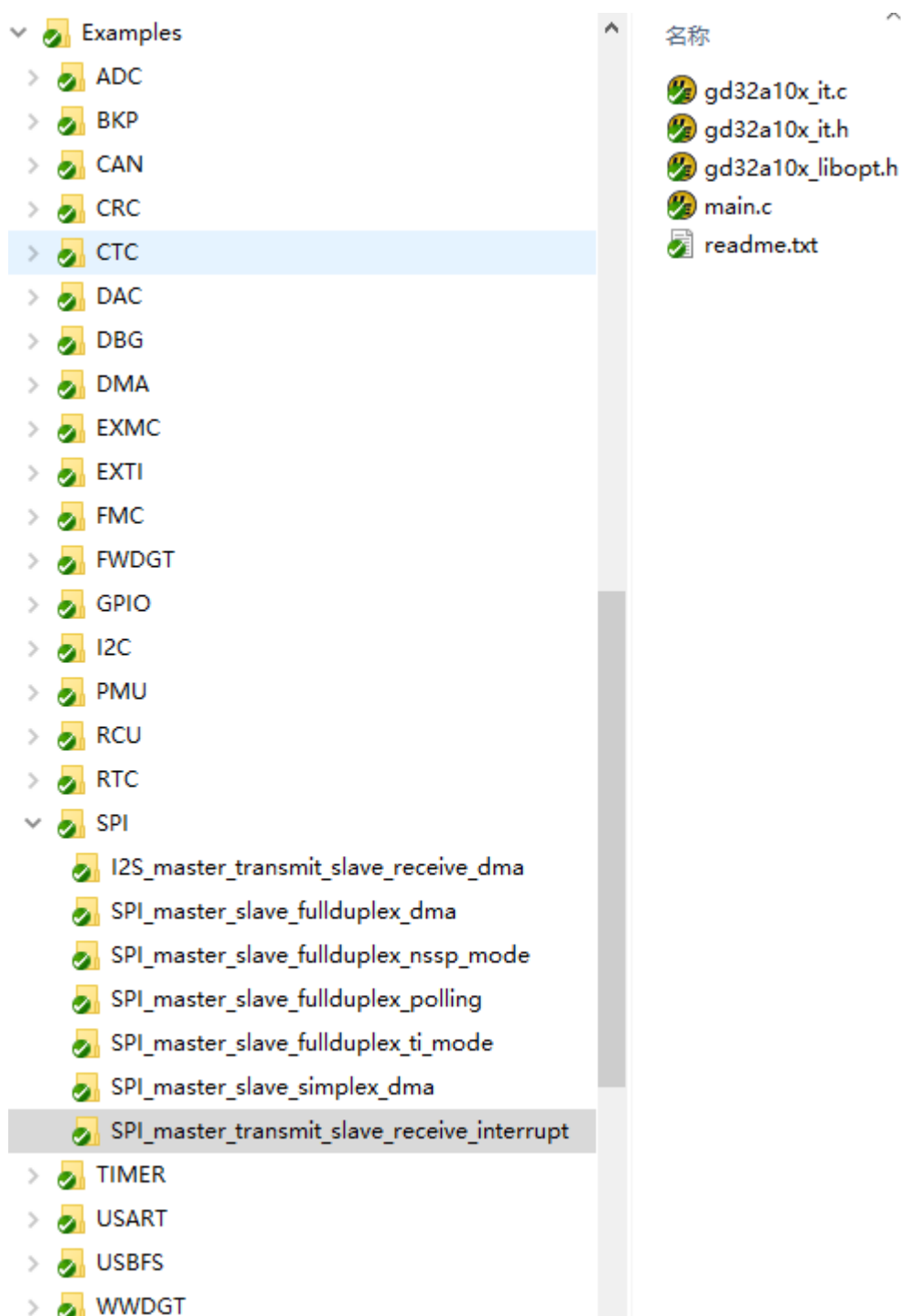
2.1.3. Template Folder

Template folder includes a simple demo of how to use LED, how to print by USART and use key to control, (IAR_project is run in IAR, and Keil_project is run in Keil4). User can use the project template to compile the formware examples, the steps are shown as below:

Select files

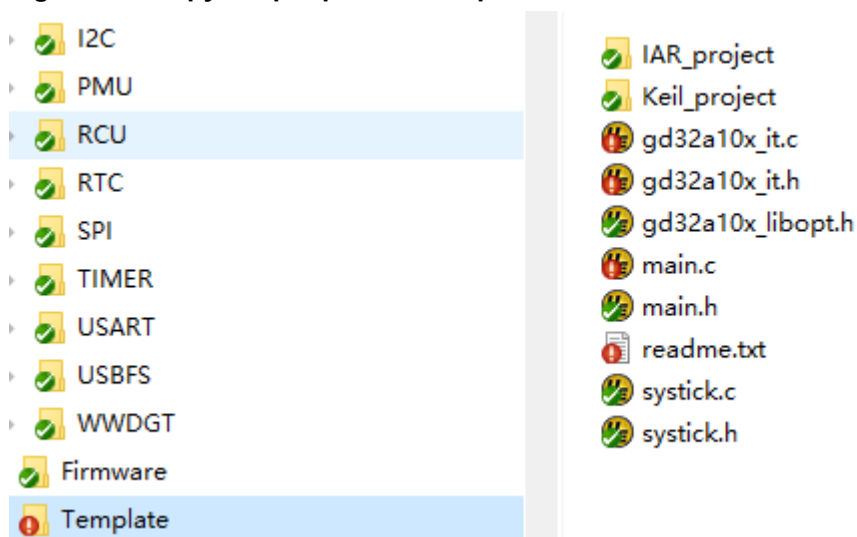
Open "Examples" folder, select the module to be tested, such as SPI, open "SPI" folder, select an example of SPI, such as "SPI_master_transmit_slave_receive_interrupt", shown as below:

Figure 2-2. Select peripheral example files



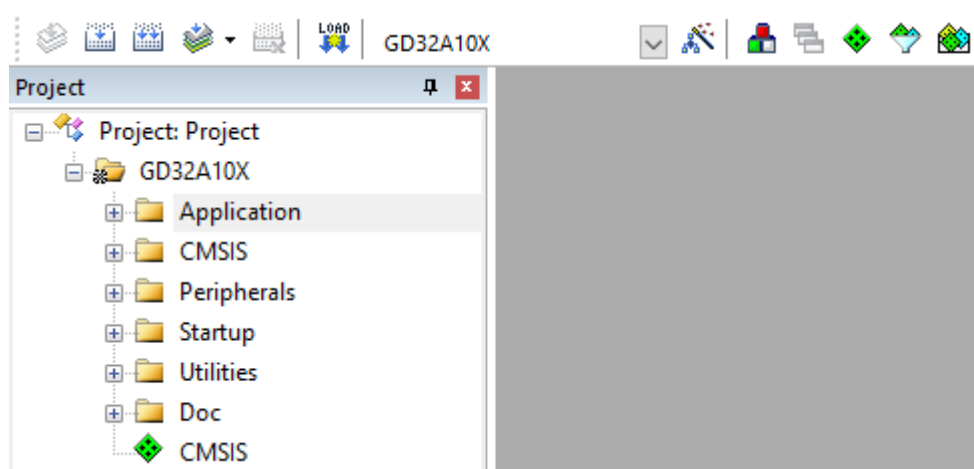
Copy files

Open "Template" folder, keep the folders of " IAR_project" and " Keil_project", and delete the other files, then copy all the files in "SPI_master_transmit_slave_receive_interrupt" folder to the "Template" subfolder, shown as below:

Figure 2-3. Copy the peripheral example files

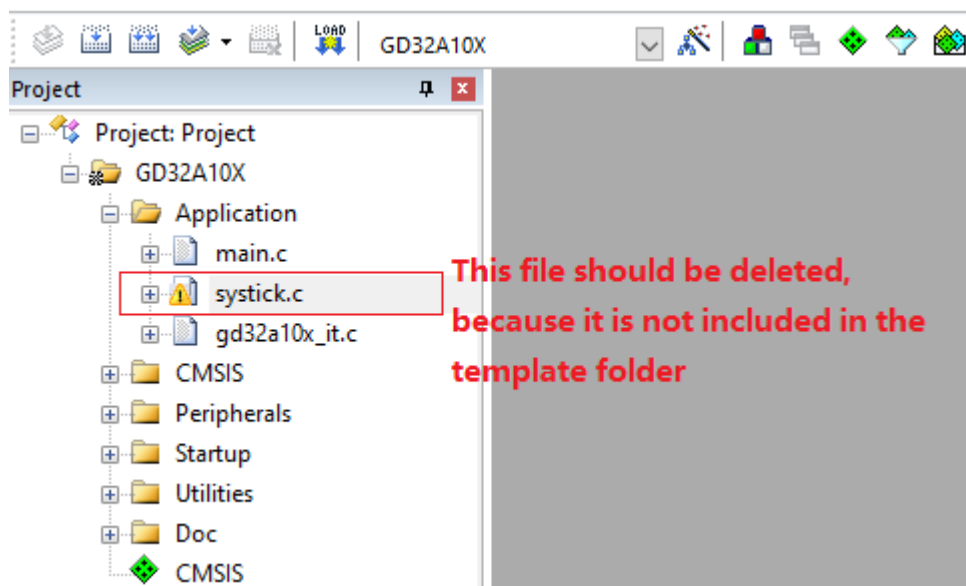
Open a project

GD provides project in Keil and IAR, users can open project in different IDEs according to their need, such as "Keil_project", open \Template\Keil_project\Project.uvproj, shown as below:

Figure 2-4. Open the project file

Because different module and different functions adopt different files, users should add or delete the files in project according to the copied files, shown as below:

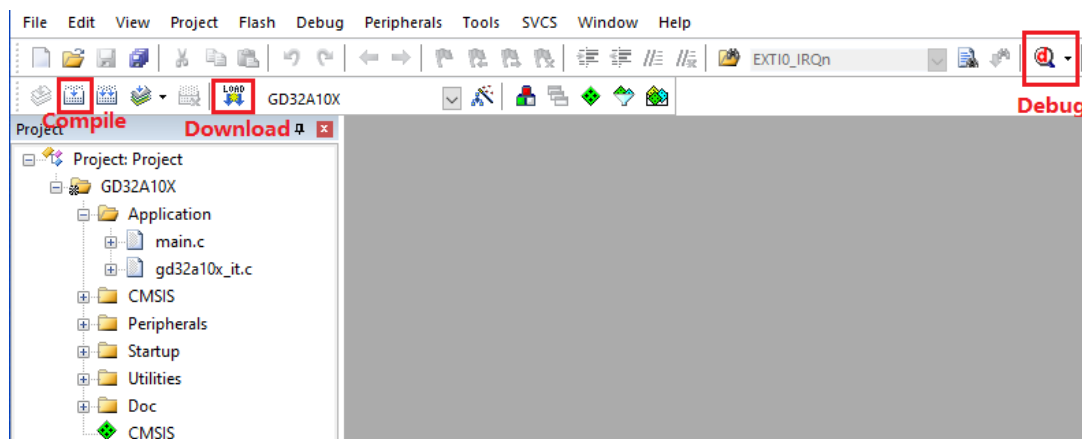
Figure 2-5. Configure project files



Compile-Debug-Download

First compile the project, if there is no error, then select the right jumper cap according to the description of readme, download the project to the target board, and there will be the phenomenon showed accord with the description of readme. The usage of IDE can refer to corresponding software user guide. If users are using Keil, the figure is shown as below:

Figure 2-6. Compile-debug-download



2.1.4. Utilities Folder

Utilities folder includes files about the firmware examples on evaluation board:

- LCD_Commom and Third_Party subfolders include files for USB tests;
- gd32a10x_eval.h and gd32a10x_lcd_eval.h are related header files of the evaluation board about running the firmware examples;
- gd32a10x_eval.c and gd32a10x_lcd_eval.c are related source files of the evaluation

board about running the firmware examples.

Note: All the codes accord with MISRA-C:2004 standard, and will not be influenced by different software IDEs.

2.2. File descriptions of Firmware Library

The major files about the firmware library are listed and described in the table below.

Table 2-1. Function descriptions of Firmware Library

Files	Descriptions
gd32a10x_libopt.h	The header file about all the header files of peripherals. It is the only one file which is necessity to be included in the user's application, to connect the firmware library and the application.
main.c	Example of main function.
gd32a10x_it.h	Header file, including all the prototypes of interrupt service routines.
gd32a10x_it.c	Source files about interrupt service routines of peripherals. User can written his own interrupt functions in this file. For the different interrupt service requests to the same interrupt vector, users can confirm the interrupt source by functions of judging interrupt flags of peripherals. The functions are included in the firmware library.
gd32a10x_xxx.h	The header file of peripheral PPP, including functions about peripheral PPP, and the variables used for functions.
gd32a10x_xxx.c	The C source file for driving peripheral PPP.
systick.h	The header file of systick.c, including prototypes of systick configuration function and delay function.
systick.c	The source file about systick configuration function and delay function.
readme.txt	Description document about how to configure and how to use the firmware example.

3. Firmware Library of Standard Peripherals

3.1. Overview of Firmware Library of Standard Peripherals

The description format of firmware functions are shown as below:

Table 3-1. Peripheral function format of Firmware Library

Function name	Name of peripheral function
Function prototype	Declaration prototype
Function descriptions	Explain the function how to work
Precondition	Requirements should meet before calling this function
The called functions	Other firmware functions called in this functin
Input parameter{in}	
Input parameter name	Description
xxxx	Description of input parameters
Output parameter{out}	
Output parameter name	Description
xxxx	Description of output parameters
Return value	
Return value type	The range of return value

3.2. ADC

The 12-bit ADC is an analog-to-digital converter using the successive approximation method. The ADC registers are listed in chapter [3.2.1](#), the ADC firmware functions are introduced in chapter [3.2.2](#).

3.2.1. Descriptions of Peripheral registers

ADC registers are listed in the table shown as below:

Table 3-2. ADC Registers

Registers	Descriptions
ADC_STAT	Status register
ADC_CTL0	Control register 0
ADC_CTL1	Control register 1
ADC_SAMPT0	Sample time register 0
ADC_SAMPT1	Sample time register 1
ADC_IOFFx (x=0..3)	Inserted channel data offset register x(x=0..3)
ADC_WDHT	Watchdog high threshold register
ADC_WDLT	Watchdog low threshold register

Registers	Descriptions
ADC_RSQ0	Regular sequence register 0
ADC_RSQ1	Regular sequence register 1
ADC_RSQ2	Regular sequence register 2
ADC_ISQ	Inserted sequence register
ADC_IDATAx	Inserted data register x(x=0..3)
ADC_RDATA	Regular data register
ADC_OVSAMPCTL	Oversample control register

3.2.2. Descriptions of Peripheral functions

ADC firmware functions are listed in the table shown as below:

Table 3-3. ADC firmware function

Function name	Function description
adc_deinit	reset ADCx peripheral
adc_mode_config	configure the ADC sync mode
adc_special_function_config	enable or disable ADC special function
adc_data_alignment_config	configure ADC data alignment
adc_enable	enable ADC interface
adc_disable	disable ADC interface
adc_calibration_enable	ADC calibration and reset calibration
adc_tempsensor_vrefint_enable	enable the temperature sensor and Vrefint channel
adc_tempsensor_vrefint_disable	disable the temperature sensor and Vrefint channel
adc_resolution_config	configure ADC resolution
adc_oversample_mode_config	configure ADC oversample mode
adc_oversample_mode_enable	enable ADC oversample mode
adc_oversample_mode_disable	disable ADC oversample mode
adc_dma_mode_enable	enable DMA request
adc_dma_mode_disable	disable DMA request
adc_discontinuous_mode_config	configure ADC discontinuous mode
adc_channel_length_config	configure the length of regular channel group or inserted channel group
adc_regular_channel_config	configure ADC regular channel
adc_inserted_channel_config	configure ADC inserted channel
adc_inserted_channel_offset_config	configure ADC inserted channel offset
adc_external_trigger_source_config	configure ADC external trigger source
adc_external_trigger_config	enable ADC external trigger
adc_software_trigger_enable	enable ADC software trigger
adc_regular_data_read	read ADC regular group data register
adc_inserted_data_read	read ADC inserted group data register
adc_sync_mode_convert_value_read	read the last ADC0 and ADC1 conversion result data in sync mode

Function name	Function description
adc_watchdog_single_channel_enable	configure ADC analog watchdog single channel
adc_watchdog_group_channel_enable	configure ADC analog watchdog group channel
adc_watchdog_disable	disable ADC analog watchdog
adc_watchdog_threshold_config	configure ADC analog watchdog threshold
adc_flag_get	get the ADC flag bits
adc_flag_clear	clear the ADC flag bits
adc_regular_software_startconv_flag_get	get the bit state of ADCx software start conversion
adc_inserted_software_startconv_flag_get	get the bit state of ADCx software inserted channel start conversion
adc_interrupt_flag_get	get the ADC interrupt bits
adc_interrupt_flag_clear	clear the ADC flag
adc_interrupt_enable	enable ADC interrupt
adc_interrupt_disable	disable ADC interrupt

adc_deinit

The description of adc_deinit is shown as below:

Table 3-4. Function adc_deinit

Function name	adc_deinit
Function prototype	void adc_deinit(uint32_t adc_periph);
Function descriptions	reset ADCx peripheral
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Input parameter{in}	
adc_periph	ADC peripheral
ADCx(x=0,1)	ADC peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset ADC0 */
adc_deinit(ADC0);
```

adc_mode_config

The description of adc_mode_config is shown as below:

Table 3-5. Function `adc_mode_config`

Function name	<code>adc_mode_config</code>
Function prototype	<code>void adc_mode_config(uint32_t mode);</code>
Function descriptions	configure the ADCs sync mode
Precondition	-
The called functions	-
Input parameter{in}	
mode	ADC mode
<code>ADC_MODE_FREE</code>	all the ADC work independently
<code>ADC_DAUL_REGULAL _PARALLEL_INSERTE D_PARALLEL</code>	ADC0 and ADC1 work in combined regular parallel + inserted parallel mode
<code>ADC_DAUL_REGULAL _PARALLEL_INSERTE D_ROTATION</code>	ADC0 and ADC1 work in combined regular parallel + trigger rotation mode
<code>ADC_DAUL_INSERTE D_PARALLEL_REGUL AL_FOLLOWUP_FAST</code>	ADC0 and ADC1 work in combined inserted parallel + follow-up fast mode
<code>ADC_DAUL_INSERTE D_PARALLEL_REGUL AL_FOLLOWUP_SLO W</code>	ADC0 and ADC1 work in combined inserted parallel + follow-up slow mode
<code>ADC_DAUL_INSERTE D_PARALLEL</code>	ADC0 and ADC1 work in inserted parallel mode only
<code>ADC_DAUL_REGULAL _PARALLEL</code>	ADC0 and ADC1 work in regular parallel mode only
<code>ADC_DAUL_REGULAL _FOLLOWUP_FAST</code>	ADC0 and ADC1 work in follow-up fast mode only
<code>ADC_DAUL_REGULAL _FOLLOWUP_SLOW</code>	ADC0 and ADC1 work in follow-up slow mode only
<code>ADC_DAUL_INSERTE D_TRRIGGER_ROTAT ION</code>	ADC0 and ADC1 work in trigger rotation mode only
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the ADC sync mode */
adc_mode_config(ADC_MODE_FREE);
```


adc_special_function_config

The description of adc_special_function_config is shown as below:

Table 3-6. Function adc_special_function_config

Function name	adc_special_function_config
Function prototype	void adc_special_function_config(uint32_t adc_periph, uint32_t function, ControlStatus newvalue);
Function descriptions	enable or disable ADC special function
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
ADCx(x=0,1)	ADC peripheral selection
Input parameter{in}	
function	the function to config
ADC_SCAN_MODE	scan mode select
ADC_INSERTED_CHANNEL_AUTO	inserted channel group convert automatically
ADC_CONTINUOUS_MODE	continuous mode select
Input parameter{in}	
newvalue	control value
ENABLE	enable function
DISABLE	disable function
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable ADC0 scan mode */
```

```
adc_special_function_config(ADC0, ADC_SCAN_MODE, ENABLE);
```

adc_data_alignment_config

The description of adc_data_alignment_config is shown as below:

Table 3-7. Function adc_data_alignment_config

Function name	adc_data_alignment_config
Function prototype	void adc_data_alignment_config(uint32_t adc_periph, uint32_t data_alignment);
Function descriptions	configure ADCx data alignment
Precondition	-

The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
data_alignment	data alignment select
<i>ADC_DATAALIGN_RIGHT</i>	LSB alignment
<i>ADC_DATAALIGN_LEFT</i>	MSB alignment
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC0 data alignment */
```

```
adc_data_alignment_config(ADC0, ADC_DATAALIGN_RIGHT);
```

adc_enable

The description of adc_enable is shown as below:

Table 3-8. Function adc_enable

Function name	adc_enable
Function prototype	void adc_enable(uint32_t adc_periph);
Function descriptions	enable ADCx interface
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable ADC0 */
```

```
adc_enable(ADC0);
```

adc_disable

The description of adc_disable is shown as below:

Table 3-9. Function adc_disable

Function name	adc_disable
Function prototype	void adc_disable(uint32_t adc_periph);
Function descriptions	disable ADCx interface
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable ADC0 */
adc_disable(ADC0);
```

adc_calibration_enable

The description of adc_calibration_enable is shown as below:

Table 3-10. Function adc_calibration_enable

Function name	adc_calibration_enable
Function prototype	void adc_calibration_enable(uint32_t adc_periph);
Function descriptions	ADCx calibration and reset calibration
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* ADC0 calibration and reset calibration */
adc_calibration_enable(ADC0);
```

adc_tempsensor_vrefint_enable

The description of adc_tempsensor_vrefint_enable is shown as below:

Table 3-11. Function adc_tempsensor_vrefint_enable

Function name	adc_tempsensor_vrefint_enable
Function prototype	void adc_tempsensor_vrefint_enable(void);
Function descriptions	enable the temperature sensor and Vrefint channel
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the temperature sensor and Vrefint channel */
adc_tempsensor_vrefint_enable();
```

adc_tempsensor_vrefint_disable

The description of adc_tempsensor_vrefint_disable is shown as below:

Table 3-12. Function adc_tempsensor_vrefint_disable

Function name	adc_tempsensor_vrefint_disable
Function prototype	void adc_tempsensor_vrefint_disable(void);
Function descriptions	disable the temperature sensor and Vrefint channel
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the temperature sensor and Vrefint channel */
adc_tempsensor_vrefint_disable();
```

adc_resolution_config

The description of adc_resolution_config is shown as below:

Table 3-13. Function adc_resolution_config

Function name	adc_resolution_config
Function prototype	void adc_resolution_config(uint32_t adc_periph , uint32_t resolution);
Function descriptions	configure ADC resolution
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
resolution	ADC resolution
<i>ADC_RESOLUTION_12B</i>	12-bit ADC resolution
<i>ADC_RESOLUTION_10B</i>	10-bit ADC resolution
<i>ADC_RESOLUTION_8B</i>	8-bit ADC resolution
<i>ADC_RESOLUTION_6B</i>	6-bit ADC resolution
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC0 data alignment */
adc_data_alignment_config(ADC0, ADC_DATAALIGN_RIGHT);
```

adc_oversample_mode_config

The description of adc_oversample_mode_config is shown as below:

Table 3-14. Function adc_oversample_mode_config

Function name	adc_oversample_mode_config
Function prototype	void adc_oversample_mode_config(uint32_t adc_periph, uint32_t mode, uint16_t shift, uint8_t ratio);
Function descriptions	configure ADC oversample mode
Precondition	-
The called functions	-

Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
mode	ADC oversampling mode
<i>ADC_OVERSAMPLING _ALL_CONVERT</i>	all oversampled conversions for a channel are done consecutively after a trigger
<i>ADC_OVERSAMPLING _ONE_CONVERT</i>	each oversampled conversion for a channel needs a trigger
Input parameter{in}	
shift	ADC oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_NONE</i>	no oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_1B</i>	1-bit oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_2B</i>	2-bit oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_3B</i>	3-bit oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_4B</i>	4-bit oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_5B</i>	5-bit oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_6B</i>	6-bit oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_7B</i>	7-bit oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_8B</i>	8-bit oversampling shift
Input parameter{in}	
ratio	ADC oversampling ratio
<i>ADC_OVERSAMPLING _RATIO_MUL2</i>	oversampling ratio multiple 2
<i>ADC_OVERSAMPLING _RATIO_MUL4</i>	oversampling ratio multiple 4
<i>ADC_OVERSAMPLING _RATIO_MUL8</i>	oversampling ratio multiple 8
<i>ADC_OVERSAMPLING _RATIO_MUL16</i>	oversampling ratio multiple 16
<i>ADC_OVERSAMPLING _RATIO_MUL32</i>	oversampling ratio multiple 32
<i>ADC_OVERSAMPLING _RATIO_MUL64</i>	oversampling ratio multiple 64

ADC_OVERSAMPLING_RATIO_MUL128	oversampling ratio multiple 128
ADC_OVERSAMPLING_RATIO_MUL256	oversampling ratio multiple 256
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC1 oversample mode: 16 times sample, 4 bits shift */
```

```
adc_oversample_mode_config(ADC1, ADC_OVERSAMPLING_ALL_CONVERT,
ADC_OVERSAMPLING_SHIFT_4B, ADC_OVERSAMPLING_RATIO_MUL16);
```

adc_oversample_mode_enable

The description of adc_oversample_mode_enable is shown as below:

Table 3-15. Function adc_oversample_mode_enable

Function name	adc_oversample_mode_enable
Function prototype	void adc_oversample_mode_enable(uint32_t adc_periph);
Function descriptions	enable ADC oversample mode
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
ADCx(x=0,1)	ADC peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable ADC0 oversample mode */
```

```
adc_oversample_mode_enable (ADC0);
```

adc_oversample_mode_disable

The description of adc_oversample_mode_disable is shown as below:

Table 3-16. Function adc_oversample_mode_disable

Function name	adc_oversample_mode_disable
Function prototype	void adc_oversample_mode_disable(uint32_t adc_periph);
Function descriptions	disable ADC oversample mode

Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable ADC0 oversample mode */
adc_oversample_mode_disable (ADC0);
```

adc_dma_mode_enable

The description of adc_dma_mode_enable is shown as below:

Table 3-17. Function adc_dma_mode_enable

Function name	adc_dma_mode_enable
Function prototype	void adc_dma_mode_enable(uint32_t adc_periph);
Function descriptions	enable ADCx DMA request
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable ADC0 DMA request */
adc_dma_mode_enable(ADC0);
```

adc_dma_mode_disable

The description of adc_dma_mode_disable is shown as below:

Table 3-18. Function adc_dma_mode_disable

Function name	adc_dma_mode_disable
Function prototype	void adc_dma_mode_disable(uint32_t adc_periph);
Function descriptions	disable ADCx DMA request

Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable ADC0 DMA request */
```

```
adc_dma_mode_disable(ADC0);
```

adc_discontinuous_mode_config

The description of adc_discontinuous_mode_config is shown as below:

Table 3-19. Function adc_discontinuous_mode_config

Function name	adc_discontinuous_mode_config
Function prototype	void adc_discontinuous_mode_config(uint32_t adc_periph, uint8_t adc_channel_group, uint8_t length);
Function descriptions	configure ADC discontinuous mode
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
adc_channel_group	select the channel group
<i>ADC_REGULAR_CHANNEL</i>	regular channel group
<i>ADC_INSERTED_CHANNEL</i>	inserted channel group
<i>ADC_CHANNEL_DISCON_DISABLE</i>	disable discontinuous mode of regular and inserted channel
Input parameter{in}	
length	number of conversions in discontinuous mode, the number can be 1..8 for regular channel, the number has no effect for inserted channel
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC0 regular channel group discontinuous mode */  
  
adc_discontinuous_mode_config(ADC0, ADC_REGULAR_CHANNEL, 6);
```

adc_channel_length_config

The description of adc_channel_length_config is shown as below:

Table 3-20. Function adc_channel_length_config

Function name	adc_channel_length_config
Function prototype	void adc_channel_length_config(uint32_t adc_periph, uint8_t adc_channel_group, uint32_t length);
Function descriptions	configure the length of regular channel group or inserted channel group
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
ADCx(x=0,1)	ADC peripheral selection
Input parameter{in}	
adc_channel_group	select the channel group
ADC_REGULAR_CHANNEL	regular channel group
ADC_INSERTED_CHANNEL	inserted channel group
Input parameter{in}	
length	the length of the channel, regular channel 1-16, inserted channel 1-4
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the length of ADC0 regular channel */  
  
adc_channel_length_config(ADC0, ADC_REGULAR_CHANNEL, 4);
```

adc_regular_channel_config

The description of adc_regular_channel_config is shown as below:

Table 3-21. Function adc_regular_channel_config

Function name	adc_regular_channel_config
Function prototype	void adc_regular_channel_config(uint32_t adc_periph, uint8_t rank, uint8_t adc_channel, uint32_t sample_time);

Function descriptions	configure ADC regular channel
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
rank	the regular group sequence rank, this parameter must be between 0 to 15
Input parameter{in}	
adc_channel	the selected ADC channel
<i>ADC_CHANNEL_x(x=0..17)</i>	ADC Channelx (x=0..17)(x=16 and x=17 are only for ADC0)
Input parameter{in}	
sample_time	the sample time value
<i>ADC_SAMPLETIME_1 POINT5</i>	1.5 cycles
<i>ADC_SAMPLETIME_7 POINT5</i>	7.5 cycles
<i>ADC_SAMPLETIME_1 3POINT5</i>	13.5 cycles
<i>ADC_SAMPLETIME_2 8POINT5</i>	28.5 cycles
<i>ADC_SAMPLETIME_4 1POINT5</i>	41.5 cycles
<i>ADC_SAMPLETIME_5 5POINT5</i>	55.5 cycles
<i>ADC_SAMPLETIME_7 1POINT5</i>	71.5 cycles
<i>ADC_SAMPLETIME_2 39POINT5</i>	239.5 cycles
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC0 regular channel */
```

```
adc_regular_channel_config(ADC0, 1, ADC_CHANNEL_0, ADC_SAMPLETIME_7POINT5);
```

adc_inserted_channel_config

The description of `adc_inserted_channel_config` is shown as below:

Table 3-22. Function `adc_inserted_channel_config`

Function name	<code>adc_inserted_channel_config</code>
Function prototype	<code>void adc_inserted_channel_config(uint32_t adc_periph, uint8_t rank, uint8_t adc_channel, uint32_t sample_time);</code>
Function descriptions	configure ADC inserted channel
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<code>ADCx(0,1)</code>	ADC peripheral selection
Input parameter{in}	
rank	the inserted group sequencer rank, this parameter must be between 0 to 3
Input parameter{in}	
adc_channel	the selected ADC channel
<code>ADC_CHANNEL_x(x=0..17)</code>	ADC Channelx (x=0..17)(x=16 and x=17 are only for ADC0)
Input parameter{in}	
sample_time	the sample time value
<code>ADC_SAMPLETIME_1POINT5</code>	1.5 cycles
<code>ADC_SAMPLETIME_7POINT5</code>	7.5 cycles
<code>ADC_SAMPLETIME_13POINT5</code>	13.5 cycles
<code>ADC_SAMPLETIME_28POINT5</code>	28.5 cycles
<code>ADC_SAMPLETIME_41POINT5</code>	41.5 cycles
<code>ADC_SAMPLETIME_55POINT5</code>	55.5 cycles
<code>ADC_SAMPLETIME_71POINT5</code>	71.5 cycles
<code>ADC_SAMPLETIME_239POINT5</code>	239.5 cycles
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC0 inserted channel */
```

```
adc_inserted_channel_config(ADC0, 1, ADC_CHANNEL_0, ADC_SAMPLETIME_7POINT5);
```

adc_inserted_channel_offset_config

The description of adc_inserted_channel_offset_config is shown as below:

Table 3-23. Function adc_inserted_channel_offset_config

Function name	adc_inserted_channel_offset_config
Function prototype	void adc_inserted_channel_offset_config(uint32_t adc_periph, uint8_t inserted_channel, uint16_t offset);
Function descriptions	configure ADC inserted channel offset
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
ADCx(x=0,1)	ADC peripheral selection
Input parameter{in}	
inserted_channel	insert channel select
ADC_INSERTED_CHANNEL_x(x=0..3)	inserted channel, x=0,1,2,3
Input parameter{in}	
offset	the offset data, this parameter must be between 0 to 4095
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC0 inserted channel offset */
```

```
adc_inserted_channel_offset_config(ADC0, ADC_INSERTED_CHANNEL_0, 100);
```

adc_external_trigger_source_config

The description of adc_external_trigger_source_config is shown as below:

Table 3-24. Function adc_external_trigger_source_config

Function name	adc_external_trigger_source_config
Function prototype	void adc_external_trigger_source_config(uint32_t adc_periph, uint8_t adc_channel_group, uint32_t external_trigger_source);
Function descriptions	configure ADC external trigger source
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
ADCx(x=0,1)	ADC peripheral selection
Input parameter{in}	

adc_channel_group	select the channel group
<i>ADC_REGULAR_CHANNEL</i>	regular channel group
<i>ADC_INSERTED_CHANNEL</i>	inserted channel group
Input parameter{in}	
external_trigger_source	regular or inserted group trigger source
<i>ADC0_1_EXTTRIGGER_REGULAR_T0_CH0</i>	TIMER0 CH0 event select for regular channel
<i>ADC0_1_EXTTRIGGER_REGULAR_T0_CH1</i>	TIMER0 CH1 event select for regular channel
<i>ADC0_1_EXTTRIGGER_REGULAR_T0_CH2</i>	TIMER0 CH2 event select for regular channel
<i>ADC0_1_EXTTRIGGER_REGULAR_T1_CH1</i>	TIMER1 CH1 event select for regular channel
<i>ADC0_1_EXTTRIGGER_REGULAR_T2_TRGO</i>	TIMER2 TRGO event select for regular channel
<i>ADC0_1_EXTTRIGGER_REGULAR_T3_CH3</i>	TIMER3 CH3 event select for regular channel
<i>ADC0_1_EXTTRIGGER_REGULAR_T7_TRGO</i>	TIMER7 TRGO event select for regular channel
<i>ADC0_1_EXTTRIGGER_REGULAR_EXTI_11</i>	external interrupt line 11 for regular channel
<i>ADC0_1_EXTTRIGGER_REGULAR_NONE</i>	software trigger for regular channel
<i>ADC0_1_EXTTRIGGER_INSERTED_T0_TRGO</i>	TIMER0 TRGO event select for inserted channel
<i>ADC0_1_EXTTRIGGER_INSERTED_T0_CH3</i>	TIMER0 CH3 event select for inserted channel
<i>ADC0_1_EXTTRIGGER_INSERTED_T1_TRGO</i>	TIMER1 TRGO event select for inserted channel
<i>ADC0_1_EXTTRIGGER_INSERTED_T1_CH0</i>	TIMER1 CH0 event select for inserted channel
<i>ADC0_1_EXTTRIGGER_INSERTED_T2_CH3</i>	TIMER2 CH3 event select for inserted channel
<i>ADC0_1_EXTTRIGGER_INSERTED_T3_TRGO</i>	TIMER3 TRGO event select for inserted channel
<i>ADC0_1_EXTTRIGGER_INSERTED_EXTI_15</i>	external interrupt line 15 for inserted channel
<i>ADC0_1_EXTTRIGGER_INSERTED_T7_CH3</i>	TIMER7 CH3 event select for inserted channel
<i>ADC0_1_EXTTRIGGER_INSERTED_NONE</i>	software trigger for inserted channel

<i>SERTE_NONE</i>	
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC0 regular channel external trigger source */
```

```
adc_external_trigger_source_config(ADC0,ADC_REGULAR_CHANNEL,  
ADC0_1_EXTTRIG_REGULAR_T0_CH0);
```

adc_external_trigger_config

The description of adc_external_trigger_config is shown as below:

Table 3-25. Function adc_external_trigger_config

Function name	adc_external_trigger_config
Function prototype	void adc_external_trigger_config(uint32_t adc_periph, uint8_t adc_channel_group, ControlStatus newvalue);
Function descriptions	configure ADC external trigger
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
adc_channel_group	select the channel group
<i>ADC_REGULAR_CHANNEL</i>	regular channel group
<i>ADC_INSERTED_CHANNEL</i>	inserted channel group
Input parameter{in}	
newvalue	control value
<i>ENABLE</i>	enable function
<i>DISABLE</i>	disable function
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable ADC0 inserted channel group external trigger */
```

```
adc_external_trigger_config(ADC0, ADC_INSERTED_CHANNEL_0, ENABLE);
```

adc_software_trigger_enable

The description of adc_software_trigger_enable is shown as below:

Table 3-26. Function adc_software_trigger_enable

Function name	adc_software_trigger_enable
Function prototype	void adc_software_trigger_enable(uint32_t adc_periph, uint8_t adc_channel_group);
Function descriptions	enable ADC software trigger
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
adc_channel_group	select the channel group
<i>ADC_REGULAR_CHANNEL</i>	regular channel group
<i>ADC_INSERTED_CHANNEL</i>	inserted channel group
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable ADC0 regular channel group software trigger */
adc_software_trigger_enable(ADC0, ADC_REGULAR_CHANNEL);
```

adc_regular_data_read

The description of adc_regular_data_read is shown as below:

Table 3-27. Function adc_regular_data_read

Function name	adc_regular_data_read
Function prototype	uint16_t adc_regular_data_read(uint32_t adc_periph);
Function descriptions	read ADC regular group data register
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Output parameter{out}	
-	-

Return value	
uint16_t	ADC conversion value (0-0xFFFF)

Example:

```
/* read ADC0 regular group data register */
```

```
uint16_t adc_value = 0;
```

```
adc_value = adc_regular_data_read(ADC0);
```

adc_inserted_data_read

The description of adc_inserted_data_read is shown as below:

Table 3-28. Function adc_inserted_data_read

Function name	adc_inserted_data_read
Function prototype	uint16_t adc_inserted_data_read(uint32_t adc_periph, uint8_t inserted_channel);
Function descriptions	read ADC inserted group data register
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
ADCx(x=0,1)	ADC peripheral selection
Input parameter{in}	
inserted_channel	insert channel select
ADC_INSERTED_CHANNEL_0 ADC_INSERTED_CHANNEL_1 ADC_INSERTED_CHANNEL_2 ADC_INSERTED_CHANNEL_3	inserted Channelx, x=0,1,2,3
Output parameter{out}	
-	-
Return value	
uint16_t	ADC conversion value (0-0xFFFF)

Example:

```
/* read ADC0 inserted group data register */
```

```
uint16_t adc_value = 0;
```

```
adc_value = adc_inserted_data_read (ADC0, ADC_INSERTED_CHANNEL_0);
```

adc_sync_mode_convert_value_read

The description of adc_sync_mode_convert_value_read is shown as below:

Table 3-29. Function adc_sync_mode_convert_value_read

Function name	adc_sync_mode_convert_value_read
Function prototype	uint32_t adc_sync_mode_convert_value_read(void);

Function descriptions	read the last ADC0 and ADC1 conversion result data in sync mode
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint32_t	ADC conversion value (0-0xFFFFFFFF)

Example:

```
/* read the last ADC0 and ADC1 conversion result data in sync mode */

uint32_t adc_value = 0;

adc_value = adc_sync_mode_convert_value_read ();
```

adc_watchdog_single_channel_enable

The description of adc_watchdog_single_channel_enable is shown as below:

Table 3-30. Function adc_watchdog_single_channel_enable

Function name	adc_watchdog_single_channel_enable
Function prototype	void adc_watchdog_single_channel_enable(uint32_t adc_periph, uint8_t adc_channel);
Function descriptions	configure ADC analog watchdog single channel
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
adc_channel	the selected ADC channel
<i>ADC_CHANNEL_x(x=0..17)</i>	ADC Channelx(x=0..17) (x=16 and x=17 are only for ADC0)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC0 analog watchdog single channel */

adc_watchdog_single_channel_enable(ADC0, ADC_CHANNEL_1);
```

adc_watchdog_group_channel_enable

The description of adc_watchdog_group_channel_enable is shown as below:

Table 3-31. Function adc_watchdog_group_channel_enable

Function name	adc_watchdog_group_channel_enable
Function prototype	void adc_watchdog_group_channel_enable(uint32_t adc_periph, uint8_t adc_channel_group);
Function descriptions	configure ADC analog watchdog group channel
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
adc_channel_group	the channel group use analog watchdog
<i>ADC_REGULAR_CHANNEL</i>	regular channel group
<i>ADC_INSERTED_CHANNEL</i>	inserted channel group
<i>ADC_REGULAR_INSERTED_CHANNEL</i>	both regular and inserted group
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC0 analog watchdog group channel */
```

```
adc_watchdog_group_channel_enable(ADC0, ADC_REGULAR_CHANNEL);
```

adc_watchdog_disable

The description of adc_watchdog_disable is shown as below:

Table 3-32. Function adc_watchdog_disable

Function name	adc_watchdog_disable
Function prototype	void adc_watchdog_disable(uint32_t adc_periph);
Function descriptions	disable ADC analog watchdog
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(0,1)</i>	ADC peripheral selection

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable ADC0 analog watchdog */
```

```
adc_watchdog_disable(ADC0);
```

adc_watchdog_threshold_config

The description of adc_watchdog_threshold_config is shown as below:

Table 3-33. Function adc_watchdog_threshold_config

Function name	adc_watchdog_threshold_config
Function prototype	void adc_watchdog_threshold_config(uint32_t adc_periph, uint16_t low_threshold, uint16_t high_threshold);
Function descriptions	configure ADC analog watchdog threshold
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
ADCx(x=0,1)	ADC peripheral selection
Input parameter{in}	
low_threshold	analog watchdog low threshold, 0..4095
Input parameter{in}	
high_threshold	analog watchdog high threshold, 0..4095
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC0 analog watchdog threshold */
```

```
adc_watchdog_threshold_config(ADC0, 0x0400, 0x0A00);
```

adc_flag_get

The description of adc_flag_get is shown as below:

Table 3-34. Function adc_flag_get

Function name	adc_flag_get
Function prototype	FlagStatus adc_flag_get(uint32_t adc_periph , uint32_t adc_flag);
Function descriptions	get the ADC flag bits

Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
adc_flag	the adc flag bits
<i>ADC_FLAG_WDE</i>	analog watchdog event flag
<i>ADC_FLAG_EOC</i>	end of group conversion flag
<i>ADC_FLAG_EOIC</i>	end of inserted group conversion flag
<i>ADC_FLAG_STIC</i>	start flag of inserted channel group
<i>ADC_FLAG_STRC</i>	start flag of regular channel group
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get the ADC0 analog watchdog flag bits*/
```

```
FlagStatus flag_value;
```

```
flag_value = adc_flag_get(ADC0, ADC_FLAG_WDE);
```

adc_flag_clear

The description of adc_flag_clear is shown as below:

Table 3-35. Function adc_flag_clear

Function name	adc_flag_clear
Function prototype	void adc_flag_clear(uint32_t adc_periph, uint32_t adc_flag);
Function descriptions	clear the ADC flag bits
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
adc_flag	the adc flag bits
<i>ADC_FLAG_WDE</i>	analog watchdog event flag
<i>ADC_FLAG_EOC</i>	end of group conversion flag
<i>ADC_FLAG_EOIC</i>	end of inserted group conversion flag
<i>ADC_FLAG_STIC</i>	start flag of inserted channel group
<i>ADC_FLAG_STRC</i>	start flag of regular channel group

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear the ADC0 analog watchdog flag bits*/
```

```
adc_flag_clear(ADC0, ADC_FLAG_WDE);
```

adc_regular_software_startconv_flag_get

The description of adc_regular_software_startconv_flag_get is shown as below:

Table 3-36. Function adc_regular_software_startconv_flag_get

Function name	adc_regular_software_startconv_flag_get
Function prototype	FlagStatus adc_regular_software_startconv_flag_get(uint32_t adc_periph);
Function descriptions	get the bit state of ADCx software regular channel start conversion
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
ADCx(x=0,1)	ADC peripheral selection
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get the bit state of ADC0 software regular channel start conversion */
```

```
FlagStatus flag_value;
```

```
flag_value = adc_regular_software_startconv_flag_get(ADC0);
```

adc_inserted_software_startconv_flag_get

The description of adc_inserted_software_startconv_flag_get is shown as below:

Table 3-37. Function adc_inserted_software_startconv_flag_get

Function name	adc_inserted_software_startconv_flag_get
Function prototype	FlagStatus adc_inserted_software_startconv_flag_get(uint32_t adc_periph);
Function descriptions	get the bit state of ADCx software inserted channel start conversion
Precondition	-
The called functions	-
Input parameter{in}	

adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get the bit state of ADC0 software inserted channel start conversion */
```

```
FlagStatus flag_value;
```

```
flag_value = adc_inserted_software_startconv_flag_get(ADC0);
```

adc_interrupt_flag_get

The description of adc_interrupt_flag_get is shown as below:

Table 3-38. Function adc_interrupt_flag_get

Function name	adc_interrupt_flag_get
Function prototype	FlagStatus adc_interrupt_flag_get(uint32_t adc_periph, uint32_t adc_interrupt);
Function descriptions	get the ADC interrupt bits
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
adc_interrupt	the adc interrupt bits
<i>ADC_INT_WDE</i>	analog watchdog interrupt
<i>ADC_INT_EOC</i>	end of group conversion interrupt
<i>ADC_INT_EOIC</i>	end of inserted group conversion interrupt
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get the ADC0 analog watchdog interrupt bits*/
```

```
FlagStatus flag_value;
```

```
flag_value = adc_interrupt_flag_get(ADC0, ADC_INT_WDE);
```

adc_interrupt_flag_clear

The description of adc_interrupt_flag_clear is shown as below:

Table 3-39. Function adc_interrupt_flag_clear

Function name	adc_interrupt_flag_clear
Function prototype	void adc_interrupt_flag_clear(uint32_t adc_periph, uint32_t adc_interrupt);
Function descriptions	clear the ADC interrupt bits
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
adc_interrupt	the adc interrupt bits
<i>ADC_INT_WDE</i>	analog watchdog interrupt
<i>ADC_INT_EOC</i>	end of group conversion interrupt
<i>ADC_INT_EOIC</i>	end of inserted group conversion interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear the ADC0 analog watchdog interrupt bits*/
adc_interrupt_flag_clear(ADC0, ADC_INT_WDE);
```

adc_interrupt_enable

The description of adc_interrupt_enable is shown as below:

Table 3-40. Function adc_interrupt_enable

Function name	adc_interrupt_enable
Function prototype	void adc_interrupt_enable(uint32_t adc_periph, uint32_t adc_interrupt);
Function descriptions	enable ADC interrupt
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
adc_interrupt	the adc interrupt
<i>ADC_INT_WDE</i>	analog watchdog interrupt
<i>ADC_INT_EOC</i>	end of group conversion interrupt

<i>ADC_INT_EOIC</i>	end of inserted group conversion interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable ADC0 analog watchdog interrupt */
adc_interrupt_enable(ADC0, ADC_INT_WDE);
```

adc_interrupt_disable

The description of `adc_interrupt_disable` is shown as below:

Table 3-41. Function `adc_interrupt_disable`

Function name	<code>adc_interrupt_disable</code>
Function prototype	<code>void adc_interrupt_disable(uint32_t adc_periph , uint32_t adc_interrupt);</code>
Function descriptions	Disable ADC interrupt
Precondition	-
The called functions	-
Input parameter{in}	
adc_periph	ADC peripheral
<i>ADCx(x=0,1)</i>	ADC peripheral selection
Input parameter{in}	
adc_interrupt	the adc interrupt
<i>ADC_INT_WDE</i>	analog watchdog interrupt
<i>ADC_INT_EOC</i>	end of group conversion interrupt
<i>ADC_INT_EOIC</i>	end of inserted group conversion interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable ADC0 interrupt */
adc_interrupt_disable(ADC0, ADC_INT_WDE);
```

3.3. BKP

The Backup registers are located in the Backup domain that remains powered-on by V_{BAT} even if V_{DD} power is shut down, they are forty two 16-bit (84 bytes) registers for data protection of user application data, and the wake-up action from Standby mode or system reset do not

affect these registers. The BKP registers are listed in chapter [3.3.1](#), the BKP firmware functions are introduced in chapter [3.3.2](#).

3.3.1. Descriptions of Peripheral registers

BKP registers are listed in the table shown as below:

Table 3-42. BKP Registers

Registers	Descriptions
BKP_DATAx (x= 0..41)	Backup data register
BKP_OCTL	RTC signal output control register
BKP_TPCTL	Tamper pin control register
BKP_TPCS	Tamper control and status register

3.3.2. Descriptions of Peripheral functions

BKP firmware functions are listed in the table shown as below:

Table 3-43. BKP firmware function

Function name	Function description
bkp_deinit	reset data registers
bkp_data_write	write data register
bkp_data_read	read data register
bkp_rtc_calibration_output_enable	enable RTC clock calibration output
bkp_rtc_calibration_output_disable	disable RTC clock calibration output
bkp_rtc_signal_output_enable	enable RTC alarm or second signal output
bkp_rtc_signal_output_disable	disable RTC alarm or second signal output
bkp_rtc_output_select	select RTC output, the RTC output can be select as alarm pulse or second pulse
bkp_rtc_clock_output_select	select RTC clock output
bkp_rtc_clock_calibration_direction_select	select RTC clock calibration direction
bkp_rtc_calibration_value_set	set RTC clock calibration value
bkp_tamper_detection_enable	enable tamper detection
bkp_tamper_detection_disable	disable tamper detection
bkp_tamper_active_level_set	set tamper pin active level
bkp_interrupt_enable	enable tamper interrupt
bkp_interrupt_disable	disable tamper interrupt
bkp_flag_get	get bkp flag state
bkp_flag_clear	clear bkp flag state
bkp_interrupt_flag_get	get bkp interrupt flag state
bkp_interrupt_flag_clear	clear bkp interrupt flag state

bkp_deinit

The description of bkp_deinit is shown as below:

Table 3-44. Function bkp_deinit

Function name	bkp_deinit
Function prototype	void bkp_deinit(void);
Function descriptions	reset data registers
Precondition	-
The called functions	rcu_bkp_reset_enable / rcu_bkp_reset_disable
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset BKP registers */
```

```
bkp_deinit ();
```

bkp_data_write

The description of bkp_data_write is shown as below:

Table 3-45. Function bkp_data_write

Function name	bkp_data_write
Function prototype	void bkp_data_write(bkp_data_register_enum register_number, uint16_t data);
Function descriptions	write data register
Precondition	-
The called functions	-
Input parameter{in}	
register_number	refer to bkp_data_register_enum
<i>BKP_DATA_x(x = 0..41)</i>	bkp data register number x
Input parameter{in}	
data	the data to be write in BKP data register
<i>0-0xffff</i>	data value
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* write BKP data register */

bkp_data_write (BKP_DATA_0, 0x1226);
```

bkp_data_read

The description of bkp_data_read is shown as below:

Table 3-46. Function bkp_data_read

Function name	bkp_data_read
Function prototype	uint16_t bkp_data_read (bkp_data_register_enum register_number);
Function descriptions	read data register
Precondition	-
The called functions	-
Input parameter{in}	
register_number	refer to bkp_data_register_enum
<i>BKP_DATA_x(x = 0..41)</i>	bkp data register number x
Output parameter{out}	
-	-
Return value	
uint16_t	0-0xffff

Example:

```
/* read BKP data register */

uint16_t data;

data = bkp_data_read (BKP_DATA_0);
```

bkp_rtc_calibration_output_enable

The description of bkp_rtc_calibration_output_enable is shown as below:

Table 3-47. Function bkp_rtc_calibration_output_enable

Function name	bkp_rtc_calibration_output_enable
Function prototype	void bkp_rtc_calibration_output_enable(void);
Function descriptions	enable RTC clock calibration output
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* enable RTC clock calibration output */
```

```
bkp_rtc_calibration_output_enable();
```

bkp_rtc_calibration_output_disable

The description of bkp_rtc_calibration_output_disable is shown as below:

Table 3-48. Function bkp_rtc_calibration_output_disable

Function name	bkp_rtc_calibration_output_disable
Function prototype	void bkp_rtc_calibration_output_disable(void);
Function descriptions	disable RTC clock calibration output
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable RTC clock calibration output */
```

```
bkp_rtc_calibration_output_disable();
```

bkp_rtc_signal_output_enable

The description of bkp_rtc_signal_output_enable is shown as below:

Table 3-49. Function bkp_rtc_signal_output_enable

Function name	bkp_rtc_signal_output_enable
Function prototype	void bkp_rtc_signal_output_enable (void);
Function descriptions	enable RTC alarm or second signal output
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable RTC alarm or second signal output */
```

```
bkp_rtc_signal_output_enable();
```

bkp_rtc_signal_output_disable

The description of bkp_rtc_signal_output_disable is shown as below:

Table 3-50. Function bkp_rtc_signal_output_disable

Function name	bkp_rtc_signal_output_disable
Function prototype	void bkp_rtc_signal_output_disable (void);
Function descriptions	disable RTC alarm or second signal output
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable RTC alarm or second signal output */
```

```
bkp_rtc_signal_output_disable();
```

bkp_rtc_output_select

The description of bkp_rtc_output_select is shown as below:

Table 3-51. Function bkp_rtc_output_select

Function name	bkp_rtc_output_select
Function prototype	void bkp_rtc_output_select (uint16_t outputsel);
Function descriptions	select RTC output, the RTC output can be select as alarm pulse or second pulse
Precondition	-
The called functions	-
Input parameter{in}	
outputsel	RTC output selection
<i>RTC_OUTPUT_ALARM_PULSE</i>	RTC alarm pulse is selected as the RTC output
<i>RTC_OUTPUT_SECONDS_PULSE</i>	RTC second pulse is selected as the RTC output
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* select RTC output alarm signal output */
```

```
bkp_rtc_output_select (RTC_OUTPUT_ALARM_PULSE);
```

bkp_rtc_clock_output_select

The description of bkp_rtc_clock_output_select is shown as below:

Table 3-52. Function bkp_rtc_clock_output_select

Function name	bkp_rtc_clock_output_select
Function prototype	void bkp_rtc_clock_output_select(uint16_t clocksel);
Function descriptions	select RTC clock output, the RTC clock output can be select as divided 64 or no division
Precondition	-
The called functions	-
Input parameter{in}	
clocksel	RTC clock output selection
<i>RTC_CLOCK_DIV_64</i>	RTC clock divided 64 is selected as the RTC clock output
<i>RTC_CLOCK_DIV_1</i>	RTC clock is selected as the RTC clock output
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* select RTC clock divided 64 to output */
```

```
bkp_rtc_clock_output_select (RTC_CLOCK_DIV_64);
```

bkp_rtc_clock_calibration_direction_select

The description of bkp_rtc_clock_calibration_direction_select is shown as below:

Table 3-53. Function bkp_rtc_clock_calibration_direction_select

Function name	bkp_rtc_clock_calibration_direction_select
Function prototype	void bkp_rtc_clock_calibration_direction_select(uint16_t direction);
Function descriptions	select RTC clock calibration direction, the RTC clock calibration direction can be select as slowed down or speed up
Precondition	-
The called functions	-
Input parameter{in}	

direction	RTC clock calibration direction
<i>RTC_CLOCK_SLOW_DOWN</i>	RTC clock slow down
<i>RTC_CLOCK_SPEED_UP</i>	RTC clock speed up
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set RTC clock slowed down */
```

```
bkp_rtc_clock_calibration_direction_select (RTC_CLOCK_SLOWED_DOWN);
```

bkp_rtc_calibration_value_set

The description of bkp_rtc_calibration_value_set is shown as below:

Table 3-54. Function bkp_rtc_calibration_value_set

Function name	bkp_rtc_calibration_value_set
Function prototype	void bkp_rtc_calibration_value_set(uint8_t value);
Function descriptions	set RTC clock calibration value
Precondition	-
The called functions	-
Input parameter{in}	
value	RTC clock calibration value
<i>0x00 - 0x7F</i>	value
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set RTC clock calibration value */
```

```
bkp_rtc_calibration_value_set (0x7f);
```

bkp_tamper_detection_enable

The description of bkp_tamper_detection_enable is shown as below:

Table 3-55. Function bkp_tamper_detection_enable

Function name	bkp_tamper_detection_enable
Function prototype	void bkp_tamper_detection_enable (void);
Function descriptions	enable tamper detection

Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable tamper pin detection */
```

```
bkp_tamper_detection_enable();
```

bkp_tamper_detection_disable

The description of bkp_tamper_detection_disable is shown as below:

Table 3-56. Function bkp_tamper_detection_disable

Function name	bkp_tamper_detection_disable
Function prototype	void bkp_tamper_detection_disable (void);
Function descriptions	disable tamper detection
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable tamper pin detection */
```

```
bkp_tamper_detection_disable();
```

bkp_tamper_active_level_set

The description of bkp_tamper_active_level_set is shown as below:

Table 3-57. Function bkp_tamper_active_level_set

Function name	bkp_tamper_active_level_set
Function prototype	void bkp_tamper_active_level_set (uint16_t level);
Function descriptions	set tamper pin active level
Precondition	-
The called functions	-

Input parameter{in}	
level	tamper pin active level
<i>TAMPER_PIN_ACTIVE_HIGH</i>	the tamper pin is active high
<i>TAMPER_PIN_ACTIVE_LOW</i>	the tamper pin is active low
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set tamper pin active level high */
```

```
bkp_tamper_active_level_set (TAMPER_PIN_ACTIVE_HIGH);
```

bkp_interrupt_enable

The description of bkp_interrupt_enable is shown as below:

Table 3-58. Function bkp_interrupt_enable

Function name	bkp_interrupt_enable
Function prototype	void bkp_interrupt_enable (void);
Function descriptions	enable tamper interrupt
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable tamper pin interrupt */
```

```
bkp_interrupt_enable ();
```

bkp_interrupt_disable

The description of bkp_interrupt_disable is shown as below:

Table 3-59. Function bkp_interrupt_disable

Function name	bkp_interrupt_disable
Function prototype	void bkp_interrupt_disable (void);
Function descriptions	disable tamper interrupt

Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable tamper pin interrupt */
```

```
bkp_interrupt_disable ();
```

bkp_flag_get

The description of bkp_flag_get is shown as below:

Table 3-60. Function bkp_flag_get

Function name	bkp_flag_get
Function prototype	FlagStatus bkp_flag_get(void);
Function descriptions	get bkp flag state
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get BKP flag state */
```

```
FlagStatus status;
```

```
status = bkp_flag_get ();
```

bkp_flag_clear

The description of bkp_flag_clear is shown as below:

Table 3-61. Function bkp_flag_clear

Function name	bkp_flag_clear
Function prototype	void bkp_flag_clear(void);
Function descriptions	clear bkp flag state

Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear BKP flag state */
```

```
bkp_flag_clear ();
```

bkp_interrupt_flag_get

The description of bkp_interrupt_flag_get is shown as below:

Table 3-62. Function bkp_interrupt_flag_get

Function name	bkp_interrupt_flag_get
Function prototype	FlagStatus bkp_interrupt_flag_get(void);
Function descriptions	get bkp interrupt flag state
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get BKP interrupt flag state */
```

```
bkp_interrupt_flag_get ();
```

bkp_interrupt_flag_clear

The description of bkp_interrupt_flag_clear is shown as below:

Table 3-63. Function bkp_interrupt_flag_clear

Function name	bkp_interrupt_flag_clear
Function prototype	void bkp_interrupt_flag_clear(void);
Function descriptions	clear bkp interrupt flag state
Precondition	-
The called functions	-

Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear BKP interrupt flag state */
```

```
bkp_interrupt_flag_clear ();
```

3.4. CAN

CAN bus (for Controller Area Network) is a bus standard designed to allow microcontrollers and devices to communicate with each other without a host computer. The CAN registers are listed in chapter [3.4.1](#), the CAN firmware functions are introduced in chapter [3.4.2](#).

3.4.1. Descriptions of Peripheral registers

CAN registers are listed in the table shown as below:

Table 3-64. CAN Registers

Registers	Descriptions
CAN_CTL	Control register
CAN_STAT	Status register
CAN_TSTAT	Transmit status register
CAN_RFIFO0	Receive message FIFO0 register
CAN_RFIFO1	Receive message FIFO1 register
CAN_INTEN	Interrupt enable register
CAN_ERR	Error register
CAN_BT	Bit timing register
CAN_FDCTL	FD control register
CAN_FDSTAT	FD status register
CAN_FDTDC	FD transmitter delay compensation register
CAN_DBT	Date Bit timing register
CAN_TMIx	Transmit mailbox identifier register
CAN_TMPx	Transmit mailbox property register
CAN_TMDATA0x	Transmit mailbox data0 register
CAN_TMDATA1x	Transmit mailbox data1 register
CAN_RFIFOMIx	Receive FIFO mailbox identifier register
CAN_RFIFOMPx	Receive FIFO mailbox property register
CAN_RFIFOMDAT	Receive FIFO mailbox data0 register

Registers	Descriptions
A0x	
CAN_RFIFOMDAT A1x	Receive FIFO mailbox data1 register
CAN_FCTL	Filter control register
CAN_FMCFG	Filter mode configuration register
CAN_FSCFG	Filter scale configuration register
CAN_FAFIFO	Filter associated FIFO registe
CAN_FW	Filter working register
CAN_FxDATAy	Filter x data y register

3.4.2. Descriptions of Peripheral functions

CAN firmware functions are listed in the table shown as below:

Table 3-65. CAN firmware function

Function name	Function description
can_deinit	deinitialize CAN
can_struct_para_init	initialize CAN parameter struct with a default value
can_init	initialize CAN
can_fd_init	initialize CAN FD function
can_filter_init	initialize CAN filter
can_filter_mask_mode_init	CAN filter mask mode initialization
can_monitor_mode_set	CAN communication mode configure
can_fd_function_enable	CAN FD frame function enable
can_fd_function_disable	CAN FD frame function disable
can1_filter_start_bank	set can1 fliter start bank number
can_debug_freeze_enable	CAN debug freeze enable
can_debug_freeze_disable	CAN debug freeze disable
can_time_trigger_mode_enable	CAN time trigggle mode enable
can_time_trigger_mode_disable	CAN time trigggle mode disable
can_message_transmit	transmit CAN message
can_transmit_states	get CAN transmit state
can_transmission_stop	stop CAN transmission
can_message_receive	CAN receive message
can_fifo_release	CAN release fifo
can_receive_message_length_get	CAN receive message length
can_working_mode_set	CAN working mode
can_wakeup	CAN wakeup from sleep mode
can_error_get	CAN get error
can_receive_error_number_get	get CAN receive error number
can_transmit_error_number_get	get CAN transmit error number
can_interrupt_enable	CAN interrupt enable

Function name	Function description
can_interrupt_disable	CAN interrupt disable
can_flag_get	CAN get flag state
can_flag_clear	CAN clear flag state
can_interrupt_flag_get	CAN get interrupt flag state
can_interrupt_flag_clear	CAN clear interrupt flag state

Structure can_parameter_struct

Table 3-66. Structure can_parameter_struct

Member name	Function description
working_mode	CAN working mode
resync_jump_width	CAN resynchronization jump width
time_segment_1	time segment 1
time_segment_2	time segment 2
time_triggered	time triggered communication mode
auto_bus_off_recovery	automatic bus-off recovery
auto_wake_up	automatic wake-up mode
auto_retrans	automatic retransmission mode
rec_fifo_overwrite	receive FIFO overwrite mode
trans_fifo_order	transmit FIFO order
prescaler	baudrate prescaler

Structure can_transmit_message_struct

Table 3-67. Structure can_transmit_message_struct

Member name	Function description
tx_sfid	standard format frame identifier
tx_efid	extended format frame identifier
tx_ff	format of frame, standard or extended format
tx_ft	type of frame, data or remote
tx_dlen	data length
tx_data[64]	transmit data
fd_flag	CAN FD frame flag
fd_brs	bit rate of data switch
fd_esi	error status indicator

Structure can_receive_message_struct

Table 3-68. Structure can_receive_message_struct

Member name	Function description
rx_sfid	standard format frame identifier
rx_efid	extended format frame identifier

Member name	Function description
rx_ff	format of frame, standard or extended format
rx_ft	type of frame, data or remote
rx_dlen	data length
rx_data[8]	receive data
rx_fi	filtering index
fd_flag	CAN FD frame flag
fd_brs	bit rate of data switch
fd_esi	error status indicator

Structure can_filter_parameter_struct

Table 3-69. Structure can_filter_parameter_struct

Member name	Function description
filter_list_high	filter list number high bits
filter_list_low	filter list number low bits
filter_mask_high	filter mask number high bits
filter_mask_low	filter mask number low bits
filter_fifo_number	receive FIFO associated with the filter
filter_number	filter number
filter_mode	filter mode, list or mask
filter_bits	filter scale
filter_enable	filter work or not

Structure can_fd_tdc_struct

Table 3-70. Structure can_fd_tdc_struct

Member name	Function description
tdc_mode	transmitter delay compensation mode
tdc_filter	transmitter delay compensation filter
tdc_offset	transmitter delay compensation offset

Structure can_fdframe_struct

Table 3-71. Structure can_fdframe_struct

Member name	Function description
fd_frame	FD operation function
excp_event_detect	protocol exception event detection function
delay_compensation	transmitter delay compensation mode
p_delay_compensation	pointer to the struct of the transmitter delay compensation, refer to Table 3-70. Structure can_fd_tdc_struct
iso_bosch	ISO/Bosch mode choice
esi_mode	error state indicator mode
data_resync_jump_	CAN resynchronization jump width

Member name	Function description
width	
data_time_segment _1	time segment 1
data_time_segment _2	time segment 2
data_prescaler	baudrate prescaler

can_deinit

The description of can_deinit is shown as below:

Table 3-72. Function can_deinit

Function name	can_deinit
Function prototype	void can_deinit(uint32_t can_periph);
Function descriptions	deinitialize CAN
Precondition	-
The called functions	rcu_periph_reset_enable/ rcu_periph_reset_disable
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
-	-
Function name	can_deinit
Function prototype	void can_deinit(uint32_t can_periph);
Function descriptions	deinitialize CAN
Precondition	-
The called functions	rcu_periph_reset_enable/ rcu_periph_reset_disable
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* CAN0 deinitialize */
can_deinit(CAN0);
```

can_struct_para_init

The description of can_struct_para_init is shown as below:

Table 3-73. Function can_struct_para_init

Function name	can_struct_para_init
Function prototype	void can_struct_para_init(can_struct_type_enum type, void* p_struct)
Function descriptions	initialize CAN parameter struct with a default value
Precondition	-
The called functions	-
Input parameter{in}	
type	CAN peripheral
CAN_INIT_STRUCT	CAN initialize parameters struct
CAN_FILTER_STRUCT	CAN filter parameters struct
CAN_FD_FRAME_STRUCT	CAN initialize FD frame parameters struct
CAN_TX_MESSAGE_STRUCT	CAN transmit message struct
CAN_RX_MESSAGE_STRUCT	CAN receive message struct
Output parameter{out}	
p_struct	the struct pointer that needs initialize
Return value	
-	-

Example:

```
/* Initialize CAN parameter struct */
can_parameter_struct can_init;
can_struct_para_init (CAN_INIT_STRUCT, &can_init);
```

can_init

The description of can_init is shown as below:

Table 3-74. Function can_init

Function name	can_init
Function prototype	ErrStatus can_init(uint32_t can_periph, can_parameter_struct* can_parameter_init);
Function descriptions	initialize CAN
Precondition	can_struct_para_init()
The called functions	-
Input parameter{in}	

can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
can_parameter_init	CAN parameter initialization stuct, the structure members can refer to members of the structure Table 3-66. Structure <i>can_parameter</i> struct
Output parameter{out}	
-	-
Return value	
ErrStatus	SUCCESS / ERROR
Function name	can_init
Function prototype	ErrStatus can_init(uint32_t can_periph, can_parameter_struct* can_parameter_init);
Function descriptions	initialize CAN
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
can_parameter_init	CAN parameter initialization stuct, the structure members can refer to members of the structure Table 3-66. Structure <i>can_parameter</i> struct
Output parameter{out}	
-	-
Return value	
ErrStatus	SUCCESS / ERROR

Example:

```
/* CAN0 initialize*/

can_parameter_struct can_parameter_init;

can_init (CAN0, &can_parameter_init);
```

can_fd_init

The description of can_fd_init is shown as below:

Table 3-75. Function can_fd_init

Function name	can_fd_init
Function prototype	ErrStatus can_fd_init(uint32_t can_periph, can_fdframe_struct* can_fdframe_init);
Function descriptions	initialize CAN FD function
Precondition	can_struct_para_init()

The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
CANx(x=0,1)	CAN peripheral selection
Input parameter{in}	
can_fdframe_init	parameters for CAN FD initialization, the structure members can refer to members of the structure Table 3-71. Structure can_fdframe_struct
Output parameter{out}	
-	-
Return value	
ErrStatus	SUCCESS / ERROR

Example:

```
/* CAN0 FD initialize*/
```

```
can_fdframe_struct fd_init_para;
```

```
can_fd_init(CAN0, &fd_init_para);
```

can_filter_init

The description of can_filter_init is shown as below:

Table 3-76. Function can_filter_init

Function name	can_filter_init
Function prototype	void can_filter_init(can_filter_parameter_struct* can_filter_parameter_init);
Function descriptions	initialize CAN filter
Precondition	can_struct_para_init()
The called functions	-
Input parameter{in}	
can_filter_parameter_init	CAN filter initialization struct, the structure members can refer to members of the structure Table 3-69. Structure can_filter_parameter_struct
Output parameter{out}	
-	-
Return value	
-	-
Function name	can_filter_init
Function prototype	void can_filter_init(can_filter_parameter_struct* can_filter_parameter_init);
Function descriptions	initialize CAN filter
Precondition	-
The called functions	-
Input parameter{in}	
can_filter_parameter_init	CAN filter initialization struct, the structure members can refer to members of the structure Table 3-69. Structure can_filter_parameter_struct
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* initialize CAN filter */
```

```
can_filter_init(&can_filter);
```

can_filter_mask_mode_init

The description of can_filter_mask_mode_init is shown as below:

Table 3-77. Function can_filter_mask_mode_init

Function name	can_filter_mask_mode_init
Function prototype	void can_filter_mask_mode_init(uint32_t id, uint32_t mask, can_format_fifo_enum format_fifo, uint16_t filter_number)
Function descriptions	CAN filter mask mode initialization
Precondition	-
The called functions	can_filter_init()
Input parameter{in}	
id	value range (0x00000000 - 0xFFFFFFFF)
Input parameter{in}	
mask	value range (0x00000000 - 0xFFFFFFFF)
Input parameter{in}	
format_fifo	format and fifo states, only one parameter can be selected which is shown as below
CAN_STANDARD_FIFO0	standard format and store to FIFO0
CAN_STANDARD_FIFO1	standard format and store to FIFO1
CAN_EXTENDED_FIFO0	extended format and store to FIFO0
CAN_EXTENDED_FIFO1	extended format and store to FIFO1
Input parameter{in}	
filter_number	filter sequence number, value range(0x00 - 0x1C)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* CAN filter mask mode initialization */
```

```
can_filter_mask_mode_init(0x11, 0x11, CAN_STANDARD_FIFO0, 0);
```

can_monitor_mode_set

The description of can_monitor_mode_set is shown as below:

Table 3-78. Function can_monitor_mode_set

Function name	can_monitor_mode_set
Function prototype	ErrStatus can_monitor_mode_set(uint32_t can_periph, uint8_t mode)
Function descriptions	CAN communication mode configure
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
mode	communication mode, only one parameter can be selected which is shown as below
<i>CAN_NORMAL_MODE</i>	normal mode
<i>CAN_LOOPBACK_MODE</i>	loopback mode
<i>CAN_SILENT_MODE</i>	silent mode
<i>CAN_SILENT_LOOPBACK_MODE</i>	silent loopback mode
Output parameter{out}	
-	-
Return value	
ErrStatus	SUCCESS / ERROR

Example:

```
/* CAN communication mode configure */
```

```
can_monitor_mode_set(CAN0, CAN_NORMAL_MODE);
```

can_fd_function_enable

The description of can_fd_function_enable is shown as below:

Table 3-79. Function can_fd_function_enable

Function name	can_fd_function_enable
Function prototype	void can_fd_function_enable(uint32_t can_periph)
Function descriptions	CAN FD frame function enable
Precondition	-
The called functions	-
Input parameter{in}	

can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* CAN0 FD frame function enable */
```

```
can_fd_function_enable(CAN0);
```

can_fd_function_disable

The description of can_fd_function_disable is shown as below:

Table 3-80. Function can_fd_function_disable

Function name	can_fd_function_disable
Function prototype	void can_fd_function_disable(uint32_t can_periph)
Function descriptions	CAN FD frame function disable
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* CAN0 FD frame function disable */
```

```
can_fd_function_disable(CAN0);
```

can1_filter_start_bank

The description of can1_filter_start_bank is shown as below:

Table 3-81. Function can1_filter_start_bank

Function name	can1_filter_start_bank
Function prototype	void can1_filter_start_bank(uint8_t start_bank);
Function descriptions	set CAN1 filter start bank number
Precondition	-
The called functions	-
Input parameter{in}	

start_bank	CAN1 start bank number
1..27	start number
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set CAN1 fliter start bank number 15*/
```

```
can1_filter_start_bank (15);
```

can_debug_freeze_enable

The description of can_debug_freeze_enable is shown as below:

Table 3-82. Function can_debug_freeze_enable

Function name	can_debug_freeze_enable
Function prototype	void can_debug_freeze_enable(uint32_t can_periph);
Function descriptions	enable CAN debug freeze
Precondition	-
The called functions	dbg_periph_enable
Input parameter{in}	
can_periph	CAN peripheral
CANx(x=0,1)	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
-	-
Function name	can_debug_freeze_enable
Function prototype	void can_debug_freeze_enable(uint32_t can_periph);
Function descriptions	enable CAN debug freeze
Precondition	-
The called functions	dbg_periph_enable
Input parameter{in}	
can_periph	CAN peripheral
CANx(x=0,1)	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable CAN0 debug freeze */
```


can_debug_freeze_enable (CAN0);

can_debug_freeze_disable

The description of can_debug_freeze_disable is shown as below:

Table 3-83. Function can_debug_freeze_disable

Function name	can_debug_freeze_disable
Function prototype	void can_debug_freeze_disable(uint32_t can_periph);
Function descriptions	disable CAN debug freeze
Precondition	-
The called functions	dbg_periph_disable
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
-	-
Function name	can_debug_freeze_disable
Function prototype	void can_debug_freeze_disable(uint32_t can_periph);
Function descriptions	disable CAN debug freeze
Precondition	-
The called functions	dbg_periph_disable
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable CAN0 debug freeze */
```

```
can_debug_freeze_disable (CAN0);
```

can_time_trigger_mode_enable

The description of can_time_trigger_mode_enable is shown as below:

Table 3-84. Function can_time_trigger_mode_enable

Function name	can_time_trigger_mode_enable
Function prototype	void can_time_trigger_mode_enable(uint32_t can_periph);
Function descriptions	enable CAN time trigger mode

Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
-	-
Function name	can_time_trigger_mode_enable
Function prototype	void can_time_trigger_mode_enable(uint32_t can_periph);
Function descriptions	enable CAN time trigger mode
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable CAN0 time trigger mode */
```

```
can_time_trigger_mode_enable (CAN0);
```

can_time_trigger_mode_disable

The description of can_time_trigger_mode_disable is shown as below:

Table 3-85. Function can_time_trigger_mode_disable

Function name	can_time_trigger_mode_disable
Function prototype	void can_time_trigger_mode_disable(uint32_t can_periph);
Function descriptions	disable CAN time trigger mode
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Function name	can_time_trigger_mode_disable
Function prototype	void can_time_trigger_mode_disable(uint32_t can_periph);
Function descriptions	disable CAN time trigger mode
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable CAN0 time trigger mode */
```

```
can_time_trigger_mode_disable (CAN0);
```

can_message_transmit

The description of can_message_transmit is shown as below:

Table 3-86. Function can_message_transmit

Function name	can_message_transmit
Function prototype	uint8_t can_message_transmit(uint32_t can_periph, can_trasmit_message_struct* transmit_message);
Function descriptions	transmit CAN message
Precondition	can_struct_para_init()
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
transmit_message	CAN transmit message stuct, the structure members can refer to members of the structure Table 3-67. Structure can_trasmit_message_struct
Output parameter{out}	
-	-
Return value	
uint8_t	0x00-0x03
Function name	can_message_transmit
Function prototype	uint8_t can_message_transmit(uint32_t can_periph, can_trasmit_message_struct* transmit_message);
Function descriptions	transmit CAN message

Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
transmit_message	CAN transmit message struct, the structure members can refer to members of the structure Table 3-67. Structure <i>can_transmit_message</i> struct
Output parameter{out}	
-	-
Return value	
uint8_t	0x00-0x03

Example:

```
/* CAN0 transmit message and return the mailbox number*/
```

```
uint8_t transmit_mailbox = 0;
```

```
transmit_mailbox = can_message_transmit(CAN0, &transmit_message);
```

can_transmit_states

The description of can_transmit_states is shown as below:

Table 3-87. Function can_transmit_states

Function name	can_transmit_states
Function prototype	can_transmit_state_enum can_transmit_states(uint32_t can_periph, uint8_t mailbox_number);
Function descriptions	get CAN transmit state
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
mailbox_number	Mailbox number
<i>CAN_MAILBOXx</i>	CAN_MAILBOXx(x=0,1,2)
Output parameter{out}	
-	-
Return value	
can_transmit_state_enum	0..4
Function name	can_transmit_states
Function prototype	can_transmit_state_enum can_transmit_states(uint32_t can_periph, uint8_t

	mailbox_number);
Function descriptions	get CAN transmit state
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
mailbox_number	Mailbox number
<i>CAN_MAILBOXx</i>	CAN_MAILBOXx(x=0,1,2)
Output parameter{out}	
-	-
Return value	
can_transmit_state_e num	0..4

Example:

```
/* CAN0 mailbox0 transmit state */
```

```
uint8_t transmit_state = 0;
```

```
transmit_state = can_transmit_states (CAN0, CAN_MAILBOX0);
```

can_transmission_stop

The description of can_transmission_stop is shown as below:

Table 3-88. Function can_transmission_stop

Function name	can_transmission_stop
Function prototype	void can_transmission_stop(uint32_t can_periph, uint8_t mailbox_number);
Function descriptions	stop CAN transmission
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
mailbox_number	Mailbox number
<i>CAN_MAILBOXx</i>	CAN_MAILBOXx(x=0,1,2)
Output parameter{out}	
-	-
Return value	
-	-
Function name	can_transmission_stop
Function prototype	void can_transmission_stop(uint32_t can_periph, uint8_t mailbox_number);

Function descriptions	stop CAN transmission
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
mailbox_number	Mailbox number
<i>CAN_MAILBOXx</i>	CAN_MAILBOXx(x=0,1,2)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* stop CAN0 mailbox0 transmission */
```

```
can_transmission_stop (CAN0, CAN_MAILBOX0);
```

can_message_receive

The description of can_message_receive is shown as below:

Table 3-89. Function can_message_receive

Function name	can_message_receive
Function prototype	void can_message_receive(uint32_t can_periph, uint8_t fifo_number, can_receive_message_struct* receive_message);
Function descriptions	CAN receive message
Precondition	can_struct_para_init()
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
fifo_number	Fifo number
<i>CAN_FIFOx</i>	CAN_FIFOx(x=0,1)
Input parameter{in}	
receive_message	CAN message receive struct, the structure members can refer to members of the structure Table 3-68. Structure can_receive_message_struct
Output parameter{out}	
-	-
Return value	
-	-
Function name	can_message_receive

Function prototype	void can_message_receive(uint32_t can_periph, uint8_t fifo_number, can_receive_message_struct* receive_message);
Function descriptions	CAN receive message
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
fifo_number	Fifo number
<i>CAN_FIFOx</i>	CAN_FIFOx(x=0,1)
Input parameter{in}	
receive_message	CAN message receive struct, the structure members can refer to members of the structure Table 3-68. Structure can_receive_message_struct
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* CAN0 FIFO0 receive message */
```

```
can_message_receive(CAN0, CAN_FIFO0, &receive_message);
```

can_fifo_release

The description of can_fifo_release is shown as below:

Table 3-90. Function can_fifo_release

Function name	can_fifo_release
Function prototype	void can_fifo_release(uint32_t can_periph, uint8_t fifo_number);
Function descriptions	release FIFO0
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
fifo_number	Fifo number
<i>CAN_FIFOx</i>	CAN_FIFOx(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Function name	can_fifo_release
Function prototype	void can_fifo_release(uint32_t can_periph, uint8_t fifo_number);
Function descriptions	release FIFO0
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
fifo_number	Fifo number
<i>CAN_FIFOx</i>	CAN_FIFOx(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* CAN0 release FIFO0 */
```

```
can_fifo_release (CAN0, CAN_FIFO0);
```

can_receive_message_length_get

The description of can_receive_message_length_get is shown as below:

Table 3-91. Function can_receive_message_length_get

Function name	can_receive_message_length_get
Function prototype	uint8_t can_receive_message_length_get(uint32_t can_periph, uint8_t fifo_number);
Function descriptions	CAN receive message length
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
fifo_number	Fifo number
<i>CAN_FIFOx</i>	CAN_FIFOx(x=0,1)
Output parameter{out}	
-	-
Return value	
uint8_t	0..3
Function name	can_receive_message_length_get
Function prototype	uint8_t can_receive_message_length_get(uint32_t can_periph, uint8_t

	fifo_number);
Function descriptions	CAN receive message length
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
fifo_number	Fifo number
<i>CAN_FIFOx</i>	CAN_FIFOx(x=0,1)
Output parameter{out}	
-	-
Return value	
uint8_t	0..3

Example:

```
/* CAN0 FIFO0 receive message length */
```

```
uint8_t frame_number = 0;
```

```
frame_number = can_receive_message_length_get (CAN0, CAN_FIFO0);
```

can_working_mode_set

The description of can_working_mode_set is shown as below:

Table 3-92. Function can_working_mode_set

Function name	can_working_mode_set
Function prototype	ErrStatus can_working_mode_set(uint32_t can_periph, uint8_t working_mode);
Function descriptions	set CAN working mode
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
can_working_mode	Mode select
<i>CAN_MODE_INITIALIZE</i>	Initialize mode
<i>CAN_MODE_NORMAL</i>	Normal mode
<i>CAN_MODE_SLEEP</i>	Sleep mode
Output parameter{out}	
-	-
Return value	

ErrStatus	SUCCESS / ERROR
------------------	-----------------

Example:

```
/* set CAN0 working at initialize mode */
```

```
can_working_mode_set (CAN0, CAN_MODE_INITIALIZE);
```

can_wakeup

The description of can_wakeup is shown as below:

Table 3-93. Function can_wakeup

Function name	can_wakeup
Function prototype	ErrStatus can_wakeup(uint32_t can_periph);
Function descriptions	wake up CAN
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
ErrStatus	SUCCESS / ERROR
Function name	can_wakeup
Function prototype	ErrStatus can_wakeup(uint32_t can_periph);
Function descriptions	wake up CAN
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
ErrStatus	SUCCESS / ERROR

Example:

```
/* wake up CAN0 */
```

```
can_wakeup (CAN0);
```

can_error_get

The description of can_error_get is shown as below:

Table 3-94. Function can_error_get

Function name	can_error_get
Function prototype	can_error_enum can_error_get(uint32_t can_periph);
Function descriptions	get CAN error type
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
CANx(x=0,1)	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
can_error_enum	0..7
Function name	can_error_get
Function prototype	can_error_enum can_error_get(uint32_t can_periph);
Function descriptions	get CAN error type
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
CANx(x=0,1)	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
can_error_enum	0..7

Example:

```
/* get CAN0 error type */
can_error_get (CAN0);
```

can_receive_error_number_get

The description of can_receive_error_number_get is shown as below:

Table 3-95. Function can_receive_error_number_get

Function name	can_receive_error_number_get
Function prototype	uint8_t can_receive_error_number_get(uint32_t can_periph);
Function descriptions	get CAN receive error number
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
CANx(x=0,1)	CAN peripheral selection

Output parameter{out}	
-	-
Return value	
uint8_t	0..255
Function name	can_receive_error_number_get
Function prototype	uint8_t can_receive_error_number_get(uint32_t can_periph);
Function descriptions	get CAN receive error number
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
CANx(x=0,1)	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
uint8_t	0..255

Example:

```
/* get CAN0 receive error number */
can_receive_error_number_get (CAN0);
```

can_transmit_error_number_get it

The description of can_transmit_error_number_get is shown as below:

Table 3-96. Function can_transmit_error_number_get

Function name	can_transmit_error_number_get
Function prototype	uint8_t can_transmit_error_number_get(uint32_t can_periph);
Function descriptions	get CAN transmit error number
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
CANx(x=0,1)	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
uint8_t	0..255
Function name	can_transmit_error_number_get
Function prototype	uint8_t can_transmit_error_number_get(uint32_t can_periph);
Function descriptions	get CAN transmit error number
Precondition	-
The called functions	-

Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Output parameter{out}	
-	-
Return value	
uint8_t	0..255

Example:

```
/* get CAN0 transmit error number */
can_transmit_error_number_get (CAN0);
```

can_interrupt_enable

The description of can_interrupt_enable is shown as below:

Table 3-97. Function can_interrupt_enable

Function name	can_interrupt_enable
Function prototype	void can_interrupt_enable(uint32_t can_periph, uint32_t interrupt);
Function descriptions	enable CAN interrupt
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
interrupt	Interrupt type
<i>CAN_INT_TME</i>	transmit mailbox empty interrupt enable
<i>CAN_INT_RFNE0</i>	receive FIFO0 not empty interrupt enable
<i>CAN_INT_RFF0</i>	receive FIFO0 full interrupt enable
<i>CAN_INT_RFO0</i>	receive FIFO0 overfull interrupt enable
<i>CAN_INT_RFNE1</i>	receive FIFO1 not empty interrupt enable
<i>CAN_INT_RFF1</i>	receive FIFO1 full interrupt enable
<i>CAN_INT_RFO1</i>	receive FIFO1 overfull interrupt enable
<i>CAN_INT_WERR</i>	warning error interrupt enable
<i>CAN_INT_PERR</i>	passive error interrupt enable
<i>CAN_INT_BO</i>	bus-off interrupt enable
<i>CAN_INT_ERRN</i>	error number interrupt enable
<i>CAN_INT_ERR</i>	error interrupt enable
<i>CAN_INT_WU</i>	wakeup interrupt enable
<i>CAN_INT_SLPW</i>	sleep working interrupt enable
Output parameter{out}	
-	-

Return value	
-	-
Function name	can_interrupt_enable
Function prototype	void can_interrupt_enable(uint32_t can_periph, uint32_t interrupt);
Function descriptions	enable CAN interrupt
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
CANx(x=0,1)	CAN peripheral selection
Input parameter{in}	
interrupt	Interrupt type
CAN_INT_TME	transmit mailbox empty interrupt enable
CAN_INT_RFNE0	receive FIFO0 not empty interrupt enable
CAN_INT_RFF0	receive FIFO0 full interrupt enable
CAN_INT_RFO0	receive FIFO0 overfull interrupt enable
CAN_INT_RFNE1	receive FIFO1 not empty interrupt enable
CAN_INT_RFF1	receive FIFO1 full interrupt enable
CAN_INT_RFO1	receive FIFO1 overfull interrupt enable
CAN_INT_WERR	warning error interrupt enable
CAN_INT_PERR	passive error interrupt enable
CAN_INT_BO	bus-off interrupt enable
CAN_INT_ERRN	error number interrupt enable
CAN_INT_ERR	error interrupt enable
CAN_INT_WU	wakeup interrupt enable
CAN_INT_SLPW	sleep working interrupt enable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* CAN0 transmit mailbox empty interrupt enable */
```

```
can_interrupt_enable (CAN0, CAN_INT_TME);
```

can_interrupt_disable

The description of can_interrupt_disable is shown as below:

Table 3-98. Function can_interrupt_disable

Function name	can_interrupt_disable
Function prototype	void can_interrupt_disable(uint32_t can_periph, uint32_t interrupt);
Function descriptions	disable CAN interrupt

Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
interrupt	Interrupt type
<i>CAN_INT_TME</i>	transmit mailbox empty interrupt enable
<i>CAN_INT_RFNE0</i>	receive FIFO0 not empty interrupt enable
<i>CAN_INT_RFF0</i>	receive FIFO0 full interrupt enable
<i>CAN_INT_RFO0</i>	receive FIFO0 overfull interrupt enable
<i>CAN_INT_RFNE1</i>	receive FIFO1 not empty interrupt enable
<i>CAN_INT_RFF1</i>	receive FIFO1 full interrupt enable
<i>CAN_INT_RFO1</i>	receive FIFO1 overfull interrupt enable
<i>CAN_INT_WERR</i>	warning error interrupt enable
<i>CAN_INT_PERR</i>	passive error interrupt enable
<i>CAN_INT_BO</i>	bus-off interrupt enable
<i>CAN_INT_ERRN</i>	error number interrupt enable
<i>CAN_INT_ERR</i>	error interrupt enable
<i>CAN_INT_WU</i>	wakeup interrupt enable
<i>CAN_INT_SLPW</i>	sleep working interrupt enable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* CAN0 transmit mailbox empty interrupt disable */
```

```
can_interrupt_disable (CAN0, CAN_INT_TME);
```

can_flag_get

The description of can_flag_get is shown as below:

Table 3-99. Function can_flag_get

Function name	can_flag_get
Function prototype	FlagStatus can_flag_get(uint32_t can_periph, can_flag_enum flag);
Function descriptions	get CAN flag state
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection

Input parameter{in}	
flag	CAN flags
CAN_FLAG_MTE2	mailbox 2 transmit error
CAN_FLAG_MTE1	mailbox 1 transmit error
CAN_FLAG_MTE0	mailbox 0 transmit error
CAN_FLAG_MTF2	mailbox 2 transmit finished
CAN_FLAG_MTF1	mailbox 1 transmit finished
CAN_FLAG_MTF0	mailbox 0 transmit finished
CAN_FLAG_RFO0	receive FIFO0 overfull
CAN_FLAG_RFF0	receive FIFO0 full
CAN_FLAG_RFO1	receive FIFO1 overfull
CAN_FLAG_RFF1	receive FIFO1 full
CAN_FLAG_BOERR	bus-off error
CAN_FLAG_PERR	passive error
CAN_FLAG_WERR	warning error
Output parameter{out}	
-	-
Return value	
FlagStatus	SET / RESET

Example:

```
/* get CAN0 mailbox 0 transmit finished flag */
```

```
can_flag_get (CAN0, CAN_FLAG_MTF0);
```

can_flag_clear

The description of can_flag_clear is shown as below:

Table 3-100. Function can_flag_clear

Function name	can_flag_clear
Function prototype	void can_flag_clear(uint32_t can_periph, can_flag_enum flag);
Function descriptions	clear CAN flag state
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
CANx(x=0,1)	CAN peripheral selection
Input parameter{in}	
flag	CAN flags
CAN_FLAG_MTE2	mailbox 2 transmit error
CAN_FLAG_MTE1	mailbox 1 transmit error
CAN_FLAG_MTE0	mailbox 0 transmit error
CAN_FLAG_MTF2	mailbox 2 transmit finished

<i>CAN_FLAG_MTF1</i>	mailbox 1 transmit finished
<i>CAN_FLAG_MTF0</i>	mailbox 0 transmit finished
<i>CAN_FLAG_RFO0</i>	receive FIFO0 overfull
<i>CAN_FLAG_RFF0</i>	receive FIFO0 full
<i>CAN_FLAG_RFO1</i>	receive FIFO1 overfull
<i>CAN_FLAG_RFF1</i>	receive FIFO1 full
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear CAN0 mailbox 0 transmit error flag */
```

```
can_flag_clear (CAN0, CAN_FLAG_MTE0);
```

can_interrupt_flag_get

The description of can_interrupt_flag_get is shown as below:

Table 3-101. Function can_interrupt_flag_get

Function name	can_interrupt_flag_get
Function prototype	FlagStatus can_interrupt_flag_get(uint32_t can_periph, can_interrupt_flag_enum flag);
Function descriptions	get CAN interrupt flag state
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
<i>CANx(x=0,1)</i>	CAN peripheral selection
Input parameter{in}	
flag	CAN interrupt flags
<i>CAN_INT_FLAG_SLPIF</i>	status change interrupt flag of sleep working mode entering
<i>CAN_INT_FLAG_WUIF</i>	status change interrupt flag of wakeup from sleep working mode
<i>CAN_INT_FLAG_ERRIF</i>	error interrupt flag
<i>CAN_INT_FLAG_MTF2</i>	mailbox 2 transmit finished interrupt flag
<i>CAN_INT_FLAG_MTF1</i>	mailbox 1 transmit finished interrupt flag
<i>CAN_INT_FLAG_MTF0</i>	mailbox 0 transmit finished interrupt flag
<i>CAN_INT_FLAG_RFO0</i>	receive FIFO0 overfull interrupt flag
<i>CAN_INT_FLAG_RFF0</i>	receive FIFO0 full interrupt flag
<i>CAN_INT_FLAG_RFO1</i>	receive FIFO1 overfull interrupt flag
<i>CAN_INT_FLAG_RFF1</i>	receive FIFO1 full interrupt flag

Output parameter{out}	
-	-
Return value	
FlagStatus	SET / RESET

Example:

```
/* get CAN0 mailbox 0 transmit finished interrupt flag */
can_interrupt_flag_get (CAN0, CAN_INT_FLAG_MTF0);
```

can_interrupt_flag_clear

The description of can_interrupt_flag_clear is shown as below:

Table 3-102. Function can_interrupt_flag_clear

Function name	can_interrupt_flag_clear
Function prototype	void can_interrupt_flag_clear(uint32_t can_periph, can_interrupt_flag_enum flag);
Function descriptions	clear CAN interrupt flag state
Precondition	-
The called functions	-
Input parameter{in}	
can_periph	CAN peripheral
CANx(x=0,1)	CAN peripheral selection
Input parameter{in}	
flag	CAN interrupt flags
CAN_INT_FLAG_SLPIF	status change interrupt flag of sleep working mode entering
CAN_INT_FLAG_WUIF	status change interrupt flag of wakeup from sleep working mode
CAN_INT_FLAG_ERRIF	error interrupt flag
CAN_INT_FLAG_MTF2	mailbox 2 transmit finished interrupt flag
CAN_INT_FLAG_MTF1	mailbox 1 transmit finished interrupt flag
CAN_INT_FLAG_MTF0	mailbox 0 transmit finished interrupt flag
CAN_INT_FLAG_RFO0	receive FIFO0 overfull interrupt flag
CAN_INT_FLAG_RFF0	receive FIFO0 full interrupt flag
CAN_INT_FLAG_RFO1	receive FIFO1 overfull interrupt flag
CAN_INT_FLAG_RFF1	receive FIFO1 full interrupt flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear CAN0 mailbox 0 transmit finished interrupt flag */
```

```
can_interrupt_flag_clear (CAN0, CAN_INT_FLAG_MTF0);
```

3.5. CRC

A cyclic redundancy check (CRC) is an error-detecting code commonly used in digital networks and storage devices to detect accidental changes to raw data. The CRC registers are listed in chapter [3.5.1](#), the CRC firmware functions are introduced in chapter [3.5.2](#).

3.5.1. Descriptions of Peripheral registers

CRC registers are listed in the table shown as below:

Table 3-103. CRC Registers

Registers	Descriptions
CRC_DATA	CRC data register
CRC_FDATA	CRC free data register
CRC_CTL	CRC control register

3.5.2. Descriptions of Peripheral functions

CRC firmware functions are listed in the table shown as below:

Table 3-104. CRC firmware function

Function name	Function description
crc_deinit	deinit CRC calculation unit
crc_data_register_reset	reset data register to the initializaiton value of data register
crc_data_register_read	read the value of the data register
crc_free_data_register_read	read the value of the free data register
crc_free_data_register_write	write data to the free data register
crc_single_data_calculate	calculate the CRC value of a 32-bit data
crc_block_data_calculate	calculate the CRC value of an array of 32-bit values

crc_deinit

The description of crc_deinit is shown as below:

Table 3-105. Function crc_deinit

Function name	crc_deinit
Function prototype	void crc_deinit(void);
Function descriptions	deinit CRC calculation unit
Precondition	-
The called functions	-
Input parameter{in}	

-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset crc */
```

```
crc_deinit();
```

crc_data_register_reset

The description of crc_data_register_reset is shown as below:

Table 3-106. Function crc_data_register_reset

Function name	crc_data_register_reset
Function prototype	void crc_data_register_reset(void);
Function descriptions	reset data register to the initializaiton value of data register
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset crc data register */
```

```
crc_data_register_reset ();
```

crc_data_register_read

The description of crc_data_register_read is shown as below:

Table 3-107. Function crc_data_register_read

Function name	crc_data_register_read
Function prototype	uint32_t crc_data_register_read(void);
Function descriptions	read the value of the data register
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	

-	-
Return value	
uint32_t	32-bit value of the data register (0-0xFFFFFFFF)

Example:

```
/* read crc data register */

uint32_t crc_value = 0;

crc_value = crc_data_register_read();
```

crc_free_data_register_read

The description of `crc_free_data_register_read` is shown as below:

Table 3-108. Function `crc_free_data_register_read`

Function name	<code>crc_free_data_register_read</code>
Function prototype	<code>uint8_t crc_free_data_register_read(void);</code>
Function descriptions	read the value of the free data register
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint8_t	8-bit value of the free data register (0-0xFF)

Example:

```
/* read crc free data register */

uint8_t crc_value = 0;

crc_value = crc_free_data_register_read();
```

crc_free_data_register_write

The description of `crc_free_data_register_write` is shown as below:

Table 3-109. Function `crc_free_data_register_write`

Function name	<code>crc_free_data_register_write</code>
Function prototype	<code>void crc_free_data_register_write(uint8_t free_data);</code>
Function descriptions	write data to the free data register
Precondition	-
The called functions	-
Input parameter{in}	
free_data	specify 8-bit data

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* write the free data register */
crc_free_data_register_write(0x11);
```

crc_single_data_calculate

The description of crc_single_data_calculate is shown as below:

Table 3-110. Function crc_single_data_calculate

Function name	crc_single_data_calculate
Function prototype	uint32_t crc_single_data_calculate(uint32_t sdata);
Function descriptions	calculate the CRC value of a 32-bit data
Precondition	-
The called functions	-
Input parameter{in}	
sdata	specify 32-bit data
Output parameter{out}	
-	-
Return value	
uint32_t	32-bit CRC calculate value (0-0xFFFFFFFF)

Example:

```
/* CRC calculate a 32-bit data */
uint32_t val = 0, valcrc = 0;
val = (uint32_t)0xabcd1234;
rcu_periph_clock_enable(RCU_CRC);
valcrc = crc_single_data_calculate(val);
```

crc_block_data_calculate

The description of crc_block_data_calculate is shown as below:

Table 3-111. Function crc_block_data_calculate

Function name	crc_block_data_calculate
Function prototype	uint32_t crc_block_data_calculate(uint32_t array[], uint32_t size);
Function descriptions	calculate the CRC value of an array of 32-bit values
Precondition	-

The called functions	-
Input parameter{in}	
array	pointer to an array of 32 bit data words
Input parameter{in}	
size	size of the array
Output parameter{out}	
-	-
Return value	
uint32_t	32-bit CRC calculate value (0-0xFFFFFFFF)

Example:

```

/* CRC calculate a 32-bit data array */

/* CRC calculate a 32-bit data array */

#define BUFFER_SIZE    6

uint32_t valcrc = 0;

static const uint32_t data_buffer[BUFFER_SIZE] = {

0x00001111, 0x00002222, 0x00003333, 0x00004444, 0x00005555, 0x00006666};

rcu_periph_clock_enable(RCU_CRC);

valcrc = crc_block_data_calculate((uint32_t *) data_buffer, BUFFER_SIZE);

```

3.6. CTC

The CTC unit trims the frequency of the IRC48M which is based on an external accurate reference signal source. It can adjust the calibration value to provide a precise IRC48M clock automatically or manually. The CTC registers are listed in chapter [3.6.1](#), the CTC firmware functions are introduced in chapter [3.6.2](#)

3.6.1. Descriptions of Peripheral registers

CTC registers are listed in the table shown as below:

Table 3-112. CTC Registers

Registers	Descriptions
CTC_CTL0	CTC control register 0
CTC_CTL1	CTC control register 1
CTC_STAT	CTC status register
CTC_INTC	CTC Interrupt clear register

3.6.2. Descriptions of Peripheral functions

CTC registers are listed in the table shown as below:

Table 3-113. CTC firmware function

Function name	Function description
ctc_deinit	reset CTC clock trim controller
ctc_counter_enable	enable CTC trim counter
ctc_counter_disable	disable CTC trim counter
ctc_irc48m_trim_value_config	configure the IRC48M trim value
ctc_software_refsource_pulse_generate	generate software reference source sync pulse
ctc_hardware_trim_mode_config	configure hardware automatically trim mode
ctc_refsource_polarity_config	configure reference signal source polarity
ctc_refsource_signal_select	select reference signal source
ctc_refsource_prescaler_config	configure reference signal source prescaler
ctc_clock_limit_value_config	configure clock trim base limit value
ctc_counter_reload_value_config	configure CTC counter reload value
ctc_counter_capture_value_read	read CTC counter capture value when reference sync pulse occurred
ctc_counter_direction_read	read CTC trim counter direction when reference sync pulse occurred
ctc_counter_reload_value_read	read CTC counter reload value
ctc_irc48m_trim_value_read	read the IRC48M trim value
ctc_interrupt_enable	enable the CTC interrupt
ctc_interrupt_disable	disable the CTC interrupt
ctc_interrupt_flag_get	get CTC interrupt flag
ctc_interrupt_flag_clear	clear CTC interrupt flag
ctc_flag_get	get CTC flag
ctc_flag_clear	clear CTC flag

ctc_deinit

The description of ctc_deinit is shown as below:

Table 3-114. Function ctc_deinit

Function name	ctc_deinit
Function prototype	void ctc_deinit (void)
Function descriptions	Reset CTC peripheral
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Input parameter{in}	
-	-
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* reset CTC */
```

```
ctc_deinit();
```

ctc_counter_enable

The description of ctc_counter_enable is shown as below:

Table 3-115. Function ctc_counter_enable

Function name	ctc_counter_enable
Function prototype	void ctc_counter_enable (void);
Function descriptions	enable CTC counter
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable CTC trim counter*/
```

```
ctc_counter_enable ();
```

ctc_counter_disable

The description of ctc_counter_disable is shown as below:

Table 3-116. Function ctc_counter_disable

Function name	ctc_counter_disable
Function prototype	void ctc_counter_disable (void);
Function descriptions	disable CTC counter
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	

Example:

```
/* disable CTC trim counter */
```

```
ctc_counter_disable ();
```

ctc_irc48m_trim_value_config

The description of ctc_irc48m_trim_value_config is shown as below:

Table 3-117. Function ctc_irc48m_trim_value_config

Function name	ctc_irc48m_trim_value_config
Function prototype	void ctc_irc48m_trim_value_config(uint8_t trim_value);
Function descriptions	configure the IRC48M trim value
Precondition	-
The called functions	-
Input parameter{in}	
trim_value	0~63
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* IRC48M trim value configuration */
```

```
ctc_irc48m_trim_value_config (0x01);
```

ctc_software_refsource_pulse_generate

The description of ctc_software_refsource_pulse_generate is shown as below:

Table 3-118. Function ctc_software_refsource_pulse_generate

Function name	ctc_software_refsource_pulse_generate
Function prototype	void ctc_software_refsource_pulse_generate (void)
Function descriptions	generate software reference source sync pulse
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* generate reference source sync pulse */

ctc_software_refsource_pulse_generate ();
```

ctc_hardware_trim_mode_config

The description of ctc_hardware_trim_mode_config is shown as below:

Table 3-119. Function ctc_hardware_trim_mode_config

Function name	ctc_hardware_trim_mode_config
Function prototype	void ctc_hardware_trim_mode_config(uint32_t hardmode);
Function descriptions	configure hardware automatically trim mode
Precondition	-
The called functions	-
Input parameter{in}	
hardmode	hardware automatically trim mode enable or disable
CTC_HARDWARE_TRIM_MODE_ENABLE	hardware automatically trim mode enable
CTC_HARDWARE_TRIM_MODE_DISABLE	hardware automatically trim mode disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable CTC hardware trim */

ctc_hardware_trim_mode_config (CTC_HARDWARE_TRIM_MODE_ENABLE);
```

ctc_refsource_polarity_config

The description of ctc_refsource_polarity_config is shown as below:

Table 3-120. Function ctc_refsource_polarity_config

Function name	ctc_refsource_polarity_config
Function prototype	void ctc_refsource_polarity_config(uint32_t polarity);
Function descriptions	configure reference signal source polarity
Precondition	-
The called functions	-
Input parameter{in}	
polarity	reference signal source polarity
CTC_REFSOURCE_POLARITY_FALLING	reference signal source polarity is falling edge

<i>CTC_REFSOURCE_POLARITY_RISING</i>	reference signal source polarity is rising edge
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set reference source polarity */
```

```
ctc_refsource_polarity_config (CTC_REFSOURCE_POLARITY_RISING);
```

ctc_refsource_signal_select

The description of ctc_refsource_signal_select is shown as below:

Table 3-121. Function ctc_refsource_signal_select

Function name	ctc_refsource_signal_select
Function prototype	void ctc_refsource_signal_select(uint32_t refs);
Function descriptions	select reference signal source
Precondition	-
The called functions	-
Input parameter{in}	
refs	reference signal source
<i>CTC_REFSOURCE_GPIO</i>	GPIO is selected
<i>CTC_REFSOURCE_LXTAL</i>	LXTAL is selected
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reference signal selection */
```

```
ctc_refsource_signal_select (CTC_REFSOURCE_LXTAL);
```

ctc_refsource_prescaler_config

The description of ctc_refsource_prescaler_config is shown as below:

Table 3-122. Function ctc_refsource_prescaler_config

Function name	ctc_refsource_prescaler_config
Function prototype	void ctc_refsource_prescaler_config(uint32_t prescaler);
Function descriptions	configure reference signal source prescaler

Precondition	-
The called functions	-
Input parameter{in}	
prescaler	Prescaler factor
<i>CTC_REFSOURCE_P</i> <i>SC_OFF</i>	reference signal not divided
<i>CTC_REFSOURCE_P</i> <i>SC_DIV2</i>	reference signal divided by 2
<i>CTC_REFSOURCE_P</i> <i>SC_DIV4</i>	reference signal divided by 4
<i>CTC_REFSOURCE_P</i> <i>SC_DIV8</i>	reference signal divided by 8
<i>CTC_REFSOURCE_P</i> <i>SC_DIV16</i>	reference signal divided by 16
<i>CTC_REFSOURCE_P</i> <i>SC_DIV32</i>	reference signal divided by 32
<i>CTC_REFSOURCE_P</i> <i>SC_DIV64</i>	reference signal divided by 64
<i>CTC_REFSOURCE_P</i> <i>SC_DIV128</i>	reference signal divided by 128
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure reference signal source prescaler */
```

```
ctc_refsource_prescaler_config(CTC_REFSOURCE_PSC_DIV2);
```

ctc_clock_limit_value_config

The description of ctc_clock_limit_value_config is shown as below:

Table 3-123. Function ctc_clock_limit_value_config

Function name	ctc_clock_limit_value_config
Function prototype	void ctc_clock_limit_value_config(uint8_t limit_value);
Function descriptions	configure clock trim base limit value
Precondition	-
The called functions	-
Input parameter{in}	
limit_value	0x00 - 0xFF
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* configure clock trim base limit value */
```

```
ctc_clock_limit_value_config (0x1F);
```

ctc_counter_reload_value_config

The description of ctc_counter_reload_value_config is shown as below:

Table 3-124. Function ctc_counter_reload_value_config

Function name	ctc_counter_reload_value_config
Function prototype	void ctc_counter_reload_value_config(uint16_t reload_value);
Function descriptions	configure CTC counter reload value
Precondition	-
The called functions	-
Input parameter{in}	
reload_value	0x0000 - 0xFFFF
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure CTC counter reload value */
```

```
ctc_counter_reload_value_config (0x00FF);
```

ctc_counter_capture_value_read

The description of ctc_counter_capture_value_read is shown as below:

Table 3-125. Function ctc_counter_capture_value_read

Function name	ctc_counter_capture_value_read
Function prototype	uint16_t ctc_counter_capture_value_read(void);
Function descriptions	read CTC counter capture value
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint16_t	读取计数器捕获值(0x0000 - 0xFFFF)

Example:

```
/* read CTC counter capture value */

uint16_t ctc_value = 0;

ctc_value = ctc_counter_capture_value_read ();
```

ctc_counter_direction_read

The description of ctc_counter_direction_read is shown as below:

Table 3-126. Function ctc_counter_direction_read

Function name	ctc_counter_direction_read
Function prototype	FlagStatus ctc_counter_direction_read(void);
Function descriptions	read CTC trim counter direction
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
FlagStatus	SET(向下计数) / RESET(向上计数)

Example:

```
/* read ctc counter direction */

FlagStatus ctc_direction = SET;

ctc_direction = ctc_counter_direction_read ();
```

ctc_counter_reload_value_read

The description of ctc_counter_reload_value_read is shown as below:

Table 3-127. Function ctc_counter_reload_value_read

Function name	ctc_counter_reload_value_read
Function prototype	uint16_t ctc_counter_reload_value_read(void);
Function descriptions	read CTC counter reload value
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	

uint16_t	读取计数器重载值的16位数据 (0x0000 - 0xFFFF)
-----------------	----------------------------------

Example:

```
/* read CTC counter reload value */

uint16_t ctc_reload_value = 0;

ctc_reload_value = ctc_counter_reload_value_read ();
```

ctc_irc48m_trim_value_read

The description of ctc_irc48m_trim_value_read is shown as below:

Table 3-128. Function ctc_irc48m_trim_value_read

Function name	ctc_irc48m_trim_value_read
Function prototype	uint8_t ctc_irc48m_trim_value_read(void);
Function descriptions	read the IRC48M trim value
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint8_t	6位IRC48M校准值 (0-63)

Example:

```
/* read the IRC48M trim value */

uint8_t ctc_trim_value = 0;

ctc_trim_value = ctc_irc48m_trim_value_read ();
```

ctc_interrupt_enable

The description of ctc_interrupt_enable is shown as below:

Table 3-129. Function ctc_interrupt_enable

Function name	ctc_interrupt_enable
Function prototype	void ctc_interrupt_enable(uint32_t interrupt);
Function descriptions	enable the CTC interrupt
Precondition	-
The called functions	-
Input parameter{in}	
interrupt	CTC interrupt
<i>CTC_INT_CKOK</i>	clock trim OK interrupt
<i>CTC_INT_CKWARN</i>	clock trim warning interrupt

<i>CTC_INT_ERR</i>	error interrupt
<i>CTC_INT_ERE</i>	expect reference interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable CTC clock trim OK interrupt */
ctc_interrupt_enable (CTC_INT_CKOK);
```

ctc_interrupt_disable

The description of ctc_interrupt_disable is shown as below:

Table 3-130. Function ctc_interrupt_disable

Function name	ctc_interrupt_disable
Function prototype	void ctc_interrupt_disable(uint32_t interrupt);
Function descriptions	disable the CTC interrupt
Precondition	-
The called functions	-
Input parameter{in}	
interrupt	CTC interrupt
<i>CTC_INT_CKOK</i>	clock trim OK interrupt
<i>CTC_INT_CKWARN</i>	clock trim warning interrupt
<i>CTC_INT_ERR</i>	error interrupt
<i>CTC_INT_ERE</i>	expect reference interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable CTC clock trim OK interrupt */
ctc_interrupt_disable (CTC_INT_CKOK);
```

ctc_interrupt_flag_get

The description of ctc_interrupt_flag_get is shown as below:

Table 3-131. Function ctc_interrupt_flag_get

Function name	ctc_interrupt_flag_get
Function prototype	FlagStatus ctc_interrupt_flag_get(uint32_t interrupt);
Function descriptions	get CTC interrupt flag

Precondition	-
The called functions	-
Input parameter{in}	
interrupt	CTC interrupt flag
<i>CTC_INT_FLAG_CKOK</i>	clock trim OK interrupt
<i>CTC_INT_FLAG_CKWARN</i>	clock trim warning interrupt
<i>CTC_INT_FLAG_ERR</i>	error interrupt
<i>CTC_INT_FLAG_EREFP</i>	expect reference interrupt
<i>CTC_INT_FLAG_CKEERR</i>	clock trim error bit interrupt
<i>CTC_INT_FLAG_REFMISS</i>	reference sync pulse miss interrupt
<i>CTC_INT_FLAG_TRIMERR</i>	trim value error interrupt
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get CTC interrupt flag status */
```

```
FlagStatus state = ctc_interrupt_flag_get (CTC_INT_FLAG_CKOK);
```

ctc_interrupt_flag_clear

The description of ctc_interrupt_flag_clear is shown as below:

Table 3-132. Function ctc_interrupt_flag_clear

Function name	ctc_interrupt_flag_clear
Function prototype	void ctc_interrupt_flag_clear(uint32_t interrupt);
Function descriptions	clear CTC interrupt flag
Precondition	-
The called functions	-
Input parameter{in}	
interrupt	CTC interrupt flag
<i>CTC_INT_FLAG_CKOK</i>	clock trim OK interrupt
<i>CTC_INT_FLAG_CKWARN</i>	clock trim warning interrupt
<i>CTC_INT_FLAG_ERR</i>	error interrupt
<i>CTC_INT_FLAG_EREFP</i>	expect reference interrupt

<i>CTC_INT_FLAG_CKE</i> <i>RR</i>	clock trim error bit interrupt
<i>CTC_INT_FLAG_REF</i> <i>MISS</i>	reference sync pulse miss interrupt
<i>CTC_INT_FLAG_TRIM</i> <i>ERR</i>	trim value error interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/*clear CTC interrupt flag status */
```

```
ctc_interrupt_flag_clear (CTC_INT_FLAG_CKOK);
```

ctc_flag_get

The description of ctc_flag_get is shown as below:

Table 3-133. Function ctc_flag_get

Function name	ctc_flag_get
Function prototype	FlagStatus ctc_flag_get(uint32_t flag);
Function descriptions	get CTC status flag
Precondition	-
The called functions	-
Input parameter{in}	
flag	CTC status flag
<i>CTC_FLAG_CKOK</i>	clock trim OK interrupt flag
<i>CTC_FLAG_CKWARN</i>	clock trim warning interrupt flag
<i>CTC_FLAG_ERR</i>	error interrupt flag
<i>CTC_FLAG_EREFS</i>	expect reference interrupt flag
<i>CTC_FLAG_CKERR</i>	clock trim error bit
<i>CTC_FLAG_REFMISS</i>	reference sync pulse miss flag
<i>CTC_FLAG_TRIMERR</i>	trim value error flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get CTC flag status */
```

```
FlagStatus state = ctc_flag_get (CTC_FLAG_CKOK);
```

ctc_flag_clear

The description of ctc_flag_clear is shown as below:

Table 3-134. Function ctc_flag_clear

Function name	ctc_flag_clear
Function prototype	void ctc_flag_clear (uint32_t flag);
Function descriptions	clear CTC status flag
Precondition	-
The called functions	-
Input parameter{in}	
flag	CTC status flag
CTC_FLAG_CKOK	clock trim OK interrupt flag
CTC_FLAG_CKWARN	clock trim warning interrupt flag
CTC_FLAG_ERR	error interrupt flag
CTC_FLAG_EREf	expect reference interrupt flag
CTC_FLAG_CKERR	clock trim error bit
CTC_FLAG_REFMISs	reference sync pulse miss flag
CTC_FLAG_TRIMERR	trim value error flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear CTC flag status */
```

```
ctc_flag_clear (CTC_FLAG_CKOK);
```

3.7. DAC

The Digital-to-analog converter converts 12-bit digital data to a voltage on the external pins. The DAC registers are listed in chapter [3.7.1](#), the DAC firmware functions are introduced in chapter [3.7.2](#).

3.7.1. Descriptions of Peripheral registers

DAC registers are listed in the table shown as below:

Table 3-135. DAC Registers

Registers	Descriptions
DAC_CTL	DAC control register
DAC_SWT	DAC software trigger register
DAC0_R12DH	DAC0 12-bit right-aligned data holding register

Registers	Descriptions
DAC0_L12DH	DAC0 12-bit left-aligned data holding register
DAC0_R8DH	DAC0 8-bit right-aligned data holding register
DAC1_R12DH	DAC1 12-bit right-aligned data holding register
DAC1_L12DH	DAC1 12-bit left-aligned data holding register
DAC1_R8DH	DAC1 8-bit right-aligned data holding register
DACC_R12DH	DAC concurrent mode 12-bit right-aligned data holding register
DACC_L12DH	DAC concurrent mode 12-bit left-aligned data holding register
DACC_R8DH	DAC concurrent mode 8-bit right-aligned data holding register
DAC0_DO	DAC0 data output register
DAC1_DO	DAC1 data output register

3.7.2. Descriptions of Peripheral functions

DAC registers are listed in the table shown as below:

Table 3-136. DAC firmware function

Function name	Function description
dac_deinit	deinitialize DAC
dac_enable	enable DAC
dac_disable	disable DAC
dac_dma_enable	dac_dma_enable
dac_dma_disable	dac_dma_disable
dac_output_buffer_enable	enable DAC output buffer
dac_output_buffer_disable	disable DAC output buffer
dac_trigger_enable	enable DAC trigger
dac_trigger_disable	disable DAC trigger
dac_software_trigger_enable	enable DAC software trigger
dac_software_trigger_disable	disable DAC software trigger
dac_trigger_source_config	configure DAC trigger source
dac_wave_mode_config	configure DAC wave mode
dac_wave_bit_width_config	configure DAC wave bit width
dac_lfsr_noise_config	configure DAC LFSR noise mode
dac_triangle_noise_config	configure DAC triangle noise mode
dac_output_value_get	get the last data output value
dac_data_set	set DAC data holding register value
dac_concurrent_data_set	set DAC concurrent mode data holding register value
dac_concurrent_enable	enable DAC concurrent mode
dac_concurrent_disable	disable DAC concurrent mode
dac_concurrent_software_trigger_enable	enable DAC concurrent software trigger
dac_concurrent_software_trigger_disable	disable DAC concurrent software trigger

Function name	Function description
<code>dac_concurrent_output_buffer_enable</code>	enable DAC concurrent buffer function
<code>dac_concurrent_output_buffer_disable</code>	disable DAC concurrent buffer function

dac_deinit

The description of `dac_deinit` is shown as below:

Table 3-137. Function `dac_deinit`

Function name	<code>dac_deinit</code>
Function prototype	<code>void dac_deinit(void)</code>
Function descriptions	Reset DAC peripheral
Precondition	-
The called functions	<code>rcu_periph_reset_enable</code> / <code>rcu_periph_reset_disable</code>
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* deinitialize DAC */
dac_deinit();
```

dac_enable

The description of `dac_enable` is shown as below:

Table 3-138. Function `dac_enable`

Function name	<code>dac_enable</code>
Function prototype	<code>void dac_enable(uint32_t dac_periph)</code>
Function descriptions	enable DAC
Precondition	-
The called functions	-
Input parameter{in}	
<code>dac_periph</code>	peripheral
<code>DACx</code>	peripheral selection(x =0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DAC */
```

```
dac_enable(DAC0);
```

dac_disable

The description of `dac_disable` is shown as below:

Table 3-139. Function `dac_disable`

Function name	<code>dac_disable</code>
Function prototype	<code>void dac_disable(uint32_t dac_periph)</code>
Function descriptions	disable DAC
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DAC */
```

```
dac_disable(DAC0);
```

dac_dma_enable

The description of `dac_dma_enable` is shown as below:

Table 3-140. Function `dac_dma_enable`

Function name	<code>dac_dma_enable</code>
Function prototype	<code>void dac_dma_enable(uint32_t dac_periph)</code>
Function descriptions	enable DAC DMA function
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DAC DMA function */
```

```
dac_dma_enable(DAC0);
```

dac_dma_disable

The description of `dac_dma_disable` is shown as below:

Table 3-141. Function `dac_dma_disable`

Function name	<code>dac_dma_disable</code>
Function prototype	<code>void dac_dma_disable(uint32_t dac_periph)</code>
Function descriptions	disable DAC DMA function
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DAC DMA function */
```

```
dac_dma_disable(DAC0);
```

dac_output_buffer_enable

The description of `dac_output_buffer_enable` is shown as below:

Table 3-142. Function `dac_output_buffer_enable`

Function name	<code>dac_output_buffer_enable</code>
Function prototype	<code>void dac_output_buffer_enable(uint32_t dac_periph)</code>
Function descriptions	enable DAC output buffer
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:


```
/* enable DAC output buffer */
```

```
dac_output_buffer_enable(DAC0);
```

dac_output_buffer_disable

The description of `dac_output_buffer_disable` is shown as below:

Table 3-143. Function `dac_output_buffer_disable`

Function name	<code>dac_output_buffer_disable</code>
Function prototype	<code>void dac_output_buffer_disable(uint32_t dac_periph)</code>
Function descriptions	disable DAC output buffer
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DAC output buffer */
```

```
dac_output_buffer_disable(DAC0);
```

dac_trigger_enable

The description of `dac_trigger_enable` is shown as below:

Table 3-144. Function `dac_trigger_enable`

Function name	<code>dac_trigger_enable</code>
Function prototype	<code>void dac_trigger_enable(uint32_t dac_periph)</code>
Function descriptions	enable DAC trigger
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DAC trigger */
```

```
dac_trigger_enable(DAC0);
```

dac_trigger_disable

The description of `dac_trigger_disable` is shown as below:

Table 3-145. Function `dac_trigger_disable`

Function name	<code>dac_trigger_disable</code>
Function prototype	<code>void dac_trigger_disable(uint32_t dac_periph)</code>
Function descriptions	disable DAC trigger
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DAC trigger */
```

```
dac_trigger_disable(DAC0);
```

dac_software_trigger_enable

The description of `dac_software_trigger_enable` is shown as below:

Table 3-146. Function `dac_software_trigger_enable`

Function name	<code>dac_software_trigger_enable</code>
Function prototype	<code>void dac_software_trigger_enable(uint32_t dac_periph)</code>
Function descriptions	enable DAC software trigger
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DAC software trigger */
```

```
dac_software_trigger_enable(DAC0);
```

dac_software_trigger_disable

The description of `dac_software_trigger_disable` is shown as below:

Table 3-147. Function `dac_software_trigger_disable`

Function name	<code>dac_software_trigger_disable</code>
Function prototype	<code>void dac_software_trigger_disable(uint32_t dac_periph)</code>
Function descriptions	disable DAC software trigger
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DAC software trigger */
```

```
dac_software_trigger_disable(DAC0);
```

dac_trigger_source_config

The description of `dac_trigger_source_config` is shown as below:

Table 3-148. Function `dac_trigger_source_config`

Function name	<code>dac_trigger_source_config</code>
Function prototype	<code>void dac_trigger_source_config(uint32_t dac_periph,uint32_t triggersource)</code>
Function descriptions	set DAC trigger source
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Input parameter{in}	
triggersource	external triggers of DAC
<i>DAC_TRIGGER_T1_TRGO</i>	TIMER1 TRGO
<i>DAC_TRIGGER_T2_TRGO</i>	TIMER2 TRGO

<i>DAC_TRIGGER_T3_TRGO</i>	TIMER3 TRGO
<i>DAC_TRIGGER_T4_TRGO</i>	TIMER4 TRGO
<i>DAC_TRIGGER_T5_TRGO</i>	TIMER5 TRGO
<i>DAC_TRIGGER_T6_TRGO</i>	TIMER6 TRGO
<i>DAC_TRIGGER_T7_TRGO</i>	TIMER7 TRGO
<i>DAC_TRIGGER_EXTI_9</i>	EXTI interrupt line9 event
<i>DAC_TRIGGER_SOFTWARE</i>	software trigger
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set DAC trigger source*/
```

```
dac_trigger_source_config(DAC0,DAC_TRIGGER_T1_TRGO);
```

dac_wave_mode_config

The description of `dac_wave_mode_config` is shown as below:

Table 3-149. Function `dac_wave_mode_config`

Function name	<code>dac_wave_mode_config</code>
Function prototype	<code>void dac_wave_mode_config(uint32_t dac_periph, uint32_t wave_mode)</code>
Function descriptions	configure DAC wave mode
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Input parameter{in}	
wave_mode	wave_mode
<i>DAC_WAVE_DISABLE</i>	wave disable
<i>DAC_WAVE_MODE_LFSR</i>	LFSR noise mode
<i>DAC_WAVE_MODE_TRIANGLE</i>	triangle noise mode

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure DAC wave mode */
```

```
dac_wave_mode_config(DAC0, DAC_WAVE_DISABLE);
```

dac_wave_bit_width_config

The description of dac_wave_bit_width_config is shown as below:

Table 3-150. Function dac_wave_bit_width_config

Function name	dac_wave_bit_width_config
Function prototype	void dac_wave_bit_width_config(uint32_t dac_periph, uint32_t bit_width)
Function descriptions	configure DAC wave bit width
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Input parameter{in}	
bit_width	noise wave bit width
<i>DAC_WAVE_BIT_WID</i> <i>TH_x</i>	x = 1..12
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure DAC wave bit width */
```

```
dac_wave_bit_width_config(DAC0,DAC_WAVE_BIT_WIDTH_1);
```

dac_lfsr_noise_config

The description of dac_lfsr_noise_config is shown as below:

Table 3-151. Function dac_lfsr_noise_config

Function name	dac_lfsr_noise_config
Function prototype	void dac_lfsr_noise_config(uint32_t dac_periph, uint32_t unmask_bits)
Function descriptions	configure DAC LFSR noise mode
Precondition	-

The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Input parameter{in}	
unmask_bits	noise wave unmask bit width
<i>DAC_LFSR_BIT0</i>	unmask the LFSR bit0
<i>DAC_LFSR_BITSx_0</i>	unmask the LFSR bits[x:0]
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure DAC LFSR noise mode */
dac_lfsr_noise_config(DAC0,DAC_LFSR_BIT0);
```

dac_triangle_noise_config

The description of dac_triangle_noise_config is shown as below:

Table 3-152. Function dac_triangle_noise_config

Function name	dac_triangle_noise_config
Function prototype	void dac_triangle_noise_config(uint32_t dac_periph, uint32_t amplitude)
Function descriptions	configure DAC triangle noise mode
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Input parameter{in}	
amplitude	the amplitude of triangle noise
<i>DAC_TRIANGLE_AMPLITUDE_x</i>	$x = 2^n - 1 (n = 1..12)$
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure DAC triangle noise mode */
dac_triangle_noise_config(DAC0,DAC_TRIANGLE_AMPLITUDE_1);
```

dac_output_value_get

The description of dac_output_value_get is shown as below:

Table 3-153. Function dac_output_value_get

Function name	dac_output_value_get
Function prototype	uint16_t dac_output_value_get(uint32_t dac_periph)
Function descriptions	get DAC output value
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
DACx	peripheral selection(x =0,1)
Output parameter{out}	
-	-
Return value	
uint16_t	DAC output data (0x0000 – 0x07FF)-

Example:

```
/* get DAC output value */
data = dac_output_value_get(DAC0);
```

dac_concurrent_enable

The description of dac_concurrent_enable is shown as below:

Table 3-154. Function dac_concurrent_enable

Function name	dac_concurrent_enable
Function prototype	void dac_concurrent_enable (void);
Function descriptions	enable DAC concurrent mode
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DAC concurrent mode */
dac_concurrent_enable();
```

dac_concurrent_disable

The description of dac_concurrent_disable is shown as below:

Table 3-155. Function dac_concurrent_disable

Function name	dac_concurrent_disable
Function prototype	void dac_concurrent_disable (void);
Function descriptions	disable DAC concurrent mode
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DAC concurrent mode */
dac_concurrent_disable();
```

dac_concurrent_software_trigger_enable

The description of dac_concurrent_software_trigger_enable is shown as below:

Table 3-156. Function dac_concurrent_software_trigger_enable

Function name	dac_concurrent_software_trigger_enable
Function prototype	void dac_concurrent_software_trigger_enable (void);
Function descriptions	enable DAC concurrent software trigger function
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DAC concurrent software trigger function */
dac_concurrent_software_trigger_enable();
```


dac_concurrent_software_trigger_disable

The description of dac_concurrent_software_trigger_disable is shown as below:

Table 3-157. Function dac_concurrent_software_trigger_disable

Function name	dac_concurrent_software_trigger_disable
Function prototype	void dac_concurrent_software_trigger_disable (void);
Function descriptions	disable DAC concurrent software trigger function
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DAC concurrent software trigger function */
dac_concurrent_software_trigger_disable();
```

dac_concurrent_output_buffer_enable

The description of dac_concurrent_output_buffer_enable is shown as below:

Table 3-158. Function dac_concurrent_output_buffer_enable

Function name	dac_concurrent_output_buffer_enable
Function prototype	void dac_concurrent_output_buffer_enable(void);
Function descriptions	enable DAC concurrent buffer function
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DAC concurrent buffer function */
dac_concurrent_output_buffer_enable();
```

dac_concurrent_output_buffer_disable

The description of `dac_concurrent_output_buffer_disable` is shown as below:

Table 3-159. Function `dac_concurrent_output_buffer_disable`

Function name	<code>dac_concurrent_output_buffer_disable</code>
Function prototype	<code>void dac_concurrent_output_buffer_disable(void);</code>
Function descriptions	disable DAC concurrent buffer function
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DAC concurrent buffer function */
```

```
dac_concurrent_output_buffer_disable();
```

dac_data_set

The description of `dac_data_set` is shown as below:

Table 3-160. Function `dac_data_set`

Function name	<code>dac_data_set</code>
Function prototype	<code>void dac_data_set(uint32_t dac_periph, uint32_t dac_align, uint16_t data)</code>
Function descriptions	set the DAC specified data holding register value
Precondition	-
The called functions	-
Input parameter{in}	
dac_periph	peripheral
<i>DACx</i>	peripheral selection(x =0,1)
Input parameter{in}	
dac_align	DAC align mode
<i>DAC_ALIGN_8B_R</i>	data right 8b alignment
<i>DAC_ALIGN_12B_R</i>	data right 12b alignment
<i>DAC_ALIGN_12B_L</i>	data left 12b alignment
Input parameter{in}	
data	The data sending to holding register
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* set the DAC specified data holding register value */
```

```
dac_data_set(DAC0,DAC_ALIGN_8B_R,0xff);
```

dac_concurrent_data_set

The description of `dac_concurrent_data_set` is shown as below:

Table 3-161. Function `dac_concurrent_data_set`

Function name	<code>dac_concurrent_data_set</code>
Function prototype	<code>void dac_concurrent_data_set(uint32_t dac_align, uint16_t data0, uint16_t data1)</code>
Function descriptions	set DAC concurrent mode data holding register value
Precondition	-
The called functions	-
Input parameter{in}	
dac_align	DAC align mode
<i>DAC_ALIGN_8B_R</i>	data right 8b alignment
<i>DAC_ALIGN_12B_R</i>	data right 12b alignment
<i>DAC_ALIGN_12B_L</i>	data left 12b alignment
Input parameter{in}	
data0	The data sending to holding register of DAC0
Input parameter{in}	
data1	The data sending to holding register of DAC1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set DAC concurrent mode data holding register value */
```

```
dac_concurrent_data_set(DAC_ALIGN_8B_R,0xff,0xff);
```

3.8. DBG

The DBG hold unit helps debugger to debug power saving mode. The DBG registers are listed in chapter [3.8.1](#). the DBG firmware functions are introduced in chapter [3.8.2](#).

3.8.1. Descriptions of Peripheral registers

DBG registers are listed in the table shown as below:

Table 3-162. DBG Registers

Registers	Descriptions
DBG_ID	DBG ID code register
DBG_CTL	DBG control register

3.8.2. Descriptions of Peripheral functions

DBG firmware functions are listed in the table shown as below:

Table 3-163. DBG firmware function

Function name	Function description
dbg_id_get	read DBG_ID code register
dbg_low_power_enable	enable low power behavior when the MCU is in debug mode
dbg_low_power_disable	disable low power behavior when the MCU is in debug mode
dbg_periph_enable	enable peripheral behavior when the MCU is in debug mode
dbg_periph_disable	disable peripheral behavior when the MCU is in debug mode
dbg_trace_pin_enable	enable trace pin assignment
dbg_trace_pin_disable	disable trace pin assignment

Enum dbg_periph_enum

Table 3-164. Enum dbg_periph_enum

Member name	Function description
DBG_FWDGT_HOLD	debug FWDGT kept when core is halted
DBG_WWDGT_HOLD	debug WWDGT kept when core is halted
DBG_TIMER0_HOLD	hold TIMER0 counter when core is halted
DBG_TIMER1_HOLD	hold TIMER1 counter when core is halted
DBG_TIMER2_HOLD	hold TIMER2 counter when core is halted
DBG_TIMER3_HOLD	hold TIMER3 counter when core is halted
DBG_CAN0_HOLD	debug CAN0 kept when core is halted
DBG_I2C0_HOLD	hold I2C0 smbus when core is halted
DBG_I2C1_HOLD	hold I2C1 smbus when core is halted
DBG_TIMER4_HOLD	hold TIMER4 counter when core is halted
DBG_TIMER5_HOLD	hold TIMER5 counter when core is halted
DBG_TIMER6_HOLD	hold TIMER6 counter when core is halted
DBG_TIMER7_HOLD	hold TIMER7 counter when core is halted
DBG_CAN1_HOLD	debug CAN1 kept when core is halted
DBG_TIMER11_HOLD	hold TIMER11 counter when core is halted
DBG_TIMER12_HOLD	hold TIMER12 counter when core is halted
DBG_TIMER13_HOLD	hold TIMER13 counter when core is halted

DBG_TIMER8_HOLD	hold TIMER8 counter when core is halted
DBG_TIMER9_HOLD	hold TIMER9 counter when core is halted
DBG_TIMER10_HOLD	hold TIMER10 counter when core is halted

dbg_id_get

The description of dbg_id_get is shown as below:

Table 3-165. Function dbg_id_get

Function name	dbg_id_get
Function prototype	uint32_t dbg_id_get(void);
Function descriptions	Read DBG_ID code register
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint32_t	DBG_ID code (0-0xFFFFFFFF)

Example:

```
/* read DBG_ID code register */
```

```
uint32_t id_value = 0;
```

```
id_value = dbg_id_get();
```

dbg_low_power_enable

The description of dbg_low_power_enable is shown as below:

Table 3-166. Function dbg_low_power_enable

Function name	dbg_low_power_enable
Function prototype	void dbg_low_power_enable(uint32_t dbg_low_power);
Function descriptions	Enable low power behavior when the mcu is in debug mode
Precondition	-
The called functions	-
Input parameter{in}	
dbg_low_power	low power mode
DBG_LOW_POWER_SLEEP	keep debugger connection during sleep mode
DBG_LOW_POWER_DEEPSLEEP	keep debugger connection during deepsleep mode
DBG_LOW_POWER_STANDBY	keep debugger connection during standby mode

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable low power behavior when the mcu is in debug mode */
dbg_low_power_enable(DBG_LOW_POWER_SLEEP);
```

dbg_low_power_disable

The description of dbg_low_power_disable is shown as below:

Table 3-167. Function dbg_low_power_disable

Function name	dbg_low_power_disable
Function prototype	void dbg_low_power_disable(uint32_t dbg_low_power);
Function descriptions	Disable low power behavior when the mcu is in debug mode
Precondition	-
The called functions	-
Input parameter{in}	
dbg_low_power	low power mode
DBG_LOW_POWER_SLEEP	keep debugger connection during sleep mode
DBG_LOW_POWER_DEEPSLEEP	keep debugger connection during deepsleep mode
DBG_LOW_POWER_STANDBY	keep debugger connection during standby mode
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable low power behavior when the mcu is in debug mode */
dbg_low_power_disable(DBG_LOW_POWER_SLEEP);
```

dbg_periph_enable

The description of dbg_periph_enable is shown as below:

Table 3-168. Function dbg_periph_enable

Function name	dbg_periph_enable
Function prototype	void dbg_periph_enable(dbg_periph_enum dbg_periph);
Function descriptions	Enable peripheral behavior when the mcu is in debug mode

Precondition	-
The called functions	-
Input parameter{in}	
dbg_periph	Peripheral refer to Table 3-164. Enum dbg_periph_enum
<i>DBG_FWDGT_HOLD</i>	debug FWDGT kept when core is halted
<i>DBG_WWDGT_HOLD</i>	debug WWDGT kept when core is halted
<i>DBG_CANx_HOLD</i>	x=0,1, hold CANx counter when core is halted
<i>DBG_I2Cx_HOLD</i>	x=0,1, hold I2Cx smbus when core is halted
<i>DBG_TIMERx_HOLD</i>	x=0,1,2,3,4,5,6,7,8,9,10,11,12,13, hold TIMERx counter when core is halted
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable peripheral behavior when the mcu is in debug mode */
```

```
dbg_periph_enable(DBG_TIMER0_HOLD);
```

dbg_periph_disable

The description of dbg_periph_disable is shown as below:

Table 3-169. Function dbg_periph_disable

Function name	dbg_periph_disable
Function prototype	void dbg_periph_disable(dbg_periph_enum dbg_periph);
Function descriptions	Disable peripheral behavior when the mcu is in debug mode
Precondition	-
The called functions	-
Input parameter{in}	
dbg_periph	peripheral refer to Table 3-164. Enum dbg_periph_enum
<i>DBG_FWDGT_HOLD</i>	debug FWDGT kept when core is halted
<i>DBG_WWDGT_HOLD</i>	debug WWDGT kept when core is halted
<i>DBG_CANx_HOLD</i>	x=0,1, hold CANx counter when core is halted
<i>DBG_I2Cx_HOLD</i>	x=0,1, hold I2Cx smbus when core is halted
<i>DBG_TIMERx_HOLD</i>	x=0,1,2,3,4,5,6,7,8,9,10,11,12,13, hold TIMERx counter when core is halted
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable peripheral behavior when the mcu is in debug mode */
```

```
dbg_periph_disable(DBG_TIMER0_HOLD);
```

dbg_trace_pin_enable

The description of dbg_trace_pin_enable is shown as below:

Table 3-170. Function dbg_trace_pin_enable

Function name	dbg_trace_pin_enable
Function prototype	void dbg_trace_pin_enable(void);
Function descriptions	Enable trace pin assignment
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable trace pin assignment */
dbg_trace_pin_enable();
```

dbg_trace_pin_disable

The description of dbg_trace_pin_disable is shown as below:

Table 3-171. Function dbg_trace_pin_disable

Function name	dbg_trace_pin_disable
Function prototype	void dbg_trace_pin_disable(void);
Function descriptions	Disable trace pin assignment
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable trace pin assignment */
dbg_trace_pin_disable();
```


3.9. DMA

The direct memory access (DMA) controller provides a hardware method of transferring data between peripherals and/or memory without intervention from the CPU, thereby freeing up bandwidth for other system functions. The DMA registers are listed in chapter [3.9.1](#), the DMA firmware functions are introduced in chapter [3.9.2](#).

3.9.1. Descriptions of Peripheral registers

DMA registers are listed in the table shown as below:

Table 3-172. DMA Registers

Registers	Descriptions
DMA_INTF	Interrupt flag register
DMA_INTC	Interrupt flag clear register
DMA_CHxCTL (x=0..6)	Channel x control register
DMA_CHxCNT (x=0..6)	Channel x counter register
DMA_CHxPADDR (x=0..6)	Channel x peripheral base address register
DMA_CHxMADDR (x=0..6)	Channel x memory base address register

3.9.2. Descriptions of Peripheral functions

DMA firmware functions are listed in the table shown as below:

Table 3-173. DMA firmware function

Function name	Function description
<code>dma_deinit</code>	deinitialize DMA a channel registers
<code>dma_struct_para_init</code>	initialize the parameters of DMA struct with the default values
<code>dma_init</code>	initialize DMA channel
<code>dma_circulation_enable</code>	enable DMA circulation mode
<code>dma_circulation_disable</code>	disable DMA circulation mode
<code>dma_memory_to_memory_enable</code>	enable memory to memory mode
<code>dma_memory_to_memory_disable</code>	disable memory to memory mode
<code>dma_channel_enable</code>	enable DMA channel
<code>dma_channel_disable</code>	disable DMA channel
<code>dma_periph_address_config</code>	set DMA peripheral base address
<code>dma_memory_address_config</code>	set DMA memory base address
<code>dma_transfer_number_config</code>	set the number of remaining data to be transferred by the DMA
<code>dma_transfer_number_get</code>	get the number of remaining data to be transferred by the DMA
<code>dma_priority_config</code>	configure priority level of DMA channel
<code>dma_memory_width_config</code>	configure transfer data size of memory
<code>dma_periph_width_config</code>	configure transfer data size of peripheral
<code>dma_memory_increase_enable</code>	enable next address increasement algorithm of memory
<code>dma_memory_increase_disable</code>	disable next address increasement algorithm of memory
<code>dma_periph_increase_enable</code>	enable next address increasement algorithm of peripheral
<code>dma_periph_increase_disable</code>	disable next address increasement algorithm of peripheral
<code>dma_transfer_direction_config</code>	configure the direction of data transfer on the channel
<code>dma_flag_get</code>	check DMA flag is set or not
<code>dma_flag_clear</code>	clear the flag of a DMA channel
<code>dma_interrupt_flag_get</code>	check DMA flag and interrupt enable bit is set or not
<code>dma_interrupt_flag_clear</code>	clear the interrupt flag of a DMA channel
<code>dma_interrupt_enable</code>	enable DMA interrupt
<code>dma_interrupt_disable</code>	disable DMA interrupt

Structure dma_parameter_struct

Table 3-174. Structure dma_parameter_struct

Member name	Function description
periph_addr	peripheral base address
periph_width	transfer data size of peripheral
memory_addr	memory base address
memory_width	transfer data size of memory
number	channel transfer number
priority	channel priority level
periph_inc	peripheral increasing mode
memory_inc	memory increasing mode
direction	channel data transfer direction

dma_deinit

The description of dma_deinit is shown as below:

Table 3-175. Function dma_deinit

Function name	dma_deinit
Function prototype	void dma_deinit(uint32_t dma_periph, dma_channel_enum channelx);
Function descriptions	deinitialize DMA a channel registers
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0: x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* DMA0 channel0 initialize */
dma_deinit(DMA0, DMA_CH0);
```

dma_struct_para_init

The description of dma_struct_para_init is shown as below:

Table 3-176. Function dma_struct_para_init

Function name	dma_struct_para_init
Function prototype	void dma_struct_para_init(dma_parameter_struct* init_struct);
Function descriptions	initialize the parameters of DMA struct with the default values
Precondition	-
The called functions	-
Input parameter{in}	
*init_struct	a spi_parameter_struct address
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* initialize the parameters of DMA */
dma_parameter_struct dma_init_struct;
dma_struct_para_init(&dma_init_struct);
```

dma_init

The description of dma_init is shown as below:

Table 3-177. Function dma_init

Function name	dma_init
Function prototype	void dma_init(uint32_t dma_periph, dma_channel_enum channelx, dma_parameter_struct* init_struct);
Function descriptions	initialize DMA channel
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0,1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Input parameter{in}	
init_struct	Structure for initialization, the structure members can refer to Table 3-174. Structure dma_parameter_struct
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* DMA0 channel0 initialize */
dma_parameter_struct dma_init_struct;
dma_deinit(DMA0, DMA_CH0);
dma_struct_para_init(&dma_init_struct);

dma_init_struct.direction = DMA_PERIPHERAL_TO_MEMORY;
dma_init_struct.memory_addr = (uint32_t)g_destbuf;
dma_init_struct.memory_inc = DMA_MEMORY_INCREASE_ENABLE;
dma_init_struct.memory_width = DMA_MEMORY_WIDTH_8BIT;
dma_init_struct.number = TRANSFER_NUM;
dma_init_struct.periph_addr = (uint32_t)BANK0_WRITE_START_ADDR;
dma_init_struct.periph_inc = DMA_PERIPH_INCREASE_ENABLE;
dma_init_struct.periph_width = DMA_PERIPHERAL_WIDTH_8BIT;
dma_init_struct.priority = DMA_PRIORITY_ULTRA_HIGH;
dma_init(DMA0, DMA_CH0, &dma_init_struct);
```

dma_circulation_enable

The description of dma_circulation_enable is shown as below:

Table 3-178. Function dma_circulation_enable

Function name	dma_circulation_enable
Function prototype	void dma_circulation_enable(uint32_t dma_periph, dma_channel_enum channelx);
Function descriptions	enable DMA circulation mode
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0,1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DMA0 channel0 circulation mode */
dma_circulation_enable(DMA0, DMA_CH0);
```

dma_circulation_disable

The description of dma_circulation_disable is shown as below:

Table 3-179. Function dma_circulation_disable

Function name	dma_circulation_disable
Function prototype	void dma_circulation_disable(uint32_t dma_periph, dma_channel_enum channelx);
Function descriptions	disable DMA circulation mode
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0,1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DMA0 channel0 circulation mode */
dma_circulation_disable(DMA0, DMA_CH0);
```

dma_memory_to_memory_enable

The description of dma_memory_to_memory_enable is shown as below:

Table 3-180. Function dma_memory_to_memory_enable

Function name	dma_memory_to_memory_enable
Function prototype	void dma_memory_to_memory_enable(uint32_t dma_periph, dma_channel_enum channelx);
Function descriptions	enable memory to memory mode
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0,1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..</i>	DMA channel selection

6; DMA1: x=0..4)	
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DMA0 channel0 memory to memory mode */
dma_memory_to_memory_enable(DMA0, DMA_CH0);
```

dma_memory_to_memory_disable

The description of dma_memory_to_memory_disable is shown as below:

Table 3-181. Function dma_memory_to_memory_disable

Function name	dma_memory_to_memory_disable
Function prototype	void dma_memory_to_memory_disable(uint32_t dma_periph, dma_channel_enum channelx);
Function descriptions	disable memory to memory mode
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
DMAx(x=0, 1)	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
DMA_CHx(DMA0: x=0..6; DMA1: x=0..4)	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DMA0 channel0 memory to memory mode */
dma_memory_to_memory_disable(DMA0, DMA_CH0);
```

dma_channel_enable

The description of dma_channel_enable is shown as below:

Table 3-182. Function dma_channel_enable

Function name	dma_channel_enable
Function prototype	void dma_channel_enable(uint32_t dma_periph, dma_channel_enum channelx);

Function descriptions	enable DMA channel
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DMA0 channel0 */
dma_channel_enable(DMA0, DMA_CH0);
```

dma_channel_disable

The description of dma_channel_disable is shown as below:

Table 3-183. Function dma_channel_disable

Function name	dma_channel_disable
Function prototype	void dma_channel_disable(uint32_t dma_periph, dma_channel_enum channelx);
Function descriptions	disable DMA channel
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DMA0 channel0 */
```



```
dma_channel_disable(DMA0, DMA_CH0);
```

dma_periph_address_config

The description of dma_periph_address_config is shown as below:

Table 3-184. Function dma_periph_address_config

Function name	dma_periph_address_config
Function prototype	void dma_periph_address_config(uint32_t dma_periph, dma_channel_enum channelx, uint32_t address);
Function descriptions	set DMA peripheral base address
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
DMAx(x=0, 1)	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)	DMA channel selection
Input parameter{in}	
address	peripheral base address
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
#define BANK0_WRITE_START_ADDR ((uint32_t)0x08004000)

dma_periph_address_config(DMA0, DMA_CH0, BANK0_WRITE_START_ADDR);
```

dma_memory_address_config

The description of dma_memory_address_config is shown as below:

Table 3-185. Function dma_memory_address_config

Function name	dma_memory_address_config
Function prototype	void dma_memory_address_config(uint32_t dma_periph, dma_channel_enum channelx, uint32_t address);
Function descriptions	set DMA memory base address
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral

<i>DMAx(x=0,1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Input parameter{in}	
address	memory base address
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
uint8_t g_destbuf[TRANSFER_NUM];
```

```
dma_memory_address_config(DMA0, DMA_CH0, (uint32_t) g_destbuf);
```

dma_transfer_number_config

The description of dma_transfer_number_config is shown as below:

Table 3-186. Function dma_transfer_number_config

Function name	dma_transfer_number_config
Function prototype	void dma_transfer_number_config(uint32_t dma_periph, dma_channel_enum channelx, uint32_t number);
Function descriptions	set the number of remaining data to be transferred by the DMA
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0,1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Input parameter{in}	
number	data transfer number
<i>0-0xffff</i>	number
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
#define TRANSFER_NUM 0x400
```

```
dma_transfer_number_config(DMA0, DMA_CH0, TRANSFER_NUM);
```

dma_transfer_number_get

The description of dma_transfer_number_get is shown as below:

Table 3-187. Function dma_transfer_number_get

Function name	dma_transfer_number_get
Function prototype	uint32_t dma_transfer_number_get(uint32_t dma_periph, dma_channel_enum channelx);
Function descriptions	get the number of remaining data to be transferred by the DMA
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
uint32_t	0-0xffff

Example:

```
uint32_t number = 0;
```

```
number = dma_transfer_number_get(DMA0, DMA_CH0);
```

dma_priority_config

The description of dma_priority_config is shown as below:

Table 3-188. Function dma_priority_config

Function name	dma_priority_config
Function prototype	void dma_priority_config(uint32_t dma_periph, dma_channel_enum channelx, uint32_t priority);
Function descriptions	configure priority level of DMA channel
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection

Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Input parameter{in}	
priority	priority Level of this channel
<i>DMA_PRIORITY_LOW</i>	low priority
<i>DMA_PRIORITY_MEDIUM</i>	medium priority
<i>DMA_PRIORITY_HIGH</i>	high priority
<i>DMA_PRIORITY_ULTRA_HIGH</i>	ultra high priority
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
dma_priority_config(DMA0, DMA_CH0, DMA_PRIORITY_ULTRA_HIGH);
```

dma_memory_width_config

The description of dma_memory_width_config is shown as below:

Table 3-189. Function dma_memory_width_config

Function name	dma_memory_width_config
Function prototype	void dma_memory_width_config (uint32_t dma_periph, dma_channel_enum channelx, uint32_t mwidth);
Function descriptions	configure transfer data size of memory
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Input parameter{in}	
mwidth	transfer data width of memory
<i>DMA_MEMORY_WIDTH_8BIT</i>	transfer data width of memory is 8-bit
<i>DMA_MEMORY_WIDTH_16BIT</i>	transfer data width of memory is 16-bit

<i>DMA_MEMORY_WIDTH_32BIT</i>	transfer data width of memory is 32-bit
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
dma_memory_width_config(DMA0, DMA_CH0, DMA_MEMORY_WIDTH_8BIT);
```

dma_periph_width_config

The description of dma_periph_width_config is shown as below:

Table 3-190. Function dma_periph_width_config

Function name	dma_periph_width_config
Function prototype	void dma_periph_width_config (uint32_t dma_periph, dma_channel_enum channelx, uint32_t pwidth);
Function descriptions	configure transfer data size of peripheral
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0: x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Input parameter{in}	
pwidth	transfer data width of peripheral
<i>DMA_PERIPHERAL_WIDTH_8BIT</i>	transfer data width of peripheral is 8-bit
<i>DMA_PERIPHERAL_WIDTH_16BIT</i>	transfer data width of peripheral is 16-bit
<i>DMA_PERIPHERAL_WIDTH_32BIT</i>	transfer data width of peripheral is 32-bit
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
dma_periph_width_config(DMA0, DMA_CH0, DMA_PERIPHERAL_WIDTH_8BIT);
```

dma_memory_increase_enable

The description of dma_memory_increase_enable is shown as below:

Table 3-191. Function dma_memory_increase_enable

Function name	dma_memory_increase_enable
Function prototype	void dma_memory_increase_enable(uint32_t dma_periph, dma_channel_enum channelx);
Function descriptions	enable next address increasement algorithm of memory
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
dma_memory_increase_enable(DMA0, DMA_CH0);
```

dma_memory_increase_disable

The description of dma_memory_increase_disable is shown as below:

Table 3-192. Function dma_memory_increase_disable

Function name	dma_memory_increase_disable
Function prototype	void dma_memory_increase_disable(uint32_t dma_periph, dma_channel_enum channelx);
Function descriptions	disable next address increasement algorithm of memory
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
dma_memory_increase_disable(DMA0, DMA_CH0);
```

dma_periph_increase_enable

The description of dma_periph_increase_enable is shown as below:

Table 3-193. Function dma_periph_increase_enable

Function name	dma_periph_increase_enable
Function prototype	void dma_periph_increase_enable(uint32_t dma_periph, dma_channel_enum channelx);
Function descriptions	enable next address increasement algorithm of peripheral
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
dma_periph_increase_enable(DMA0, DMA_CH0);
```

dma_periph_increase_disable

The description of dma_periph_increase_disable is shown as below:

Table 3-194. Function dma_periph_increase_disable

Function name	dma_periph_increase_disable
Function prototype	void dma_periph_increase_disable(uint32_t dma_periph, dma_channel_enum channelx);
Function descriptions	disable next address increasement algorithm of peripheral
Precondition	-
The called functions	-

Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
dma_periph_increase_disable(DMA0, DMA_CH0);
```

dma_transfer_direction_config

The description of dma_transfer_direction_config is shown as below:

Table 3-195. Function dma_transfer_direction_config

Function name	dma_transfer_direction_config
Function prototype	void dma_transfer_direction_config(uint32_t dma_periph, dma_channel_enum channelx, uint32_t direction);
Function descriptions	configure the direction of data transfer on the channel
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Input parameter{in}	
direction	specify the direction of data transfer
<i>DMA_PERIPHERAL_TO_MEMORY</i>	read from peripheral and write to memory
<i>DMA_MEMORY_TO_PERIPHERAL</i>	read from memory and write to peripheral
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
dma_transfer_direction_config(DMA0, DMA_CH0, DMA_PERIPHERAL_TO_MEMORY);
```

dma_flag_get

The description of dma_flag_get is shown as below:

Table 3-196. Function dma_flag_get

Function name	dma_flag_get
Function prototype	FlagStatus dma_flag_get(uint32_t dma_periph, dma_channel_enum channelx, uint32_t flag);
Function descriptions	check DMA flag is set or not
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Input parameter{in}	
flag	specify get which flag
<i>DMA_FLAG_G</i>	global interrupt flag of channel
<i>DMA_FLAG_FTF</i>	full transfer finish flag of channel
<i>DMA_FLAG_HTF</i>	half transfer finish flag of channel
<i>DMA_FLAG_ERR</i>	error flag of channel
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
FlagStatus flag = RESET;
```

```
flag = dma_flag_get(DMA0, DMA_CH0, DMA_FLAG_FTF);
```

dma_flag_clear

The description of dma_flag_clear is shown as below:

Table 3-197. Function dma_flag_clear

Function name	dma_flag_clear
Function prototype	void dma_flag_clear(uint32_t dma_periph, dma_channel_enum channelx, uint32_t flag);

Function descriptions	clear the flag of a DMA channel
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Input parameter{in}	
flag	specify get which flag
<i>DMA_FLAG_G</i>	global interrupt flag of channel
<i>DMA_FLAG_FTF</i>	full transfer finish flag of channel
<i>DMA_FLAG_HTF</i>	half transfer finish flag of channel
<i>DMA_FLAG_ERR</i>	error flag of channel
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
dma_flag_clear(DMA0, DMA_CH0, DMA_FLAG_FTF);
```

dma_interrupt_flag_get

The description of dma_interrupt_flag_get is shown as below:

Table 3-198. Function dma_interrupt_flag_get

Function name	dma_interrupt_flag_get
Function prototype	FlagStatus dma_interrupt_flag_get(uint32_t dma_periph, dma_channel_enum channelx, uint32_t flag);
Function descriptions	check DMA flag and interrupt enable bit is set or not
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Input parameter{in}	

flag	specify get which flag
<i>DMA_INT_FLAG_FTF</i>	full transfer finish interrupt flag of channel
<i>DMA_INT_FLAG_HTF</i>	half transfer finish interrupt flag of channel
<i>DMA_INT_FLAG_ER</i>	error interrupt flag of channel
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
if(dma_interrupt_flag_get(DMA0, DMA_CH3, DMA_INT_FLAG_FTF)){
    dma_interrupt_flag_clear(DMA0, DMA_CH3, DMA_INT_FLAG_G);
}
```

dma_interrupt_flag_clear

The description of dma_interrupt_flag_clear is shown as below:

Table 3-199. Function dma_interrupt_flag_clear

Function name	dma_interrupt_flag_clear
Function prototype	void dma_interrupt_flag_clear(uint32_t dma_periph, dma_channel_enum channelx, uint32_t flag);
Function descriptions	clear the interrupt flag of a DMA channel
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Input parameter{in}	
flag	specify get which flag
<i>DMA_INT_FLAG_G</i>	global interrupt flag of channel
<i>DMA_INT_FLAG_FTF</i>	full transfer finish interrupt flag of channel
<i>DMA_INT_FLAG_HTF</i>	half transfer finish interrupt flag of channel
<i>DMA_INT_FLAG_ER</i>	error interrupt flag of channel

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
if(dma_interrupt_flag_get(DMA0, DMA_CH3, DMA_INT_FLAG_FTF)){
    dma_interrupt_flag_clear(DMA0, DMA_CH3, DMA_INT_FLAG_G);
}
```

dma_interrupt_enable

The description of dma_interrupt_enable is shown as below:

Table 3-200. Function dma_interrupt_enable

Function name	dma_interrupt_enable
Function prototype	void dma_interrupt_enable(uint32_t dma_periph, dma_channel_enum channelx, uint32_t source);
Function descriptions	enable DMA interrupt
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0, 1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Input parameter{in}	
source	DMA interrupt source
<i>DMA_INT_FTF</i>	full transfer finish interrupt of channel
<i>DMA_INT_HTF</i>	half transfer finish interrupt of channel
<i>DMA_INT_ERR</i>	error interrupt of channel
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* DMA0 channel0 interrupt configuration */
dma_interrupt_enable(DMA0, DMA_CH0, DMA_INT_FTF);
```

dma_interrupt_disable

The description of dma_interrupt_disable is shown as below:

Table 3-201. Function dma_interrupt_disable

Function name	dma_interrupt_disable
Function prototype	void dma_interrupt_disable(uint32_t dma_periph, dma_channel_enum channelx, uint32_t source);
Function descriptions	disable DMA interrupt
Precondition	-
The called functions	-
Input parameter{in}	
dma_periph	DMA peripheral
<i>DMAx(x=0,1)</i>	DMA peripheral selection
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(DMA0:x=0..6; DMA1: x=0..4)</i>	DMA channel selection
Input parameter{in}	
source	DMA interrupt source
<i>DMA_INT_FTF</i>	full transfer finish interrupt of channel
<i>DMA_INT_HTF</i>	half transfer finish interrupt of channel
<i>DMA_INT_ERR</i>	error interrupt of channel
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* DMA0 channel0 interrupt configuration */
```

```
dma_interrupt_disable(DMA0, DMA_CH0, DMA_INT_FTF);
```

3.10. EXMC

The external memory controller EXMC, is used as a translator for MCU to access a variety of external memory. The EXMC registers are listed in chapter [3.10.1](#), the EXMC firmware functions are introduced in chapter [3.10.2](#).

3.10.1. Descriptions of Peripheral registers

EXMC registers are listed in the table shown as below:

Table 3-202. EXMC Registers

Registers	Descriptions
EXMC_SNCTL	SRAM/NOR Flash control registers
EXMC_SNTCFG	SRAM/NOR Flash timing configuration registers
EXMC_SNWTCFG	SRAM/NOR Flash write timing configuration registers

3.10.2. Descriptions of Peripheral functions

EXMC firmware functions are listed in the table shown as below:

Table 3-203. EXMC firmware function

Function name	Function description
exmc_norsram_deinit	deinitialize EXMC NOR/SRAM bank
exmc_norsram_init	initialize EXMC NOR/SRAM bank
exmc_norsram_struct_para_init	initialize the struct exmc_norsram_parameter_struct
exmc_norsram_enable	enable EXMC NOR/PSRAM bank
exmc_norsram_disable	disable EXMC NOR/PSRAM bank
exmc_norsram_page_size_config	configure CRAM page size

Structure exmc_norsram_timing_parameter_struct

Table 3-204. Structure exmc_norsram_timing_parameter_struct

Member name	Function description
asyn_access_mode	asynchronous access mode
syn_data_latency	configure the data latency
syn_clk_division	configure the clock divide ratio
bus_latency	configure the bus latency
asyn_data_setup_time	configure the data setup time, asynchronous access mode valid
asyn_address_hold_time	configure the address hold time, asynchronous access mode valid
asyn_address_setup_time	configure the data setup time, asynchronous access mode valid

Structure exmc_norsram_parameter_struct

Table 3-205. Structure exmc_norsram_parameter_struct

Member name	Function description
write_mode	the write mode, synchronous mode or asynchronous mode
extended_mode	enable or disable the extended mode
asyn_wait	enable or disable the asynchronous wait function
nwait_signal	enable or disable the NWAIT signal while in synchronous bust mode
memory_write	enable or disable the write operation
nwait_config	NWAIT signal configuration

wrap_burst_mode	enable or disable the wrap burst mode
nwait_polarity	specifies the polarity of NWAIT signal from memory
burst_mode	enable or disable the burst mode
databus_width	specifies the databus width of external memory
memory_type	specifies the type of external memory
address_data_mux	specifies whether the data bus and address bus are multiplexed
read_write_timing	timing parameters for read and write if the extended mode is not used or the timing parameters for read if the extended mode is used
write_timing	timing parameters for write when the extended mode is used

exmc_norsram_deinit

The description of exmc_norsram_deinit is shown as below:

Table 3-206. Function exmc_norsram_deinit

Function name	exmc_norsram_deinit
Function prototype	void exmc_norsram_deinit(void);
Function descriptions	deinitialize EXMC NOR/SRAM bank
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* deinitialize EXMC NOR/SRAM bank */
exmc_norsram_deinit();
```

exmc_norsram_init

The description of exmc_norsram_init is shown as below:

Table 3-207. Function exmc_norsram_init

Function name	exmc_norsram_init
Function prototype	void exmc_norsram_init(exmc_norsram_parameter_struct* exmc_norsram_init_struct);
Function descriptions	initialize EXMC NOR/SRAM bank
Precondition	-
The called functions	-
Input parameter{in}	
exmc_norsram_init_st	Structure for initialization, the structure members can refer to Table 3-205 .

ruct	<u>Structure exmc_norsram_parameter_struct</u>
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* initialize EXMC NOR/SRAM bank */

exmc_norsram_parameter_struct lcd_init_struct;

exmc_norsram_timing_parameter_struct lcd_timing_init_struct;

/* configure timing parameter */

lcd_timing_init_struct.asyn_access_mode = EXMC_ACCESS_MODE_A;

lcd_timing_init_struct.syn_data_latency = EXMC_DATA_LAT_2_CLK;

lcd_timing_init_struct.syn_clk_division = EXMC_SYN_CLOCK_RATIO_DISABLE;

lcd_timing_init_struct.bus_latency = 1;

lcd_timing_init_struct.asyn_data_setup_time = 5;

lcd_timing_init_struct.asyn_address_hold_time = 2;

lcd_timing_init_struct.asyn_address_setup_time = 2;

/* configure EXMC bus parameters */

lcd_init_struct.write_mode = EXMC_ASYN_WRITE;

lcd_init_struct.extended_mode = DISABLE;

lcd_init_struct.asyn_wait = DISABLE;

lcd_init_struct.nwait_signal = DISABLE;

lcd_init_struct.memory_write = ENABLE;

lcd_init_struct.nwait_config = EXMC_NWAIT_CONFIG_BEFORE;

lcd_init_struct.wrap_burst_mode = DISABLE;

lcd_init_struct.nwait_polarity = EXMC_NWAIT_POLARITY_LOW;

lcd_init_struct.burst_mode = DISABLE;

lcd_init_struct.databus_width = EXMC_NOR_DATABUS_WIDTH_16B;

lcd_init_struct.memory_type = EXMC_MEMORY_TYPE_SRAM;

lcd_init_struct.address_data_mux = DISABLE;

lcd_init_struct.read_write_timing = &lcd_timing_init_struct;

```



```
lcd_init_struct.write_timing = &lcd_timing_init_struct;
```

```
exmc_norsram_init(&lcd_init_struct);
```

exmc_norsram_struct_para_init

The description of exmc_norsram_struct_para_init is shown as below:

Table 3-208. Function exmc_norsram_struct_para_init

Function name	exmc_norsram_struct_para_init
Function prototype	void exmc_norsram_struct_para_init(exmc_norsram_parameter_struct* exmc_norsram_init_struct);
Function descriptions	initialize the struct exmc_norsram_parameter_struct
Precondition	-
The called functions	-
Input parameter{in}	
exmc_norsram_init_struct	Structure for initialization, the structure members can refer to Table 3-205. Structure exmc_norsram_parameter_struct
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* initialize the struct nor_init_struct */
exmc_norsram_parameter_struct nor_init_struct;
exmc_norsram_struct_para_init (&nor_init_struct);
```

exmc_norsram_enable

The description of exmc_norsram_enable is shown as below:

Table 3-209. Function exmc_norsram_enable

Function name	exmc_norsram_enable
Function prototype	void exmc_norsram_enable(void);
Function descriptions	enable EXMC NOR/PSRAM bank
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable bank */
```

```
exmc_norsram_enable();
```

exmc_norsram_disable

The description of exmc_norsram_disable is shown as below:

Table 3-210. Function exmc_norsram_disable

Function name	exmc_norsram_disable
Function prototype	void exmc_norsram_disable(void);
Function descriptions	disable EXMC NOR/PSRAM bank
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable bank */
```

```
exmc_norsram_disable();
```

exmc_norsram_page_size_config

The description of exmc_norsram_page_size_config is shown as below:

Table 3-211. Function exmc_norsram_page_size_config

Function name	exmc_norsram_page_size_config
Function prototype	void exmc_norsram_page_size_config(uint32_t page_size);
Function descriptions	configure CRAM page size
Precondition	-
The called functions	-
Input parameter{in}	
page_size	CRAM page size
<i>EXMC_CRAM_AUTO_SPLIT</i>	the clock is generated only during synchronous access
<i>EXMC_CRAM_PAGE_SIZE_128_BYTES</i>	page size is 128 bytes
<i>EXMC_CRAM_PAGE_SIZE_256_BYTES</i>	page size is 256 bytes

EXMC_CRAM_PAGE_SIZE_512_BYTES	page size is 512 bytes
EXMC_CRAM_PAGE_SIZE_1024_BYTES	page size is 1024 bytes
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure CRAM page size */
```

```
exmc_norsram_page_size_config (EXMC_CRAM_PAGE_SIZE_128_BYTES);
```

3.11. EXTI

EXTI is the interrupt / event controller in the MCU. It contains up to 19 independent edge detectors and generates interrupt requests or events to the processor. The EXTI registers are listed in chapter [3.11.1](#), the EXTI firmware functions are introduced in chapter [3.11.2](#).

3.11.1. Descriptions of Peripheral registers

EXTI registers are listed in the table shown as below:

Table 3-212. EXTI Registers

Registers	Descriptions
EXTI_INTEN	interrupt enable register
EXTI_EVEN	event enable register
EXTI_RTEN	rising edge trigger enable register
EXTI_FTEN	falling edge trigger enable register
EXTI_SWIEV	software interrupt event register
EXTI_PD	pending register

3.11.2. Descriptions of Peripheral functions

EXTI firmware functions are listed in the table shown as below:

Table 3-213. EXTI firmware function

Function name	Function description
exti_deinit	deinitialize the EXTI
exti_init	initialize the EXTI line x
exti_interrupt_enable	enable the interrupts from EXTI line x
exti_interrupt_disable	disable the interrupts from EXTI line x
exti_event_enable	enable the events from EXTI line x

Function name	Function description
exti_event_disable	disable the events from EXTI line x
exti_software_interrupt_enable	enable the software interrupt event from EXTI line x
exti_software_interrupt_disable	disable the software interrupt event from EXTI line x
exti_flag_get	get EXTI line x interrupt pending flag
exti_flag_clear	clear EXTI line x interrupt pending flag
exti_interrupt_flag_get	get EXTI line x interrupt pending flag
exti_interrupt_flag_clear	clear EXTI line x interrupt pending flag

Enum exti_line_enum

Table 3-214. Enum exti_line_enum

Member name	Function description
EXTI_0	EXTI line 0
EXTI_1	EXTI line 1
EXTI_2	EXTI line 2
EXTI_3	EXTI line 3
EXTI_4	EXTI line 4
EXTI_5	EXTI line 5
EXTI_6	EXTI line 6
EXTI_7	EXTI line 7
EXTI_8	EXTI line 8
EXTI_9	EXTI line 9
EXTI_10	EXTI line 10
EXTI_11	EXTI line 11
EXTI_12	EXTI line 12
EXTI_13	EXTI line 13
EXTI_14	EXTI line 14
EXTI_15	EXTI line 15
EXTI_16	EXTI line 16
EXTI_17	EXTI line 17
EXTI_18	EXTI line 18

Enum exti_mode_enum

Table 3-215. Enum exti_mode_enum

Member name	Function description
EXTI_INTERRUPT	EXTI interrupt mode
EXTI_EVENT	EXTI event mode

Enum exti_trig_type_enum

Table 3-216. Enum exti_trig_type_enum

Member name	Function description
-------------	----------------------

EXTI_TRIG_RISING	EXTI rising edge trigger
EXTI_TRIG_FALLING	EXTI falling edge trigger
EXTI_TRIG_BOTH	EXTI rising and falling edge trigger
EXTI_TRIG_NONE	EXTI without rising or falling edge trigger

exti_deinit

The description of exti_deinit is shown as below:

Table 3-217. Function exti_deinit

Function name	exti_deinit
Function prototype	void exti_deinit(void);
Function descriptions	deinitialize the EXTI
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* deinitialize the EXTI */
exti_deinit();
```

exti_init

The description of exti_init is shown as below:

Table 3-218. Function exti_init

Function name	exti_init
Function prototype	void exti_init(exti_line_enum linex, exti_mode_enum mode, exti_trig_type_enum trig_type);
Function descriptions	initialize the EXTI line x
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x, refer to Table 3-214. Enum exti_line_enum
Input parameter{in}	
mode	EXTI mode, refer to Table 3-215. Enum exti_mode_enum
Input parameter{in}	
trig_type	trigger type, refer to Table 3-216. Enum exti_trig_type_enum
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* configure EXTI_0 */
```

```
exti_init(EXTI_0, EXTI_INTERRUPT, EXTI_TRIG_BOTH);
```

exti_interrupt_enable

The description of exti_interrupt_enable is shown as below:

Table 3-219. Function exti_interrupt_enable

Function name	exti_interrupt_enable
Function prototype	void exti_interrupt_enable(exti_line_enum linex);
Function descriptions	enable the interrupts from EXTI line x
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x, refer to Table 3-214. Enum exti_line_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the interrupts from EXTI line 0 */
```

```
exti_interrupt_enable(EXTI_0);
```

exti_interrupt_disable

The description of exti_interrupt_disable is shown as below:

Table 3-220. Function exti_interrupt_disable

Function name	exti_interrupt_disable
Function prototype	void exti_interrupt_disable(exti_line_enum linex);
Function descriptions	disable the interrupts from EXTI line x
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x, refer to Table 3-214. Enum exti_line_enum
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* disable the interrupts from EXTI line 0 */
```

```
exti_interrupt_disable(EXTI_0);
```

exti_event_enable

The description of exti_event_enable is shown as below:

Table 3-221. Function exti_event_enable

Function name	exti_event_enable
Function prototype	void exti_event_enable(exti_line_enum linex);
Function descriptions	enable the events from EXTI line x
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x, refer to Table 3-214. Enum exti_line_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the events from EXTI line 0 */
```

```
exti_event_enable(EXTI_0);
```

exti_event_disable

The description of exti_event_disable is shown as below:

Table 3-222. Function exti_event_disable

Function name	exti_event_disable
Function prototype	void exti_event_disable(exti_line_enum linex);
Function descriptions	disable the events from EXTI line x
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x, refer to Table 3-214. Enum exti_line_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the events from EXTI line 0 */
```

```
exti_event_disable(EXTI_0);
```

exti_software_interrupt_enable

The description of exti_software_interrupt_enable is shown as below:

Table 3-223. Function exti_software_interrupt_enable

Function name	exti_software_interrupt_enable
Function prototype	void exti_software_interrupt_enable(exti_line_enum linex);
Function descriptions	enable the software interrupt event from EXTI line x
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x, refer to Table 3-214. Enum exti_line_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable EXTI line 0 software interrupt */
```

```
exti_software_interrupt_enable(EXTI_0);
```

exti_software_interrupt_disable

The description of exti_software_interrupt_disable is shown as below:

Table 3-224. Function exti_software_interrupt_disable

Function name	exti_software_interrupt_disable
Function prototype	void exti_software_interrupt_disable(exti_line_enum linex);
Function descriptions	disable the software interrupt event from EXTI line x
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x, refer to Table 3-214. Enum exti_line_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:


```
/* disable EXTI line 0 software interrupt */
```

```
exti_software_interrupt_disable(EXTI_0);
```

exti_flag_get

The description of exti_flag_get is shown as below:

Table 3-225. Function exti_flag_get

Function name	exti_flag_get
Function prototype	FlagStatus exti_flag_get(exti_line_enum linex);
Function descriptions	get EXTI line x interrupt pending flag
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x, refer to Table 3-214. Enum exti_line_enum
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get EXTI line 0 flag status */
```

```
FlagStatus state = exti_flag_get(EXTI_0);
```

exti_flag_clear

The description of exti_flag_clear is shown as below:

Table 3-226. Function exti_flag_clear

Function name	exti_flag_clear
Function prototype	void exti_flag_clear(exti_line_enum linex);
Function descriptions	clear EXTI line x interrupt pending flag
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x, refer to Table 3-214. Enum exti_line_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear EXTI line 0 flag status */
```

```
exti_flag_clear(EXTI_0);
```

exti_interrupt_flag_get

The description of exti_interrupt_flag_get is shown as below:

Table 3-227. Function exti_interrupt_flag_get

Function name	exti_interrupt_flag_get
Function prototype	FlagStatus exti_interrupt_flag_get(exti_line_enum linex);
Function descriptions	get EXTI line x interrupt pending flag
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x, refer to Table 3-214. Enum exti_line_enum
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get EXTI line 0 interrupt flag status */
```

```
FlagStatus state = exti_interrupt_flag_get(EXTI_0);
```

exti_interrupt_flag_clear

The description of exti_interrupt_flag_clear is shown as below:

Table 3-228. Function exti_interrupt_flag_clear

Function name	exti_interrupt_flag_clear
Function prototype	void exti_interrupt_flag_clear(exti_line_enum linex);
Function descriptions	clear EXTI line x interrupt pending flag
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x, refer to Table 3-214. Enum exti_line_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear EXTI line 0 interrupt flag status */
```

```
exti_interrupt_flag_clear(EXTI_0);
```

3.12. FMC

There is flash controller and option byte for GD32A10x series. The FMC registers are listed in chapter [3.12.1](#) the FMC firmware functions are introduced in chapter [3.12.2](#).

3.12.1. Descriptions of Peripheral registers

FMC registers are listed in the table shown as below:

Table 3-229. FMC Registers

Registers	Descriptions
FMC_WS	Wait state register
FMC_KEY	Unlock key register
FMC_OBKEY	Option byte unlock key register
FMC_STAT	Status register
FMC_CTL	Control register
FMC_ADDR	Address register
FMC_OBSTAT	Option byte status register
FMC_WP	Erase/Program Protection register
FMC_PID	Product ID register

3.12.2. Descriptions of Peripheral functions

FMC firmware functions are listed in the table shown as below:

Table 3-230. FMC firmware function

Function name	Function description
fmc_wsctl_set	set the FMC wait state counter
fmc_prefetch_enable	enable pre-fetch
fmc_prefetch_disable	disable pre-fetch
fmc_ibus_enable	enable IBUS cache
fmc_ibus_disable	disable IBUS cache
fmc_dbus_enable	enable DBUS cache
fmc_dbus_disable	disable DBUS cache
fmc_ibus_reset	reset IBUS cache
fmc_dbus_reset	reset DBUS cache
fmc_program_width_set	set program width to flash memory
fmc_unlock	unlock the main FMC operation
fmc_lock	lock the main FMC operation
fmc_page_erase	FMC erase page
fmc_mass_erase	FMC erase whole chip
fmc_doubleword_program	FMC program a double word at the corresponding address
fmc_word_program	FMC program a word at the corresponding address

Function name	Function description
ob_unlock	unlock the option byte operation
ob_lock	lock the option byte operation
ob_erase	erase the option byte
ob_write_protection_enable	enable write protection
ob_security_protection_config	configure the option byte security protection
ob_user_write	write the FMC user option byte
ob_data_program	program option bytes data
ob_user_get	get the FMC user option byte
ob_data_get	get OB_DATA in register FMC_OBSTAT
ob_write_protection_get	get the FMC option byte write protection
ob_security_protection_flag_get	get option byte security protection state
fmc_interrupt_enable	enable FMC interrupt
fmc_interrupt_disable	disable FMC interrupt
fmc_flag_get	check flag is set or not
fmc_flag_clear	clear the FMC flag
fmc_interrupt_flag_get	get FMC interrupt flag state
fmc_interrupt_flag_clear	clear FMC interrupt flag state
fmc_state_get	get FMC state
fmc_ready_wait	check FMC ready or not

Enum fmc_state_enum

Table 3-231. Enum fmc_state_enum

enum name	enum description
FMC_READY	the operation has been completed
FMC_BUSY	the operation is in progress
FMC_PGERR	program error
FMC_PGAERR	program alignment error
FMC_WPERR	erase/program protection error
FMC_TOERR	timeout error

Enum fmc_int_enum

Table 3-232. Enum fmc_int_enum

enum name	enum description
FMC_INT_END	enable FMC end of program interrupt
FMC_INT_ERR	enable FMC error interrupt

Enum fmc_flag_enum

Table 3-233. Enum fmc_flag_enum

enum name	enum description
FMC_FLAG_BUSY	FMC busy flag

enum name	enum description
FMC_FLAG_PGER R	FMC operation error flag
FMC_FLAG_PGAE RR	FMC program alignment error flag
FMC_FLAG_WPER R	FMC erase/program protection error flag
FMC_FLAG_END	FMC end of operation flag
FMC_FLAG_OBER R	FMC option bytes read error flag

Enum `fmc_interrupt_flag_enum`

Table 3-234. Enum `fmc_interrupt_flag_enum`

enum name	enum description
FMC_INT_FLAG_P GERR	FMC operation error interrupt flag
FMC_INT_FLAG_P GAERR	FMC program alignment error interrupt flag bit
FMC_INT_FLAG_W PERR	FMC erase/program protection error interrupt flag
FMC_INT_FLAG_E ND	FMC end of operation interrupt flag

`fmc_wscnt_set`

The description of `fmc_wscnt_set` is shown as below:

Table 3-235. Function `fmc_wscnt_set`

Function name	<code>fmc_wscnt_set</code>
Function prototype	<code>void fmc_wscnt_set(uint32_t wscnt);</code>
Function descriptions	set the wait state counter value
Precondition	-
The called functions	<code>rcu_periph_reset_enable</code> / <code>rcu_periph_reset_disable</code>
Input parameter{in}	
wscnt	wait state counter value
<code>FMC_WAIT_STATE_0</code>	FMC 0 wait
<code>FMC_WAIT_STATE_1</code>	FMC 1 wait
<code>FMC_WAIT_STATE_2</code>	FMC 2 wait
<code>FMC_WAIT_STATE_3</code>	FMC 3 wait
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set the wait state counter value */

fmc_wscht_set (FMC_WAIT_STATE_1);
```

fmc_prefetch_enable

The description of fmc_prefetch_enable is shown as below:

Table 3-236. Function fmc_prefetch_enable

Function name	fmc_prefetch_enable
Function prototype	void fmc_prefetch_enable(void);
Function descriptions	enable pre-fetch
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable pre-fetch */

fmc_prefetch_enable( );
```

fmc_prefetch_disable

The description of fmc_prefetch_disable is shown as below:

Table 3-237. Function fmc_prefetch_disable

Function name	fmc_prefetch_disable
Function prototype	void fmc_prefetch_disable (void);
Function descriptions	disable pre-fetch
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable pre-fetch */
```

```
fmc_prefetch_disable( );
```

fmc_ibus_enable

The description of fmc_ibus_enable is shown as below:

Table 3-238. Function fmc_ibus_enable

Function name	fmc_ibus_enable
Function prototype	void fmc_ibus_enable(void);
Function descriptions	enable IBUS cache
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable IBUS cache */
```

```
fmc_ibus_enable( );
```

fmc_ibus_disable

The description of fmc_ibus_disable is shown as below:

Table 3-239. Function fmc_ibus_disable

Function name	fmc_ibus_disable
Function prototype	void fmc_ibus_disable(void);
Function descriptions	disable IBUS cache
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable IBUS cache */
```

fmc_ibus_disable();

fmc_dbus_enable

The description of fmc_dbus_enable is shown as below:

Table 3-240. Function fmc_dbus_enable

Function name	fmc_dbus_enable
Function prototype	void fmc_dbus_enable(void);
Function descriptions	enable DBUS cache
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DBUS cache */
```

```
fmc_dbus_enable( );
```

fmc_dbus_disable

The description of fmc_dbus_disable is shown as below:

Table 3-241. Function fmc_dbus_disable

Function name	fmc_dbus_disable
Function prototype	void fmc_dbus_disable(void);
Function descriptions	disable DBUS cache
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DBUS cache */
```

```
fmc_dbus_disable( );
```


fmc_ibus_reset

The description of fmc_ibus_reset is shown as below:

Table 3-242. Function fmc_ibus_reset

Function name	fmc_ibus_reset
Function prototype	void fmc_ibus_reset (void);
Function descriptions	reset IBUS cache
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset IBUS cache */
fmc_ibus_reset( );
```

fmc_dbus_reset

The description of fmc_dbus_reset is shown as below:

Table 3-243. Function fmc_dbus_reset

Function name	fmc_dbus_reset
Function prototype	void fmc_dbus_reset(void);
Function descriptions	reset DBUS cache
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset DBUS cache */
fmc_dbus_reset( );
```

fmc_program_width_set

The description of fmc_program_width_set is shown as below:

Table 3-244. Function fmc_program_width_set

Function name	fmc_program_width_set
Function prototype	void fmc_program_width_set(uint32_t pgw);
Function descriptions	set program width to flash memory
Precondition	-
The called functions	-
Input parameter{in}	
pgw	program width
<i>FMC_PROG_W_32B</i>	32-bit program width to flash memory
<i>FMC_PROG_W_64B</i>	64-bit program width to flash memory
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set program width to flash memory */
fmc_program_width_set(FMC_PROG_W_32B);
```

fmc_unlock

The description of fmc_unlock is shown as below:

Table 3-245. Function fmc_unlock

Function name	fmc_unlock
Function prototype	void fmc_unlock (void);
Function descriptions	unlock the main FMC operation
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* unlock the main FMC operation */
fmc_unlock ( );
```

fmc_lock

The description of fmc_lock is shown as below:

Table 3-246. Function fmc_lock

Function name	fmc_lock
Function prototype	void fmc_lock(void);
Function descriptions	lock the main FMC operation
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* lock the main FMC operation */
fmc_lock( );
```

fmc_page_erase

The description of fmc_page_erase is shown as below:

Table 3-247. Function fmc_page_erase

Function name	fmc_page_erase
Function prototype	fmc_state_enum fmc_page_erase(uint32_t page_address);
Function descriptions	erase page
Precondition	fmc_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
page_address	the page address to be erased
Output parameter{out}	
-	-
Return value	
fmc_state_enum	<u>state of FMC</u>

Example:

```
/* erase page */
fmc_page_erase ( 0x08004000);
```

fmc_mass_erase

The description of fmc_mass_erase is shown as below:

Table 3-248. Function fmc_mass_erase

Function name	fmc_mass_erase
Function prototype	fmc_state_enum fmc_mass_erase(void);
Function descriptions	erase whole chip
Precondition	fmc_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC

Example:

```
/* erase whole chip */
fmc_mass_erase ( );
```

fmc_doubleword_program

The description of fmc_doubleword_program is shown as below:

Table 3-249. Function fmc_doubleword_program

Function name	fmc_doubleword_program
Function prototype	fmc_state_enum fmc_doubleword_program(uint32_t address, uint64_t data);
Function descriptions	program a double word at the corresponding address
Precondition	fmc_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
address	the address to program
data	the data to program
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC

Example:

```
/* program a double word at the corresponding address */
fmc_doubleword_program( 0x08004000,0xaabbccddeeffgghh);
```

fmc_word_program

The description of fmc_word_program is shown as below:

Table 3-250. Function fmc_word_program

Function name	fmc_word_program
Function prototype	fmc_state_enum fmc_word_program(uint32_t address, uint32_t data);
Function descriptions	program a word at the corresponding address
Precondition	fmc_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
address	the address to program
data	the data to program
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC

Example:

```
/* program a word at the corresponding address */
fmc_word_program ( 0x08004000,0xaabbccdd);
```

ob_unlock

The description of ob_unlock is shown as below:

Table 3-251. Function ob_unlock

Function name	ob_unlock
Function prototype	void ob_unlock(void);
Function descriptions	unlock the option byte operation
Precondition	fmc_unlock
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* unlock the option byte operation */
ob_unlock( );
```

ob_lock

The description of ob_lock is shown as below:

Table 3-252. Function ob_lock

Function name	ob_lock
Function prototype	void ob_lock(void);
Function descriptions	lock the option byte operation
Precondition	fmc_lock
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* lock the option byte operation */
ob_lock( );
```

ob_erase

The description of ob_erase is shown as below:

Table 3-253. Function ob_erase

Function name	ob_erase
Function prototype	void ob_erase(void);
Function descriptions	erase the FMC option byte
Precondition	ob_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* erase the FMC option byte */
ob_erase ( );
```

ob_write_protection_enable

The description of ob_write_protection_enable is shown as below:

Table 3-254. Function ob_write_protection_enable

Function name	ob_write_protection_enable
Function prototype	fmc_state_enum ob_write_protection_enable(uint32_t ob_wp);
Function descriptions	enable write protection
Precondition	ob_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
ob_wp	enable write protection
<i>OB_WP_x</i>	write protect specify sector x
<i>OB_WP_ALL</i>	write protect all sector
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC

Example:

```
/* enable write protection */
```

```
ob_write_protection_enable (OB_WP_7);
```

ob_security_protection_config

The description of ob_security_protection_config is shown as below:

Table 3-255. Function ob_security_protection_config

Function name	ob_security_protection_config
Function prototype	fmc_state_enum ob_security_protection_config (uint8_t ob_spc);
Function descriptions	configure security protection
Precondition	ob_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
ob_spc	specify security protection
<i>FMC_NSPC</i>	no security protection
<i>FMC_USPC</i>	under security protection
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC

Example:

```
/* enable security protection */
```

ob_security_protection_config (FMC_USPC);

ob_user_write

The description of ob_user_write is shown as below:

Table 3-256. Function ob_user_write

Function name	ob_user_write
Function prototype	fmc_state_enum ob_user_write(uint8_t ob_fwdgt, uint8_t ob_deepsleep, uint8_t ob_stdby);
Function descriptions	program the FMC user option byte
Precondition	ob_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
ob_fwdgt	option byte watchdog value
OB_FWDGT_SW	software free watchdog
OB_FWDGT_HW	hardware free watchdog
Input parameter{in}	
ob_deepsleep	option byte deepsleep reset value
OB_DEEPSLEEP_NRS T	no reset when entering deepsleep mode
OB_DEEPSLEEP_RST	generate a reset instead of entering deepsleep mode
Input parameter{in}	
ob_stdby	option byte standby reset value
OB_STDBY_NRST	no reset when entering standby mode
OB_STDBY_RST	generate a reset instead of entering standby mode
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC

Example:

```
/* configure user option byte */
```

```
ob_user_write(OB_FWDGT_HW, OB_DEEPSLEEP_RST, OB_STDBY_RST);
```

ob_data_program

The description of ob_data_program is shown as below:

Table 3-257. Function ob_data_program

Function name	ob_data_program
Function prototype	fmc_state_enum ob_data_program(uint32_t address, uint8_t data);
Function descriptions	program option bytes data
Precondition	ob_unlock

The called functions	fmc_ready_wait
Input parameter{in}	
address	the option bytes address to be programmed
data	the byte to be programmed
Output parameter{out}	
-	-
Return value	
fmc_state_enum	<u>state of FMC</u>

Example:

```
/* program option bytes data */
ob_data_program (0x1fff804, 0x56);
```

ob_user_get

The description of ob_user_get is shown as below:

Table 3-258. Function ob_user_get

Function name	ob_user_get
Function prototype	uint8_t ob_user_get(void);
Function descriptions	get the FMC user option byte
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint8_t	the FMC user option byte values(0xF0 – 0xFF)

Example:

```
/* get the FMC user option byte */
uint8_t user = ob_user_get ( );
```

ob_data_get

The description of ob_data_get is shown as below:

Table 3-259. Function ob_data_program

Function name	ob_data_get
Function prototype	Uint16_t ob_data_get(void);
Function descriptions	get the FMC data option byte
Precondition	-
The called functions	-

Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
Uint16_t	the FMC data option byte values(0x0 – 0xFFFF)

Example:

```
/* get the FMC data option byte */
```

```
Uint16_t data = ob_data_get ( );
```

ob_write_protection_get

The description of ob_write_protection_get is shown as below:

Table 3-260. Function ob_write_protection_get

Function name	ob_write_protection_get
Function prototype	uint32_t ob_write_protection_get(void);
Function descriptions	get the FMC option byte write protection
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint32_t	the FMC write protection option byte value(0x0 – 0xFFFFFFFF)

Example:

```
/* get the FMC option byte write protection */
```

```
uint32_t wp = ob_write_protection_get ( );
```

ob_security_protection_flag_get

The description of ob_security_protection_flag_get is shown as below:

Table 3-261. Function ob_security_protection_flag_get

Function name	ob_security_protection_flag_get
Function prototype	FlagStatus ob_security_protection_flag_get(void);
Function descriptions	get the FMC option byte security protection
Precondition	-
The called functions	-
Input parameter{in}	
-	-

Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get the FMC option byte security protection */
```

```
FlagStatus spc = ob_security_protection_flag_get( );
```

fmc_interrupt_enable

The description of fmc_interrupt_enable is shown as below:

Table 3-262. Function fmc_interrupt_enable

Function name	fmc_interrupt_enable
Function prototype	void fmc_interrupt_enable(uint32_t interrupt);
Function descriptions	enable FMC interrupt
Precondition	-
The called functions	-
Input parameter{in}	
interrupt	the FMC interrupt source
FMC_INT_END	FMC end of program interrupt
FMC_INT_ERR	FMC error interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable FMC interrupt */
```

```
fmc_interrupt_enable(FMC_INT_END);
```

fmc_interrupt_disable

The description of fmc_interrupt_disable is shown as below:

Table 3-263. Function fmc_interrupt_disable

Function name	fmc_interrupt_disable
Function prototype	void fmc_interrupt_disable(uint32_t interrupt);
Function descriptions	disable FMC interrupt
Precondition	-
The called functions	-
Input parameter{in}	
interrupt	the FMC interrupt source

<i>FMC_INT_END</i>	FMC end of program interrupt
<i>FMC_INT_ERR</i>	FMC error interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable FMC interrupt */
```

```
fmc_interrupt_disable(FMC_INT_END);
```

fmc_flag_get

The description of fmc_flag_get is shown as below:

Table 3-264. Function fmc_flag_get

Function name	fmc_flag_get
Function prototype	FlagStatus fmc_flag_get(uint32_t flag);
Function descriptions	check flag is set or not
Precondition	-
The called functions	-
Input parameter{in}	
flag	check FMC flag
<i>FMC_FLAG_BUSY</i>	FMC busy flag bit
<i>FMC_FLAG_PGERR</i>	FMC operation error flag bit
<i>FMC_FLAG_PGAERR</i>	FMC program alignment error flag bit
<i>FMC_FLAG_WPERR</i>	FMC erase/program protection error flag bit
<i>FMC_FLAG_END</i>	FMC end of operation flag bit
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get FMC flag */
```

```
FlagStatus flag = fmc_flag_get(FMC_FLAG_END);
```

fmc_flag_clear

The description of fmc_flag_clear is shown as below:

Table 3-265. Function fmc_flag_clear

Function name	fmc_flag_clear
Function prototype	void fmc_flag_clear(uint32_t flag);

Function descriptions	clear the FMC flag
Precondition	-
The called functions	-
Input parameter{in}	
flag	clear FMC flag
<i>FMC_FLAG_PGERR</i>	FMC operation error flag bit
<i>FMC_FLAG_PGAERR</i>	FMC program alignment error flag bit
<i>FMC_FLAG_WPERR</i>	FMC erase/program protection error flag bit
<i>FMC_FLAG_END</i>	FMC end of operation flag bit
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* get FMC flag */
```

```
fmc_flag_clear(FMC_FLAG_END);
```

fmc_interrupt_flag_get

The description of fmc_interrupt_flag_get is shown as below:

Table 3-266. Function fmc_interrupt_flag_get

Function name	fmc_interrupt_flag_get
Function prototype	FlagStatus fmc_interrupt_flag_get(fmc_interrupt_flag_enum flag);
Function descriptions	get FMC interrupt flag state
Precondition	-
The called functions	-
Input parameter{in}	
flag	FMC flag
<i>FMC_INT_FLAG_PGE RR</i>	FMC operation error flag bit
<i>FMC_INT_FLAG_PGA ERR</i>	FMC program alignment error flag bit
<i>FMC_INT_FLAG_WPE RR</i>	FMC erase/program protection error flag bit
<i>FMC_INT_FLAG_END</i>	FMC end of operation flag bit
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get FMC flag */
```

```
FlagStatus flag = fmc_interrupt_flag_get (FMC_INT_FLAG_PGERR);
```

fmc_interrupt_flag_clear

The description of fmc_interrupt_flag_get is shown as below:

Table 3-267. Function fmc_interrupt_flag_clear

Function name	fmc_interrupt_flag_clear
Function prototype	FlagStatus fmc_interrupt_flag_clear (fmc_interrupt_flag_enum flag);
Function descriptions	clear FMC interrupt flag state
Precondition	-
The called functions	-
Input parameter{in}	
flag	clear FMC flag
<i>FMC_INT_FLAG_PGE</i> <i>RR</i>	FMC operation error flag bit
<i>FMC_INT_FLAG_PGA</i> <i>ERR</i>	FMC program alignment error flag bit
<i>FMC_INT_FLAG_WPE</i> <i>RR</i>	FMC erase/program protection error flag bit
<i>FMC_INT_FLAG_END</i>	FMC end of operation flag bit
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear FMC flag */
```

```
fmc_interrupt_flag_get (FMC_INT_FLAG_PGERR);
```

fmc_state_get

The description of fmc_state_get is shown as below:

Table 3-268. Function fmc_state_get

Function name	fmc_state_get
Function prototype	fmc_state_enum fmc_state_get(void);
Function descriptions	get the FMC state
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	

-	-
Return value	
fmc_state_enum	state of FMC

Example:

```
/* get the FMC state */
```

```
fmc_state_enum state = fmc_state_get( );
```

fmc_ready_wait

The description of fmc_ready_wait is shown as below:

Table 3-269. Function fmc_ready_wait

Function name	fmc_ready_wait
Function prototype	fmc_state_enum fmc_ready_wait(uint32_t timeout);
Function descriptions	check whether FMC is ready or not
Precondition	-
The called functions	fmc_state_get()
Input parameter{in}	
timeout	count of loop
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC

Example:

```
/* check whether FMC is ready or not */
```

```
fmc_ready_wait (0x00001000 );
```

3.13. FWDGT

The free watchdog timer (FWDGT) is a hardware timing circuitry that can be used to detect system failures due to software malfunctions. It's suitable for the situation that requires an independent environment and lower timing accuracy. The FWDGT registers are listed in chapter [3.13.1](#) the FWDGT firmware functions are introduced in chapter [3.13.2](#).

3.13.1. Descriptions of Peripheral registers

FWDGT registers are listed in the table shown as below:

Table 3-270. FWDGT Registers

Registers	Descriptions
FWDGT_CTL	Control register

Registers	Descriptions
FWDGT_PSC	Prescaler register
FWDGT_RLD	Reload register
FWDGT_STAT	Status register

3.13.2. Descriptions of Peripheral functions

FWDGT firmware functions are listed in the table shown as below:

Table 3-271. FWDGT firmware function

Function name	Function description
<code>fwdgt_write_enable</code>	enable write access to FWDGT_PSC and FWDGT_RLD
<code>fwdgt_write_disable</code>	disable write access to FWDGT_PSC and FWDGT_RLD
<code>fwdgt_enable</code>	start the free watchdog timer counter
<code>fwdgt_prescaler_value_config</code>	configure the free watchdog timer counter prescaler value
<code>fwdgt_reload_value_config</code>	configure the free watchdog timer counter reload value
<code>fwdgt_counter_reload</code>	reload the counter of FWDGT
<code>fwdgt_config</code>	configure counter reload value, and prescaler divider value
<code>fwdgt_flag_get</code>	get flag state of FWDGT

`fwdgt_write_enable`

The description of `fwdgt_write_enable` is shown as below:

Table 3-272. Function `fwdgt_write_enable`

Function name	<code>fwdgt_write_enable</code>
Function prototype	<code>void fwdgt_write_enable(void);</code>
Function descriptions	enable write access to FWDGT_PSC and FWDGT_RLD
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable write access to FWDGT_PSC and FWDGT_RLD */
fwdgt_write_enable ( );
```

`fwdgt_write_disable`

The description of `fwdgt_write_disable` is shown as below:

Table 3-273. Function fwdgt_write_disable

Function name	fwdgt_write_disable
Function prototype	void fwdgt_write_disable(void);
Function descriptions	disable write access to FWDGT_PSC and FWDGT_RLD
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable write access to FWDGT_PSC and FWDGT_RLD */
fwdgt_write_disable ( );
```

fwdgt_enable

The description of fwdgt_enable is shown as below:

Table 3-274. Function fwdgt_enable

Function name	fwdgt_enable
Function prototype	void fwdgt_enable(void);
Function descriptions	start the free watchdog timer counter
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* start the free watchdog timer counter */
fwdgt_enable ( );
```

fwdgt_prescaler_value_config

The description of fwdgt_prescaler_value_config is shown as below:

Table 3-275. Function fwdgt_prescaler_value_config

Function name	fwdgt_prescaler_value_config
----------------------	------------------------------

Function prototype	ErrStatus fwdgt_prescaler_value_config(uint16_t prescaler_value);
Function descriptions	configure the free watchdog timer counter prescaler value
Precondition	-
Input parameter{in}	
prescaler_value	specify prescaler value
<i>FWDGT_PSC_DIV4</i>	FWDGT prescaler set to 4
<i>FWDGT_PSC_DIV8</i>	FWDGT prescaler set to 8
<i>FWDGT_PSC_DIV16</i>	FWDGT prescaler set to 16
<i>FWDGT_PSC_DIV32</i>	FWDGT prescaler set to 32
<i>FWDGT_PSC_DIV64</i>	FWDGT prescaler set to 64
<i>FWDGT_PSC_DIV128</i>	FWDGT prescaler set to 128
<i>FWDGT_PSC_DIV256</i>	FWDGT prescaler set to 256
Output parameter{out}	
-	-
Return value	
ErrStatus	ERROR / SUCCESS

Example:

```
/* set FWDGT prescaler to 256 */
```

```
ErrStatus flag;
```

```
flag = fwdgt_prescaler_value_config (FWDGT_PSC_DIV256);
```

fwdgt_reload_value_config

The description of fwdgt_reload_value_config is shown as below:

Table 3-276. Function fwdgt_reload_value_config

Function name	fwdgt_reload_value_config
Function prototype	ErrStatus fwdgt_reload_value_config(uint16_t reload_value);
Function descriptions	configure the free watchdog timer counter reload value
Precondition	-
Input parameter{in}	
reload_value	reload_value: specify window value(0x0000 - 0x0FFF)
Output parameter{out}	
-	-
Return value	
ErrStatus	ERROR / SUCCESS

Example:

```
/* set FWDGT reload value to 0x0FFF */
```

```
ErrStatus flag;
```

```
flag = fwdgt_reload_value_config (0x0FFF);
```

fwdgt_counter_reload

The description of fwdgt_counter_reload is shown as below:

Table 3-277. Function fwdgt_counter_reload

Function name	fwdgt_counter_reload
Function prototype	void fwdgt_counter_reload(void);
Function descriptions	reload the counter of FWDGT
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reload FWDGT counter */
```

```
fwdgt_counter_reload ( );
```

fwdgt_config

The description of fwdgt_config is shown as below:

Table 3-278. Function fwdgt_config

Function name	fwdgt_config
Function prototype	ErrStatus fwdgt_config(uint16_t reload_value, uint8_t prescaler_div);
Function descriptions	configure counter reload value, and prescaler divider value
Precondition	-
The called functions	-
Input parameter{in}	
reload_value	specify reload value(0x0000 - 0x0FFF)-
Input parameter{in}	
prescaler_div	FWDGT prescaler value-
<i>FWDGT_PSC_DIV4</i>	FWDGT prescaler set to 4
<i>FWDGT_PSC_DIV8</i>	FWDGT prescaler set to 8
<i>FWDGT_PSC_DIV16</i>	FWDGT prescaler set to 16
<i>FWDGT_PSC_DIV32</i>	FWDGT prescaler set to 32
<i>FWDGT_PSC_DIV64</i>	FWDGT prescaler set to 64
<i>FWDGT_PSC_DIV128</i>	FWDGT prescaler set to 128
<i>FWDGT_PSC_DIV256</i>	FWDGT prescaler set to 256
Output parameter{out}	
-	-

Return value	
ErrStatus	ERROR or SUCCESS

Example:

```
/* configure FWDGT counter clock: 40KHz(IRC40K) / 64 = 0.625 KHz */
```

```
fwdgt_config(2*500, FWDGT_PSC_DIV64);
```

fwdgt_flag_get

The description of fwdgt_flag_get is shown as below:

Table 3-279. Function fwdgt_flag_get fwdgt_write_disable

Function name	fwdgt_flag_get
Function prototype	FlagStatus fwdgt_flag_get(uint16_t flag);
Function descriptions	get flag state of FWDGT
Precondition	-
The called functions	-
Input parameter{in}	
flag	flag to get
<i>FWDGT_FLAG_PUD</i>	a write operation to FWDGT_PSC register is on going
<i>FWDGT_FLAG_RUD</i>	a write operation to FWDGT_RLD register is on going
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* test if a prescaler value update is on going */
```

```
FlagStatus status;
```

```
status = fwdgt_flag_get (FWDGT_FLAG_PUD);
```

```
if(status == RESET)
```

```
{
```

```
...
```

```
}else
```

```
{
```

```
...
```

```
}
```

3.14. GPIO

GPIO is used to implement logic input/output functions for the devices. The GPIO registers are listed in chapter [3.13.1](#), the GPIO firmware functions are introduced in chapter [3.13.2](#).

3.14.1. Descriptions of Peripheral registers

GPIO registers are listed in the table shown as below:

Table 3-280. GPIO Registers

Registers	Descriptions
GPIOx_CTL0	Port control register 0
GPIOx_CTL1	Port control register 1
GPIOx_ISTAT	Port input status register
GPIOx_OCTL	Port output control register
GPIOx_BOP	Port bit operate register
GPIOx_BC	Port bit clear register
GPIOx_LOCK	Port configuration lock register
GPIOx_SPD	Port bit speed register
AFIO_EC	Event control register
AFIO_PCF0	AFIO port configuration register 0
AFIO_EXTISS0	EXTI sources selection register 0
AFIO_EXTISS1	EXTI sources selection register 1
AFIO_EXTISS2	EXTI sources selection register 2
AFIO_EXTISS3	EXTI sources selection register 3
AFIO_PCF1	AFIO port configuration register 1
AFIO_CPSCTL	IO compensation control register

3.14.2. Descriptions of Peripheral functions

GPIO firmware functions are listed in the table shown as below:

Table 3-281. GPIO firmware function

Function name	Function description
gpio_deinit	reset GPIO port
gpio_afio_deinit	reset alternate function I/O(AFIO)
gpio_init	GPIO parameter initialization
gpio_bit_set	set GPIO pin
gpio_bit_reset	reset GPIO pin
gpio_bit_write	write data to the specified GPIO pin
gpio_port_write	write data to the specified GPIO port
gpio_input_bit_get	get GPIO pin input status
gpio_input_port_get	get GPIO port input status

Function name	Function description
gpio_output_bit_get	get GPIO pin output status
gpio_output_port_get	get GPIO port output status
gpio_pin_remap_config	configure GPIO pin remap
gpio_exti_source_select	select GPIO pin exti sources
gpio_event_output_config	configure GPIO pin event output
gpio_event_output_enable	enable GPIO pin event output
gpio_event_output_disable	disable GPIO pin event output
gpio_pin_lock	lock GPIO pin
gpio_compensation_config	configure the I/O compensation cell
gpio_compensation_flag_get	check the I/O compensation cell is ready or not

gpio_deinit

The description of gpio_deinit is shown as below:

Table 3-282. Function gpio_deinit

Function name	gpio_deinit
Function prototype	void gpio_deinit(uint32_t gpio_periph);
Function descriptions	reset GPIO port
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Input parameter{in}	
gpio_periph	GPIO port
GPIOx	GPIOx(x = A,B,C,D,E)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset GPIOA */
gpio_deinit (GPIOA);
```

gpio_afio_deinit

The description of gpio_afio_deinit is shown as below:

Table 3-283. Function gpio_afio_deinit

Function name	gpio_afio_deinit
Function prototype	void gpio_afio_deinit(void);
Function descriptions	reset alternate function I/O(AFIO)
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable

Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset alternate function */
```

```
gpio_afio_deinit();
```

gpio_init

The description of gpio_init is shown as below:

Table 3-284. Function gpio_init

Function name	gpio_init
Function prototype	void gpio_init(uint32_t gpio_periph, uint32_t mode, uint32_t speed, uint32_t pin);
Function descriptions	GPIO parameter initialization
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,D,E)
Input parameter{in}	
gpio_mode	gpio pin mode
<i>GPIO_MODE_AIN</i>	analog input mode
<i>GPIO_MODE_IN_FLOATING</i>	floating input mode
<i>GPIO_MODE_IPD</i>	pull-down input mode
<i>GPIO_MODE_IPU</i>	pull-up input mode
<i>GPIO_MODE_OUT_OD</i>	GPIO output with open-drain
<i>GPIO_MODE_OUT_PP</i>	GPIO output with push-pull
<i>GPIO_MODE_AF_OD</i>	AFIO output with open-drain
<i>GPIO_MODE_AF_PP</i>	AFIO output with push-pull
Input parameter{in}	
speed	gpio output max speed value
<i>GPIO_OSPEED_10MHZ</i>	output max speed 10MHz
<i>GPIO_OSPEED_2MHZ</i>	output max speed 2MHz
<i>GPIO_OSPEED_50MHZ</i>	output max speed 50MHz

<i>Z</i>	
<i>GPIO_OSPEED_MAX</i>	output max speed more than 50MHz
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* config PA0 as analog input mode */
```

```
gpio_init (GPIOA, GPIO_MODE_AIN, GPIO_OSPEED_50MHZ, GPIO_PIN_0);
```

gpio_bit_set

The description of gpio_bit_set is shown as below:

Table 3-285. Function gpio_bit_set

Function name	gpio_bit_set
Function prototype	void gpio_bit_set(uint32_t gpio_periph,uint32_t pin);
Function descriptions	set GPIO pin
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,D,E)
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set PA0 */
```

```
gpio_bit_set (GPIOA, GPIO_PIN_0);
```


gpio_bit_reset

The description of gpio_bit_reset is shown as below:

Table 3-286. Function gpio_bit_reset

Function name	gpio_bit_reset
Function prototype	void gpio_bit_reset(uint32_t gpio_periph, uint32_t pin);
Function descriptions	reset GPIO pin
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,D,E)
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset PA0 */
```

```
gpio_bit_set(GPIOA, GPIO_PIN_0);
```

gpio_bit_write

The description of gpio_bit_write is shown as below:

Table 3-287. Function gpio_bit_write

Function name	gpio_bit_write
Function prototype	void gpio_bit_write(uint32_t gpio_periph, uint32_t pin, bit_status bit_value);
Function descriptions	write data to the specified GPIO pin
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,D,E)
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Input parameter{in}	

bit_value	SET or RESET
<i>RESET</i>	clear the port pin
<i>SET</i>	set the port pin
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* write 1 to PA0 */
```

```
gpio_bit_write (GPIOA, GPIO_PIN_0, SET);
```

gpio_port_write

The description of gpio_port_write is shown as below:

Table 3-288. Function gpio_port_write

Function name	gpio_port_write
Function prototype	void gpio_port_write(uint32_t gpio_periph,uint16_t data);
Function descriptions	write data to the specified GPIO port
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,D,E)
Input parameter{in}	
data	specify the value to be written to the port output data register
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/*write 1010 0101 to Port A */
```

```
gpio_port_write (GPIOA, 0xA5);
```

gpio_input_bit_get

The description of gpio_input_bit_get is shown as below:

Table 3-289. Function gpio_input_bit_get

Function name	gpio_input_bit_get
Function prototype	FlagStatus gpio_input_bit_get(uint32_t gpio_periph,uint32_t pin);
Function descriptions	get GPIO pin input status

Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,D,E)
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Output parameter{out}	
-	-
Return value	
FlagStatus	SET / RESET

Example:

```
/* get status of PA0 */
```

```
FlagStatus bit_state;
```

```
bit_state = gpio_input_bit_get (GPIOA, GPIO_PIN_0);
```

gpio_input_port_get

The description of gpio_input_port_get is shown as below:

Table 3-290. Function gpio_input_port_get

Function name	gpio_input_port_get
Function prototype	uint16_t gpio_input_port_get(uint32_t gpio_periph);
Function descriptions	get GPIO port input status
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,D,E)
Output parameter{out}	
-	-
Return value	
uint16_t	0x00-0xFF

Example:

```
/* get input value of Port A */
```

```
uint16_t port_state;
```

```
port_state = gpio_input_bit_get (GPIOA);
```

gpio_output_bit_get

The description of gpio_output_bit_get is shown as below:

Table 3-291. Function gpio_output_bit_get

Function name	gpio_output_bit_get
Function prototype	FlagStatus gpio_output_bit_get(uint32_t gpio_periph,uint32_t pin);
Function descriptions	get GPIO pin output status
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,D,E)
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Output parameter{out}	
-	-
Return value	
FlagStatus	SET / RESET

Example:

```
/* get output status of PA0 */
```

```
FlagStatus bit_state;
```

```
bit_state = gpio_output_bit_get (GPIOA, GPIO_PIN_0);
```

gpio_output_port_get

The description of gpio_output_port_get is shown as below:

Table 3-292. Function gpio_output_port_get

Function name	gpio_output_port_get
Function prototype	uint16_t gpio_output_port_get(uint32_t gpio_periph);
Function descriptions	get GPIO port output status
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,D,E)
Output parameter{out}	
-	-
Return value	

Uint16_t	0x00-0xFF
-----------------	-----------

Example:

```
/* get output value of Port A */

uint16_t port_state;

port_state = gpio_output_port_get (GPIOA);
```

gpio_pin_remap_config

The description of gpio_pin_remap_config is shown as below:

Table 3-293. Function gpio_pin_remap_config

Function name	gpio_pin_remap_config
Function prototype	void gpio_pin_remap_config(uint32_t remap, ControlStatus newvalue);
Function descriptions	configure GPIO pin remap
Precondition	-
The called functions	-
Input parameter{in}	
gpio_remap	select the pin to remap
GPIO_SPI0_REMAP	SPI0 remapping
GPIO_I2C0_REMAP	I2C0 remapping
GPIO_USART0_REMAP	USART0 remapping
GPIO_USART1_REMAP	USART1 remapping
GPIO_USART2_PARTIAL_REMAP	USART2 partial remapping
GPIO_USART2_FULL_REMAP	USART2 full remapping
GPIO_TIMER0_PARTIAL_REMAP	TIMER0 partial remapping
GPIO_TIMER0_FULL_REMAP	TIMER0 full remapping
GPIO_TIMER1_PARTIAL_REMAP1	TIMER1 partial remapping
GPIO_TIMER1_PARTIAL_REMAP2	TIMER1 partial remapping
GPIO_TIMER1_FULL_REMAP	TIMER1 full remapping
GPIO_TIMER2_PARTIAL_REMAP	TIMER2 partial remapping
GPIO_TIMER2_FULL_REMAP	TIMER2 full remapping

<i>GPIO_TIMER3_REMAP</i>	TIMER3 remapping
<i>GPIO_CAN0_PARTIAL_REMAP</i>	CAN0 partial remapping
<i>GPIO_CAN0_FULL_REMAP</i>	CAN0 full remapping
<i>GPIO_PD01_REMAP</i>	PD01 remapping
<i>GPIO_ADC0_ETRGRTR_REMAP</i>	ADC0 external trigger routine conversion remapping
<i>GPIO_ADC1_ETRGRTR_REMAP</i>	ADC1 external trigger routine conversion remapping
<i>GPIO_TIMER4CH3_IREMAP</i>	TIMER4 channel3 internal remapping
<i>GPIO_CAN1_REMAP</i>	CAN1 remapping
<i>GPIO_SWJ_NONJTRST_REMAP</i>	full SWJ(JTAG-DP + SW-DP),but without NJTRST
<i>GPIO_SWJ_SWDPENABLE_REMAP</i>	JTAG-DP disabled and SW-DP enabled
<i>GPIO_SWJ_DISABLE_REMAP</i>	JTAG-DP disabled and SW-DP disabled
<i>GPIO_SPI2_REMAP</i>	SPI2 remapping
<i>GPIO_TIMER1ITR0_REMAP</i>	TIMER1 internal trigger 0 remapping
<i>GPIO_TIMER8_REMAP</i>	TIMER8 remapping
<i>GPIO_EXMC_NADV_REMAP</i>	EXMC_NADV connect/disconnect
<i>GPIO_CTC_REMAP0</i>	CTC remapping(PD15)
Input parameter{in}	
newvalue	ENABLE / DISABLE
<i>ENABLE</i>	
<i>DISABLE</i>	
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/*enable SPI0 remapping */
```

```
gpio_pin_remap_config (GPIO_SPI0_REMAP, ENABLE);
```

gpio_exti_source_select

The description of gpio_exti_source_select is shown as below:

Table 3-294. Function gpio_exti_source_select

Function name	gpio_exti_source_select
Function prototype	void gpio_exti_source_select(uint8_t output_port, uint8_t output_pin);
Function descriptions	select GPIO pin exti sources
Precondition	-
The called functions	-
Input parameter{in}	
gpio_outputport	gpio event output port
GPIO_PORT_SOURCE_GPIOx	output port source (x= A,B,C,D,E)
Input parameter{in}	
gpio_outputpin	gpio event output pin
GPIO_PIN_SOURCE_x	Pin number(x=0..15)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* config PA0 as EXTI source */
```

```
gpio_exti_source_select (GPIO_PORT_SOURCE_GPIOA, GPIO_PIN_SOURCE_0);
```

gpio_event_output_config

The description of gpio_event_output_config is shown as below:

Table 3-295. Function gpio_event_output_config

Function name	gpio_event_output_config
Function prototype	void gpio_event_output_config(uint8_t output_port, uint8_t output_pin);
Function descriptions	configure GPIO pin event output
Precondition	-
The called functions	-
Input parameter{in}	
gpio_outputport	gpio event output port
GPIO_EVENT_PORT_GPIOx	event output port x (x= A,B,C,D,E)
Input parameter{in}	
gpio_outputpin	gpio event output pin
GPIO_EVENT_PIN_x	Pin number (x=0..15)
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* Config PA0 as the output of event */
```

```
gpio_event_output_config (GPIO_EVENT_PORT_GPIOA, GPIO_EVENT_PIN_0);
```

gpio_event_output_enable

The description of gpio_event_output_enable is shown as below:

Table 3-296. Function gpio_event_output_enable

Function name	gpio_event_output_enable
Function prototype	void gpio_event_output_enable(void);
Function descriptions	enable GPIO pin event output
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable GPIO pin event output */
```

```
gpio_event_output_enable(void);
```

gpio_event_output_disable

The description of gpio_event_output_disable is shown as below:

Table 3-297. Function gpio_event_output_disable

Function name	gpio_event_output_disable
Function prototype	void gpio_event_output_disable(void);
Function descriptions	disable GPIO pin event output
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	

Example:

```
/* disable GPIO pin event output */

gpio_event_output_disable(void);
```

gpio_pin_lock

The description of gpio_pin_lock is shown as below:

Table 3-298. Function gpio_pin_lock

Function name	gpio_pin_lock
Function prototype	void gpio_pin_lock(uint32_t gpio_periph, uint32_t pin);
Function descriptions	lock GPIO pin
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,D,E)
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* lock PA0 */

gpio_pin_lock (GPIOA, GPIO_PIN_0);
```

gpio_compensation_config

The description of gpio_compensation_config is shown as below:

Table 3-299. Function gpio_compensation_config

Function name	gpio_compensation_config
Function prototype	void gpio_compensation_config(uint32_t compensation);
Function descriptions	configure the I/O compensation cell
Precondition	-
The called functions	-
Input parameter{in}	
compensation	specifies the I/O compensation cell mode

<code>GPIO_COMPENSATION_ENABLE</code>	I/O compensation cell is enabled
<code>GPIO_COMPENSATION_DISABLE</code>	I/O compensation cell is disabled
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enabled I/O compensation cell */
```

```
gpio_compensation_config (GPIO_COMPENSATION_ENABLE);
```

gpio_compensation_flag_get

The description of `gpio_compensation_flag_get` is shown as below:

Table 3-300. Function `gpio_compensation_flag_get`

Function name	<code>gpio_compensation_flag_get</code>
Function prototype	<code>FlagStatus gpio_compensation_flag_get(void);</code>
Function descriptions	check the I/O compensation cell is ready or not
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* check the I/O compensation cell state */
```

```
FlagStatus cell_state;
```

```
cell_state = gpio_compensation_flag_get (void);
```

3.15. I2C

The I2C (inter-integrated circuit) module provides an I2C interface which is an industry standard two-line serial interface for MCU to communicate with external I2C interface. The I2C registers are listed in chapter [3.15.1](#), the I2C firmware functions are introduced in chapter [3.15.2](#)

3.15.1. Descriptions of Peripheral registers

I2C registers are listed in the table shown as below:

Table 3-301. I2C Registers

Registers	Descriptions
I2C_CTL0	Control register 0
I2C_CTL1	Control register 1
I2C_SADDR0	Slave address register 0
I2C_SADDR1	Slave address register 1
I2C_DATA	Transfer buffer register
I2C_STAT0	Transfer status register 0
I2C_STAT1	Transfer status register 1
I2C_CKCFG	Clock configure register
I2C_RT	Rise time register
I2C_SAMCS	SAM control and status register
I2C_FMPCFG	Fast mode plus configure register

3.15.2. Descriptions of Peripheral functions

I2C firmware functions are listed in the table shown as below:

Table 3-302. I2C firmware function

Function name	Function description
i2c_deinit	reset I2C
i2c_clock_config	configure I2C clock
i2c_mode_addr_config	configure I2C address
i2c_smbus_type_config	select SMBus type
i2c_ack_config	whether or not to send an ACK
i2c_ackpos_config	configure I2C POAP position
i2c_master_addressing	master sends slave address
i2c_dualaddr_enable	enable dual-address mode
i2c_dualaddr_disable	disable dual-address mode
i2c_enable	enable I2C
i2c_disable	disable I2C
i2c_start_on_bus	generate a START condition on I2C bus
i2c_stop_on_bus	generate a STOP condition on I2C bus
i2c_data_transmit	I2C transmit data function
i2c_data_receive	I2C receive data function
i2c_dma_config	configure I2C DMA mode
i2c_dma_last_transfer_config	configure whether next DMA EOT is DMA last transfer or not
i2c_stretch_scl_low_config	whether to stretch SCL low when data is not ready in slave mode

Function name	Function description
i2c_slave_response_to_gcall_config	whether or not to response to a general call
i2c_software_reset_config	configure software reset of I2C
i2c_pec_config	configure I2C PEC calculation
i2c_pec_transfer_config	configure whether to transfer PEC value
i2c_pec_value_get	get packet error checking value
i2c_smbus_alert_config	configure I2C alert through SMBA pin
i2c_smbus_arp_config	configure I2C ARP protocol in SMBus
i2c_sam_enable	enable SAM_V interface
i2c_sam_disable	disable SAM_V interface
i2c_sam_timeout_enable	enable SAM_V interface timeout detect
i2c_sam_timeout_disable	disable SAM_V interface timeout detect
i2c_flag_get	get I2C flag status
i2c_flag_clear	clear I2C flag status
i2c_interrupt_enable	enable I2C interrupt
i2c_interrupt_disable	disable I2C interrupt
i2c_interrupt_flag_get	get I2C interrupt flag status
i2c_interrupt_flag_clear	clear I2C interrupt flag status

Enum i2c_flag_enum

Table 3-303. Enum i2c_flag_enum

Member name	Function description
I2C_FLAG_SBSEND	start condition sent out in master mode
I2C_FLAG_ADDSEND	address is sent in master mode or received and matches in slave mode
I2C_FLAG_BTC	byte transmission finishes
I2C_FLAG_ADD10SEND	header of 10-bit address is sent in master mode
I2C_FLAG_STPDET	stop condition detected in slave mode
I2C_FLAG_RBNE	I2C_DATA is not empty during receiving
I2C_FLAG_TBE	I2C_DATA is empty during transmitting
I2C_FLAG_BERR	a bus error occurs indication a unexpected start or stop condition on I2C bus
I2C_FLAG_LOSTARB	arbitration lost in master mode
I2C_FLAG_AERR	acknowledge error
I2C_FLAG_OUERR	over-run or under-run situation occurs in slave mode
I2C_FLAG_PECERR	PEC error when receiving data
I2C_FLAG_SMBTO	timeout signal in SMBus mode
I2C_FLAG_SMBALT	SMBus alert status
I2C_FLAG_MASTER	a flag indicating whether I2C block is in master or slave mode
I2C_FLAG_I2CBSY	busy flag
I2C_FLAG_TR	whether the I2C is a transmitter or a receiver
I2C_FLAG_RXGC	general call address (00h) received

Member name	Function description
I2C_FLAG_DEFSMB	default address of SMBus device
I2C_FLAG_HSTSMB	SMBus host header detected in slave mode
I2C_FLAG_DUMOD	dual flag in slave mode indicating which address is matched in dual-address mode
I2C_FLAG_TFF	txframe fall flag
I2C_FLAG_TFR	txframe rise flag
I2C_FLAG_RFF	rxframe fall flag
I2C_FLAG_RFR	rxframe rise flag

Enum i2c_interrupt_flag_enum

Table 3-304. Enum i2c_interrupt_flag_enum

Member name	Function description
I2C_INT_FLAG_SBSEND	start condition sent out in master mode interrupt flag
I2C_INT_FLAG_ADDSEND	address is sent in master mode or received and matches in slave mode interrupt flag
I2C_INT_FLAG_BTC	byte transmission finishes interrupt flag
I2C_INT_FLAG_ADD10SEND	header of 10-bit address is sent in master mode interrupt flag
I2C_INT_FLAG_STPDET	stop condition detected in slave mode interrupt flag
I2C_INT_FLAG_RBNE	I2C_DATA is not empty during receiving interrupt flag
I2C_INT_FLAG_TBE	I2C_DATA is empty during transmitting interrupt flag
I2C_INT_FLAG_BERR	a bus error occurs indication a unexpected start or stop condition on I2C bus interrupt flag
I2C_INT_FLAG_LOSTARB	arbitration lost in master mode interrupt flag
I2C_INT_FLAG_AERR	acknowledge error interrupt flag
I2C_INT_FLAG_OUERR	over-run or under-run situation occurs in slave mode interrupt flag
I2C_INT_FLAG_PECERR	PEC error when receiving data interrupt flag
I2C_INT_FLAG_SMBTO	timeout signal in SMBus mode interrupt flag
I2C_INT_FLAG_SMBALT	SMBus alert status interrupt flag
I2C_INT_FLAG_TFF	txframe fall interrupt flag
I2C_INT_FLAG_TFR	txframe rise interrupt flag
I2C_INT_FLAG_RFF	rxframe fall interrupt flag
I2C_INT_FLAG_RFR	rxframe rise interrupt flag

Enum i2c_interrupt_enum

Table 3-305. Enum i2c_interrupt_enum

Member name	Function description
I2C_INT_ERR	error interrupt
I2C_INT_EV	event interrupt
I2C_INT_BUF	buffer interrupt
I2C_INT_TFF	txframe fall interrupt

Member name	Function description
I2C_INT_TFR	txframe rise interrupt
I2C_INT_RFF	rxframe fall interrupt
I2C_INT_RFR	rxframe rise interrupt

i2c_deinit

The description of i2c_deinit is shown as below:

Table 3-306. Function i2c_deinit

Function name	i2c_deinit
Function prototype	void i2c_deinit(uint32_t i2c_periph);
Function descriptions	reset I2C
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset I2C0 */
```

```
i2c_deinit (I2C0);
```

i2c_clock_config

The description of i2c_clock_config is shown as below:

Table 3-307. Function i2c_clock_config

Function name	i2c_clock_config
Function prototype	void i2c_clock_config(uint32_t i2c_periph, uint32_t clk speed, uint32_t duty cyc);
Function descriptions	configure I2C clock
Precondition	-
The called functions	rcu_clock_freq_get
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
clk speed	i2c clock speed
Input parameter{in}	

dutycyc	duty cycle in fast mode
<i>I2C_DTCY_2</i>	T_low/T_high=2
<i>I2C_DTCY_16_9</i>	T_low/T_high=16/9
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure I2C0 clock speed as 100KHz */
```

```
i2c_clock_config(I2C0, 100000, I2C_DTCY_2);
```

i2c_mode_addr_config

The description of i2c_mode_addr_config is shown as below:

Table 3-308. Function i2c_mode_addr_config

Function name	i2c_mode_addr_config
Function prototype	void i2c_mode_addr_config(uint32_t i2c_periph, uint32_t mode, uint32_t addformat, uint32_t addr);
Function descriptions	configure I2C address
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
mode	I2C mode select
<i>I2C_I2CMODE_ENABLER</i>	I2C mode
<i>I2C_SMBUSMODE_ENABLED</i>	SMBus mode
Input parameter{in}	
addformat	7bits or 10bits
<i>I2C_ADDFORMAT_7BITS</i>	address format is 7 bits
<i>I2C_ADDFORMAT_10BITS</i>	address format is 10 bits
Input parameter{in}	
addr	I2C address
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* configure I2C0 address as 0x82, using 7 bits */
```

```
i2c_mode_addr_config(I2C0, I2C_I2CMODE_ENABLE, I2C_ADDFORMAT_7BITS, 0x82);
```

i2c_smbus_type_config

The description of i2c_smbus_type_config is shown as below:

Table 3-309. Function i2c_smbus_type_config

Function name	i2c_smbus_type_config
Function prototype	void i2c_smbus_type_config(uint32_t i2c_periph, uint32_t type);
Function descriptions	select SMBus type
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
type	Device or host
<i>I2C_SMBUS_DEVICE</i>	SMBus mode device type
<i>I2C_SMBUS_HOST</i>	SMBus mode host type
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* config I2C0 as SMBUS host type*/
```

```
i2c_smbus_type_config (I2C0, I2C_SMBUS_HOST);
```

i2c_ack_config

The description of i2c_ack_config is shown as below:

Table 3-310. Function i2c_ack_config

Function name	i2c_ack_config
Function prototype	void i2c_ack_config(uint32_t i2c_periph, uint32_t ack);
Function descriptions	whether or not to send an ACK
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral

<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
ack	whether or not to send an ACK
<i>I2C_ACK_ENABLE</i>	ACK will be sent
<i>I2C_ACK_DISABLE</i>	ACK will not be sent
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* I2C0 will send ACK */
```

```
i2c_ack_config (I2C0, I2C_ACK_ENABLE);
```

i2c_ackpos_config

The description of i2c_ackpos_config is shown as below:

Table 3-311. Function i2c_ackpos_config

Function name	i2c_ackpos_config
Function prototype	void i2c_ackpos_config(uint32_t i2c_periph, uint32_t pos);
Function descriptions	configure I2C POAP position
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
pos	ACK position
<i>I2C_ACKPOS_CURRENT</i>	ACKEN bit decides whether or not to send ACK or not for the current byte
<i>I2C_ACKPOS_NEXT</i>	ACKEN bit decides whether or not to send ACK for the next byte
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* The ACK of I2C0 is send for the current frame */
```

```
i2c_ackpos_config (I2C0, I2C_ACKPOS_CURRENT);
```

i2c_master_addressing

The description of i2c_master_addressing is shown as below:

Table 3-312. Function i2c_master_addressing

Function name	i2c_master_addressing
Function prototype	void i2c_master_addressing(uint32_t i2c_periph, uint32_t addr, uint32_t trandirection);
Function descriptions	master sends slave address
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
addr	slave address
Input parameter{in}	
trandirection	transmitter or receiver
<i>I2C_TRANSMITTER</i>	transmitter
<i>I2C_RECEIVER</i>	receiver
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* send slave address to I2C bus and I2C0 act as receiver */
```

```
i2c_master_addressing(I2C0, 0x82, I2C_RECEIVER);
```

i2c_dualaddr_enable

The description of i2c_dualaddr_enable is shown as below:

Table 3-313. Function i2c_dualaddr_enable

Function name	i2c_dualaddr_enable
Function prototype	void i2c_dualaddr_enable(uint32_t i2c_periph, uint32_t addr)
Function descriptions	enable dual-address mode
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
addr	second address in dual-address mode

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable I2C0 dual-address*/
```

```
i2c_dualaddr_enable (I2C0, 0x80);
```

i2c_dualaddr_disable

The description of i2c_dualaddr_disable is shown as below:

Table 3-314. Function i2c_dualaddr_disable

Function name	i2c_dualaddr_disable
Function prototype	void i2c_dualaddr_disable(uint32_t i2c_periph)
Function descriptions	disable dual-address mode
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
I2Cx	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable I2C0 dual-address */
```

```
i2c_dualaddr_disable (I2C0);
```

i2c_enable

The description of i2c_enable is shown as below:

Table 3-315. Function i2c_enable

Function name	i2c_enable
Function prototype	void i2c_enable(uint32_t i2c_periph);
Function descriptions	enable I2C
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
I2Cx	(x=0,1)

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable I2C0 */
i2c_enable (I2C0);
```

i2c_disable

The description of i2c_disable is shown as below:

Table 3-316. Function i2c_disable

Function name	i2c_disable
Function prototype	void i2c_disable(uint32_t i2c_periph);
Function descriptions	disable I2C
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
I2Cx	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable I2C0 */
i2c_disable (I2C0);
```

i2c_start_on_bus

The description of i2c_start_on_bus is shown as below:

Table 3-317. Function i2c_start_on_bus

Function name	i2c_start_on_bus
Function prototype	void i2c_start_on_bus(uint32_t i2c_periph);
Function descriptions	generate a START condition on I2C bus
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
I2Cx	(x=0,1)

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* I2C0 send a start condition to I2C bus */
```

```
i2c_start_on_bus (I2C0);
```

i2c_stop_on_bus

The description of i2c_stop_on_bus is shown as below:

Table 3-318. Function i2c_stop_on_bus

Function name	i2c_stop_on_bus
Function prototype	void i2c_stop_on_bus(uint32_t i2c_periph);
Function descriptions	generate a STOP condition on I2C bus
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
I2Cx	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* I2C0 generate a STOP condition to I2C bus */
```

```
i2c_stop_on_bus (I2C0);
```

i2c_data_transmit

The description of i2c_data_transmit is shown as below:

Table 3-319. Function i2c_data_transmit

Function name	i2c_data_transmit
Function prototype	void i2c_data_transmit(uint32_t i2c_periph, uint8_t data);
Function descriptions	I2C transmit data function
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
I2Cx	(x=0,1)

Input parameter{in}	
data	transmit data
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* I2C0 transmit data */
```

```
i2c_data_transmit (I2C0, 0x80);
```

i2c_data_receive

The description of i2c_data_receive is shown as below:

Table 3-320. Function i2c_data_receive

Function name	i2c_data_receive
Function prototype	uint8_t i2c_data_receive(uint32_t i2c_periph);
Function descriptions	I2C receive data function
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
uint8_t	0x00..0xFF

Example:

```
/* I2C0 receive data */
```

```
uint8_t i2c_receiver;
```

```
i2c_receiver = i2c_data_receive(I2C0);
```

i2c_dma_config

The description of i2c_dma_config is shown as below:

Table 3-321. Function i2c_dma_config

Function name	i2c_dma_config
Function prototype	void i2c_dma_config(uint32_t i2c_periph, uint32_t dmastate);
Function descriptions	configure I2C DMA mode
Precondition	-

The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
dmastate	on or off
<i>I2C_DMA_ON</i>	enable DMA mode
<i>I2C_DMA_OFF</i>	disable DMA mode
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* I2C0 DMA mode enable */
```

```
i2c_dma_config (I2C0, I2C_DMA_ON);
```

i2c_dma_last_transfer_config

The description of i2c_dma_last_transfer_config is shown as below:

Table 3-322. Function i2c_dma_last_transfer_config

Function name	i2c_dma_last_transfer_config
Function prototype	void i2c_dma_last_transfer_config(uint32_t i2c_periph, uint32_t dmalast);
Function descriptions	configure whether next DMA EOT is DMA last transfer or not
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
dmalast	next DMA EOT is the last transfer or not
<i>I2C_DMALST_ON</i>	next DMA EOT is the last transfer
<i>I2C_DMALST_OFF</i>	next DMA EOT is not the last transfer
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* next DMA EOT is the last transfer */
```

```
i2c_dma_last_transfer_config (I2C0, I2C_DMALST_ON);
```

i2c_stretch_scl_low_config

The description of i2c_stretch_scl_low_config is shown as below:

Table 3-323. Function i2c_stretch_scl_low_config

Function name	i2c_stretch_scl_low_config
Function prototype	void i2c_stretch_scl_low_config(uint32_t i2c_periph, uint32_t stretchpara);
Function descriptions	whether to stretch SCL low when data is not ready in slave mode
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
I2Cx	(x=0,1)
Input parameter{in}	
stretchpara	SCL stretching enable or disable
I2C_SCLSTRETCH_ENABLE	enable SCL stretching
I2C_SCLSTRETCH_DISABLE	disable SCL stretching
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* stretch SCL low when data is not ready in slave mode */
```

```
i2c_stretch_scl_low_config (I2C0, I2C_SCLSTRETCH_ENABLE);
```

i2c_slave_response_to_gcall_config

The description of i2c_slave_response_to_gcall_config is shown as below:

Table 3-324. Function i2c_slave_response_to_gcall_config

Function name	i2c_slave_response_to_gcall_config
Function prototype	void i2c_slave_response_to_gcall_config(uint32_t i2c_periph, uint32_t gcallpara);
Function descriptions	whether or not to response to a general call
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
I2Cx	(x=0,1)
Input parameter{in}	
gcallpara	response to a general call or not

<i>I2C_GCEN_ENABLE</i>	slave will response to a general call
<i>I2C_GCEN_DISABLE</i>	slave will not response to a general call
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* I2C0 will response to a general call */
```

```
i2c_slave_response_to_gcall_config (I2C0, I2C_GCEN_ENABLE);
```

i2c_software_reset_config

The description of i2c_software_reset_config is shown as below:

Table 3-325. Function i2c_software_reset_config

Function name	i2c_software_reset_config
Function prototype	void i2c_software_reset_config(uint32_t i2c_periph, uint32_t sreset);
Function descriptions	configure software reset of I2C
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
sreset	reset or not
<i>I2C_SRESET_SET</i>	I2C is under reset
<i>I2C_SRESET_RESET</i>	I2C is not under reset
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* software reset I2C0 */
```

```
i2c_software_reset_config (I2C0, I2C_SRESET_SET);
```

i2c_pec_config

The description of i2c_pec_config is shown as below:

Table 3-326. Function i2c_pec_config

Function name	i2c_pec_config
Function prototype	void i2c_pec_config(uint32_t i2c_periph, uint32_t pecstate);

Function descriptions	configure I2C PEC calculation or not
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
pecstate	on or off
<i>I2C_PEC_ENABLE</i>	PEC calculation on
<i>I2C_PEC_DISABLE</i>	PEC calculation off
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* Enable I2C PEC calculation */
```

```
i2c_pec_config (I2C0, I2C_PEC_ENABLE);
```

i2c_pec_transfer_config

The description of i2c_pec_transfer_enable is shown as below:

Table 3-327. Function i2c_pec_transfer_config

Function name	i2c_pec_transfer_config
Function prototype	void i2c_pec_transfer_config(uint32_t i2c_periph, uint32_t pecpara);
Function descriptions	configure whether to transfer PEC value
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
pecpara	Transfer PEC or not
<i>I2C_PECTRANS_ENA BLE</i>	transfer PEC
<i>I2C_PECTRANS_DISA BLE</i>	not transfer PEC
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* I2C0 transfer PEC */
```

```
i2c_pec_transfer_config (I2C0, I2C_PECTRANS_ENABLE);
```

i2c_pec_value_get

The description of i2c_pec_value_get is shown as below:

Table 3-328. Function i2c_pec_value_get

Function name	i2c_pec_value_get
Function prototype	uint8_t i2c_pec_value_get(uint32_t i2c_periph);
Function descriptions	get packet error checking value
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
uint8_t	PEC value

Example:

```
/* I2C0 get packet error checking value */
```

```
uint8_t pec_value;
```

```
pec_value = i2c_pec_value_get (I2C0);
```

i2c_smbus_alert_config

The description of i2c_smbus_alert_config is shown as below:

Table 3-329. Function i2c_smbus_alert_config

Function name	i2c_smbus_alert_config
Function prototype	void i2c_smbus_alert_config (uint32_t i2c_periph, uint32_t smbuspara);
Function descriptions	configure I2C alert through SMBA pin
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
smbuspara	issue alert through SMBA pin or not
<i>I2C_SALTSEND_ENABLE</i>	issue alert through SMBA pin

<i>I2C_SALTSEND_DISA</i> <i>BLE</i>	not issue alert through SMBA pin
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* I2C0 issue alert through SMBA pin enable*/
```

```
i2c_smbus_alert_config (I2C0, I2C_SALTSEND_ENABLE);
```

i2c_smbus_arp_config

The description of i2c_smbus_arp_config is shown as below:

Table 3-330. Function i2c_smbus_arp_config

Function name	i2c_smbus_arp_config
Function prototype	void i2c_smbus_arp_config(uint32_t i2c_periph, uint32_t arpstate);
Function descriptions	configure I2C ARP protocol in SMBus
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
arpstate	ARP protocol in SMBus switch
<i>I2C_ARP_ENABLE</i>	enable ARP
<i>I2C_ARP_DISABLE</i>	disable ARP
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable I2C0 ARP protocol in SMBus switch */
```

```
i2c_smbus_arp_config (I2C0, I2C_ARP_ENABLE);
```

i2c_sam_enable

The description of i2c_sam_enable is shown as below:

Table 3-331. Function i2c_sam_enable

Function name	i2c_sam_enable
Function prototype	void i2c_sam_enable(uint32_t i2c_periph);

Function descriptions	enable SAM_V interface
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable I2C0 SAM_V interface */
i2c_sam_enable (I2C0);
```

i2c_sam_disable

The description of i2c_sam_disable is shown as below:

Table 3-332. Function i2c_sam_disable

Function name	i2c_sam_disable
Function prototype	void i2c_sam_disable(uint32_t i2c_periph);
Function descriptions	disable SAM_V interface
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable I2C0 SAM_V interface */
i2c_sam_disable (I2C0);
```

i2c_sam_timeout_enable

The description of i2c_sam_timeout_enable is shown as below:

Table 3-333. Function i2c_sam_timeout_enable

Function name	i2c_sam_timeout_enable
Function prototype	void i2c_sam_timeout_enable(uint32_t i2c_periph);

Function descriptions	enable SAM_V interface timeout detect
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable I2C0 SAM_V interface timeout detect */
```

```
i2c_sam_timeout_enable (I2C0);
```

i2c_sam_timeout_disable

The description of i2c_sam_timeout_disable is shown as below:

Table 3-334. Function i2c_sam_timeout_disable

Function name	i2c_sam_timeout_disable
Function prototype	void i2c_sam_timeout_disable(uint32_t i2c_periph);
Function descriptions	disable SAM_V interface timeout detect
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable I2C0 SAM_V interface timeout detect */
```

```
i2c_sam_timeout_disable (I2C0);
```

i2c_flag_get

The description of i2c_flag_get is shown as below:

Table 3-335. Function i2c_flag_get

Function name	i2c_flag_get
Function prototype	FlagStatus i2c_flag_get(uint32_t i2c_periph, i2c_flag_enum flag)

Function descriptions	check I2C flag is set or not
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
flag	specify get which flag
<i>I2C_FLAG_SBSEND</i>	start condition sent out in master mode
<i>I2C_FLAG_ADDSEND</i>	address is sent in master mode or received and matches in slave mode
<i>I2C_FLAG_BTC</i>	byte transmission finishes
<i>I2C_FLAG_ADD10SEND</i>	header of 10-bit address is sent in master mode
<i>I2C_FLAG_STPDET</i>	stop condition detected in slave mode
<i>I2C_FLAG_RBNE</i>	I2C_DATA is not empty during receiving
<i>I2C_FLAG_TBE</i>	I2C_DATA is empty during transmitting
<i>I2C_FLAG_BERR</i>	a bus error occurs indication a unexpected start or stop condition on I2C bus
<i>I2C_FLAG_LOSTARB</i>	arbitration lost in master mode
<i>I2C_FLAG_AERR</i>	acknowledge error
<i>I2C_FLAG_OUERR</i>	over-run or under-run situation occurs in slave mode
<i>I2C_FLAG_PECERR</i>	PEC error when receiving data
<i>I2C_FLAG_SMBTO</i>	timeout signal in SMBus mode
<i>I2C_FLAG_SMBALT</i>	SMBus alert status
<i>I2C_FLAG_MASTER</i>	a flag indicating whether I2C block is in master or slave mode
<i>I2C_FLAG_I2CBSY</i>	busy flag
<i>I2C_FLAG_TR</i>	whether the I2C is a transmitter or a receiver
<i>I2C_FLAG_RXGC</i>	general call address (00h) received
<i>I2C_FLAG_DEFSMB</i>	default address of SMBus device
<i>I2C_FLAG_HSTSMB</i>	SMBus host header detected in slave mode
<i>I2C_FLAG_DUMOD</i>	dual flag in slave mode indicating which address is matched in dual-address mode
<i>I2C_FLAG_TFF</i>	txframe fall flag
<i>I2C_FLAG_TFR</i>	txframe rise flag
<i>I2C_FLAG_RFF</i>	rxframe fall flag
<i>I2C_FLAG_RFR</i>	rxframe rise flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET / RESET

Example:

/* check whether start condition send out */

```
FlagStatus flag_state = RESET;
```

```
flag_state = i2c_flag_get (I2C0, I2C_FLAG_SBSEND);
```

i2c_flag_clear

The description of i2c_flag_clear is shown as below:

Table 3-336. Function i2c_flag_clear

Function name	i2c_flag_clear
Function prototype	void i2c_flag_clear(uint32_t i2c_periph, i2c_flag_enum flag)
Function descriptions	clear I2C flag status
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
flag	flag type
<i>I2C_FLAG_SMBALT</i>	SMBus Alert status
<i>I2C_FLAG_SMBTO</i>	timeout signal in SMBus mode
<i>I2C_FLAG_PECERR</i>	PEC error when receiving data
<i>I2C_FLAG_OUERR</i>	over-run or under-run situation occurs in slave mode
<i>I2C_FLAG_AERR</i>	acknowledge error
<i>I2C_FLAG_LOSTARB</i>	arbitration lost in master mode
<i>I2C_FLAG_BERR</i>	a bus error occurs indication a unexpected start or stop condition on I2C bus
<i>I2C_FLAG_ADDSEND</i>	address is sent in master mode or received and matches in slave mode
<i>I2C_FLAG_TFF</i>	txframe fall flag
<i>I2C_FLAG_TFR</i>	txframe rise flag
<i>I2C_FLAG_RFF</i>	rxframe fall flag
<i>I2C_FLAG_RFR</i>	rxframe rise flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear a bus error flag*/
```

```
i2c_flag_clear (I2C0, I2C_FLAG_BERR);
```

i2c_interrupt_enable

The description of i2c_interrupt_enable is shown as below:

Table 3-337. Function i2c_interrupt_enable

Function name	i2c_interrupt_enable
Function prototype	void i2c_interrupt_enable(uint32_t i2c_periph, i2c_interrupt_enum interrupt);
Function descriptions	enable I2C interrupt
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
interrupt	interrupt type
<i>I2C_INT_ERR</i>	error interrupt
<i>I2C_INT_EV</i>	event interrupt
<i>I2C_INT_BUF</i>	buffer interrupt
<i>I2C_INT_TFF</i>	txframe fall interrupt
<i>I2C_INT_TFR</i>	txframe rise interrupt
<i>I2C_INT_RFF</i>	rxframe fall interrupt
<i>I2C_INT_RFR</i>	rxframe rise interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable I2C0 event interrupt */
```

```
i2c_interrupt_enable (I2C0, I2C_INT_EV);
```

i2c_interrupt_disable

The description of i2c_interrupt_disable is shown as below:

Table 3-338. Function i2c_interrupt_disable

Function name	i2c_interrupt_disable
Function prototype	void i2c_interrupt_disable(uint32_t i2c_periph, i2c_interrupt_enum interrupt);
Function descriptions	disable I2C interrupt
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
inttype	interrupt type

<i>I2C_INT_ERR</i>	error interrupt
<i>I2C_INT_EV</i>	event interrupt
<i>I2C_INT_BUF</i>	buffer interrupt
<i>I2C_INT_TFF</i>	txframe fall interrupt
<i>I2C_INT_TFR</i>	txframe rise interrupt
<i>I2C_INT_RFF</i>	rxframe fall interrupt
<i>I2C_INT_RFR</i>	rxframe rise interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable I2C0 event interrupt */
```

```
i2c_interrupt_disable (I2C0, I2C_INT_EV);
```

i2c_interrupt_flag_get

The description of i2c_interrupt_flag_get is shown as below:

Table 3-339. Function i2c_interrupt_flag_get

Function name	i2c_interrupt_flag_get
Function prototype	FlagStatus i2c_interrupt_flag_get(uint32_t i2c_periph, i2c_interrupt_flag_enum int_flag)
Function descriptions	get I2C interrupt flag
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
int_flag	interrupt flag
<i>I2C_INT_FLAG_SBSE ND</i>	start condition sent out in master mode interrupt flag
<i>I2C_INT_FLAG_ADDS END</i>	address is sent in master mode or received and matches in slave mode interrupt flag
<i>I2C_INT_FLAG_BTC</i>	byte transmission finishes
<i>I2C_INT_FLAG_ADD10 SEND</i>	header of 10-bit address is sent in master mode interrupt flag
<i>I2C_INT_FLAG_STPD ET</i>	stop condition detected in slave mode interrupt flag
<i>I2C_INT_FLAG_RBNE</i>	I2C_DATA is not Empty during receiving interrupt flag
<i>I2C_INT_FLAG_TBE</i>	I2C_DATA is empty during transmitting interrupt flag

<i>I2C_INT_FLAG_BERR</i>	a bus error occurs indication a unexpected start or stop condition on I2C bus interrupt flag
<i>I2C_INT_FLAG_LOSTARB</i>	arbitration lost in master mode interrupt flag
<i>I2C_INT_FLAG_AERR</i>	acknowledge error interrupt flag
<i>I2C_INT_FLAG_OUER</i> <i>R</i>	over-run or under-run situation occurs in slave mode interrupt flag
<i>I2C_INT_FLAG_PECERR</i> <i>RR</i>	PEC error when receiving data interrupt flag
<i>I2C_INT_FLAG_SMBTO</i> <i>O</i>	timeout signal in SMBus mode interrupt flag
<i>I2C_INT_FLAG_SMBAL</i> <i>LT</i>	SMBus alert status interrupt flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET / RESET

Example:

```
/* check the byte transmission finishes interrupt flag is set or not*/
```

```
FlagStatus flag_state = RESET;
```

```
flag_state = i2c_interrupt_flag_get (I2C0, I2C_INT_FLAG_BTC);
```

i2c_interrupt_flag_clear

The description of i2c_interrupt_flag_clear is shown as below:

Table 3-340. Function i2c_interrupt_flag_clear

Function name	i2c_interrupt_flag_clear
Function prototype	void i2c_interrupt_flag_clear(uint32_t i2c_periph, i2c_interrupt_flag_enum int_flag);
Function descriptions	clear I2C interrupt flag status
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
int_flag	interrupt flag
<i>I2C_INT_FLAG_ADDS</i> <i>END</i>	address is sent in master mode or received and matches in slave mode interrupt flag
<i>I2C_INT_FLAG_BERR</i>	a bus error occurs indication a unexpected start or stop condition on I2C bus interrupt flag

<i>I2C_INT_FLAG_LOSTA</i> <i>RB</i>	arbitration lost in master mode interrupt flag
<i>I2C_INT_FLAG_AERR</i>	acknowledge error interrupt flag
<i>I2C_INT_FLAG_OUER</i> <i>R</i>	over-run or under-run situation occurs in slave mode interrupt flag
<i>I2C_INT_FLAG_PECE</i> <i>RR</i>	PEC error when receiving data interrupt flag
<i>I2C_INT_FLAG_SMBT</i> <i>O</i>	timeout signal in SMBus mode interrupt flag
<i>I2C_INT_FLAG_SMBA</i> <i>LT</i>	SMBus Alert status interrupt flag
<i>I2C_INT_FLAG_TFF</i>	txframe fall interrupt flag
<i>I2C_INT_FLAG_TFR</i>	txframe rise interrupt flag
<i>I2C_INT_FLAG_RFF</i>	rxframe fall interrupt flag
<i>I2C_INT_FLAG_RFR</i>	rxframe rise interrupt flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear the acknowledge error interrupt flag */
```

```
i2c_interrupt_flag_clear (I2C0, I2C_INT_FLAG_AERR);
```

3.16. MISC

MISC is a software package that provide the interfaces for NVIC and SysTick. The NVIC and SysTick registers are listed in chapter [3.16.1](#), the MISC firmware functions are introduced in chapter [3.16.2](#).

3.16.1. Descriptions of Peripheral registers

Table 3-341. NVIC Registers

Registers	Descriptions
ISER ⁽¹⁾	Interrupt Set Enable Register
ICER ⁽¹⁾	Interrupt Clear Enable Register
ISPR ⁽¹⁾	Interrupt Set Pending Register
ICPR ⁽¹⁾	Interrupt Clear Pending Register
IABR ⁽¹⁾	Interrupt Active bit Register
IP ⁽¹⁾	Interrupt Priority Register
STIR ⁽¹⁾	Software Trigger Interrupt Register
CPUID ⁽²⁾	CPUID Base Register

Registers	Descriptions
ICSR ⁽²⁾	Interrupt Control and State Register
VTOR ⁽²⁾	Vector Table Offset Register
AIRCR ⁽²⁾	Application Interrupt and Reset Control Register
SCR ⁽²⁾	System Control Register
CCR ⁽²⁾	Configuration Control Register
SHP ⁽²⁾	System Handlers Priority Registers
SHCSR ⁽²⁾	System Handler Control and State Register
CFSR ⁽²⁾	Configurable Fault Status Register
HFSR ⁽²⁾	HardFault Status Register
DFSR ⁽²⁾	Debug Fault Status Register
MMFAR ⁽²⁾	MemManage Fault Address Register
BFAR ⁽²⁾	BusFault Address Register
AFSR ⁽²⁾	Auxiliary Fault Status Register
PFR ⁽²⁾	Processor Feature Register
DFR ⁽²⁾	Debug Feature Register
ADR ⁽²⁾	Auxiliary Feature Register
MMFR ⁽²⁾	Memory Model Feature Register
ISAR ⁽²⁾	Instruction Set Attributes Register
CPACR ⁽²⁾	Coprocessor Access Control Register

1. refer to the structure NVIC_Type, is defined in the core_cm4h file

2. refer to the structure SCB_Type, is defined in the core_cm4. file

Table 3-342. SysTick Registers

Registers	Descriptions
CTRL ⁽¹⁾	SysTick Control and Status Register
LOAD ⁽¹⁾	SysTick Reload Value Register
VAL ⁽¹⁾	SysTick Current Value Register
CALIB ⁽¹⁾	SysTick Calibration Register

1. refer to the structure SysTick_Type, is defined in the core_cm4h file

3.16.2. Descriptions of Peripheral functions

Enum IRQn_Type

Table 3-343. IRQn_Type

Member name	Function description
WWDGT_IRQn	WWDGT interrupt
LVD_IRQn	LVD from EXTI interrupt
TAMPER_IRQn	Tamper interrupt
RTC_IRQn	RTC global interrupt
FMC_IRQn	FMC global interrupt
RCU_CTC_IRQn	RCU and CTC interrupts

Member name	Function description
EXTI0_IRQn	EXTI line0 interrupt
EXTI1_IRQn	EXTI line1 interrupt
EXTI2_IRQn	EXTI line2 interrupt
EXTI3_IRQn	EXTI line3 interrupt
EXTI4_IRQn	EXTI line4 interrupt
DMA0_Channel0_IRQn	DMA0 channel0 global interrupt
DMA0_Channel1_IRQn	DMA0 channel1 global interrupt
DMA0_Channel2_IRQn	DMA0 channel2 global interrupt
DMA0_Channel3_IRQn	DMA0 channel3 global interrupt
DMA0_Channel4_IRQn	DMA0 channel4 global interrupt
DMA0_Channel5_IRQn	DMA0 channel5 global interrupt
DMA0_Channel6_IRQn	DMA0 channel6 global interrupt
ADC0_1_IRQn	ADC0 and ADC1 interrupts
CAN0_TX_IRQn	CAN0 TX interrupt
CAN0_RX0_IRQn	CAN0 RX0 interrupt
CAN0_RX1_IRQn	CAN0 RX1 interrupt
CAN0_EWMC_IRQn	CAN0 EWMC interrupt
EXTI5_9_IRQn	EXTI line[9:5] interrupts
TIMER0_BRK_TIMER8_IRQn	TIMER0 break and TIMER8 global interrupts
TIMER0_UP_TIMER9_IRQn	TIMER0 update and TIMER9 global interrupts
TIMER0_TRG_CMT_TIMER10_IRQn	TIMER0 trigger and channel commutation and TIMER10 interrupts
TIMER0_Channel_IRQn	TIMER0 channel capture compare interrupt
TIMER1_IRQn	TIMER1 global interrupt
TIMER2_IRQn	TIMER2 global interrupt
TIMER3_IRQn	TIMER3 global interrupt
I2C0_EV_IRQn	I2C0 event interrupt
I2C0_ER_IRQn	I2C0 error interrupt
I2C1_EV_IRQn	I2C1 event interrupt
I2C1_ER_IRQn	I2C1 error interrupt
SPI0_IRQn	SPI0 global interrupt
SPI1_IRQn	SPI1 global interrupt
USART0_IRQn	USART0 global interrupt
USART1_IRQn	USART1 global interrupt
USART2_IRQn	USART2 global interrupt
EXTI10_15_IRQn	EXTI line[15:10] interrupts
RTC_Alarm_IRQn	RTC alarm from EXTI interrupt
USBFS_WKUP_IRQn	USBFS wakeup from EXTI interrupt
TIMER7_BRK_TIMER11_IRQn	TIMER7 break and TIMER11 global interrupts
TIMER7_UP_TIMER12_IRQn	TIMER7 update and TIMER12 global interrupts

Member name	Function description
TIMER7_TRG_CMT_TIMER13_IRQn	TIMER7 trigger and Channel commutation and TIMER13 global interrupts
TIMER7_Channel_IRQn	TIMER7 channel capture compare interrupt
EXMC_IRQn	EXMC global interrupt
TIMER4_IRQn	TIMER4 global interrupt
SPI2_IRQn	SPI2 global interrupt
UART3_IRQn	UART3 global interrupt
UART4_IRQn	UART4 global interrupt
TIMER5_IRQn	TIMER5 global interrupt
TIMER6_IRQn	TIMER6 global interrupt
DMA1_Channel0_IRQn	DMA1 channel0 global interrupt
DMA1_Channel1_IRQn	DMA1 channel1 global interrupt
DMA1_Channel2_IRQn	DMA1 channel2 global interrupt
DMA1_Channel3_IRQn	DMA1 channel3 global interrupt
DMA1_Channel4_IRQn	DMA1 channel4 global interrupt
CAN1_TX_IRQn	CAN1 TX interrupt
CAN1_RX0_IRQn	CAN1 RX0 interrupt
CAN1_RX1_IRQn	CAN1 RX1 interrupt
CAN1_EWMC_IRQn	CAN1 EWMC interrupt
USBFS_IRQn	USBFS global interrupt

MISC firmware functions are listed in the table shown as below:

Table 3-344. MISC firmware function

Function name	Function description
<code>nvic_priority_group_set</code>	set the priority group
<code>nvic_irq_enable</code>	enable NVIC interrupt request
<code>nvic_irq_disable</code>	disable NVIC interrupt request
<code>nvic_vector_table_set</code>	set the NVIC vector table base address
<code>system_lowpower_set</code>	set the state of the low power mode
<code>system_lowpower_reset</code>	reset the state of the low power mode
<code>systick_cksourceset</code>	set the systick clock source

nvic_priority_group_set

The description of `nvic_priority_group_set` is shown as below:

Table 3-345. Function `nvic_priority_group_set`

Function name	<code>nvic_priority_group_set</code>
Function prototype	<code>void nvic_priority_group_set(uint32_t nvic_prigroup);</code>
Function descriptions	set the priority group
Precondition	-
The called functions	-

Input parameter{in}	
nvic_prigroup	priority group
<i>NVIC_PRIGROUP_PRE0_SUB4</i>	0 bits for pre-emption priority, 4 bits for subpriority
<i>NVIC_PRIGROUP_PRE1_SUB3</i>	1 bits for pre-emption priority, 3 bits for subpriority
<i>NVIC_PRIGROUP_PRE2_SUB2</i>	2 bits for pre-emption priority, 2 bits for subpriority
<i>NVIC_PRIGROUP_PRE3_SUB1</i>	3 bits for pre-emption priority, 1 bits for subpriority
<i>NVIC_PRIGROUP_PRE4_SUB0</i>	4 bits for pre-emption priority, 0 bits for subpriority
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* priority group configuration , 0 bits for pre-emption priority, 4 bits for subpriority */
```

```
nvic_priority_group_set(NVIC_PRIGROUP_PRE0_SUB4);
```

nvic_irq_enable

The description of nvic_irq_enable is shown as below:

Table 3-346. Function nvic_irq_enable

Function name	nvic_irq_enable
Function prototype	void nvic_irq_enable(uint8_t nvic_irq, uint8_t nvic_irq_pre_priority, uint8_t nvic_irq_sub_priority);
Function descriptions	enable NVIC interrupt request
Precondition	-
The called functions	nvic_priority_group_set
Input parameter{in}	
nvic_irq	NVIC interrupt, refer to enum Table 3-343. IRQn_Type
Input parameter{in}	
nvic_irq_pre_priority	the pre-emption priority needed to set
Input parameter{in}	
nvic_irq_sub_priority	the subpriority needed to set
Output parameter{out}	
-	-
Return value	
-	-

Example:


```
/* enable window watchDog timer interrupt, pre-emption priority is 1, subpriority is 1 */
nvic_irq_enable(WWDGT_IRQn, 1, 1);
```

nvic_irq_disable

The description of nvic_irq_disable is shown as below:

Table 3-347. Function nvic_irq_disable

Function name	nvic_irq_disable
Function prototype	void nvic_irq_disable(uint8_t nvic_irq);
Function descriptions	disable NVIC interrupt request
Precondition	-
The called functions	-
Input parameter{in}	
nvic_irq	NVIC interrupt, refer to enum Table 3-343. IRQn_Type
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable window watchDog timer interrupt */
nvic_irq_disable(WWDGT_IRQn);
```

nvic_vector_table_set

The description of nvic_vector_table_set is shown as below:

Table 3-348. Function nvic_vector_table_set

Function name	nvic_vector_table_set
Function prototype	void nvic_vector_table_set(uint32_t nvic_vect_tab, uint32_t offset);
Function descriptions	set the NVIC vector table base address
Precondition	-
The called functions	-
Input parameter{in}	
nvic_vect_tab	the RAM or FLASH base address
<i>NVIC_VECTTAB_RAM</i>	RAM base address
<i>NVIC_VECTTAB_FLASH</i>	Flash base address
Input parameter{in}	
offset	vector table offset (vector table start address= base address+offset)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set vector table address = NVIC_VECTTAB_FLASH +0x200 */
nvic_vector_table_set(NVIC_VECTTAB_FLASH,0x200);
```

system_lowpower_set

The description of system_lowpower_set is shown as below:

Table 3-349. Function system_lowpower_set

Function name	system_lowpower_set
Function prototype	void system_lowpower_set(uint8_t lowpower_mode);
Function descriptions	set the state of the low power mode
Precondition	-
The called functions	-
Input parameter{in}	
lowpower_mode	the low power mode state
SCB_LPM_SLEEP_EXIT_ISR	if chose this para, the system always enter low power mode by exiting from ISR
SCB_LPM_DEEPSLEEP	if chose this para, the system will enter the DEEPSLEEP mode
SCB_LPM_WAKE_BY_ALL_INT	if chose this para, the lowpower mode can be woke up by all the enable and disable interrupts
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* the system always enter low power mode by exiting from ISR */
system_lowpower_set(SCB_LPM_SLEEP_EXIT_ISR);
```

system_lowpower_reset

The description of system_lowpower_reset is shown as below:

Table 3-350. Function system_lowpower_reset

Function name	system_lowpower_reset
Function prototype	void system_lowpower_reset(uint8_t lowpower_mode);
Function descriptions	reset the state of the low power mode
Precondition	-
The called functions	-
Input parameter{in}	
lowpower_mode	the low power mode state
SCB_LPM_SLEEP_EXIT_ISR	if chose this para, the system will exit low power mode by exiting from ISR

<i>T_ISR</i>	
<i>SCB_LPM_DEEPSLEEP</i>	if chose this para, the system will enter the SLEEP mode
<i>P</i>	
<i>SCB_LPM_WAKE_BY_</i>	if chose this para, the lowpower mode only can be woke up by the enable
<i>ALL_INT</i>	interrupts
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* the system will exit low power mode by exiting from ISR */
system_lowpower_reset (SCB_LPM_SLEEP_EXIT_ISR);
```

systick_clksource_set

The description of systick_clksource_set is shown as below:

Table 3-351. Function systick_clksource_set

Function name	systick_clksource_set
Function prototype	void systick_clksource_set(uint32_t systick_clksource);
Function descriptions	set the systick clock source
Precondition	-
The called functions	-
Input parameter{in}	
systick_clksource	the systick clock source needed to choose
<i>SYSTICK_CLKSOURC</i>	systick clock source is from HCLK
<i>E_HCLK</i>	
<i>SYSTICK_CLKSOURC</i>	systick clock source is from HCLK/8
<i>E_HCLK_DIV8</i>	
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* systick clock source is HCLK/8 */
systick_clksource_set (SYSTICK_CLKSOURCE_HCLK_DIV8);
```

3.17. PMU

According to the Power management unit (PMU), provides three types of power saving modes, including Sleep, Deep-sleep and Standby mode. The PMU registers are listed in chapter

[3.17.1](#), the PMU firmware functions are introduced in chapter [3.17.2](#).

3.17.1. Descriptions of Peripheral registers

PMU registers are listed in the table shown as below:

Table 3-352. PMU Registers

Registers	Descriptions
PMU_CTL	Control register
PMU_CS	Control and status register

3.17.2. Descriptions of Peripheral functions

PMU firmware functions are listed in the table shown as below:

Table 3-353. PMU firmware function

Function name	Function description
pmu_deinit	deinitialize the PMU
pmu_lvd_select	select low voltage detector threshold
pmu_ldo_output_select	select LDO output voltage
pmu_lvd_disable	disable PMU lvd
pmu_to_sleepmode	PMU work at sleep mode
pmu_to_deepsleepmode	PMU work at deepsleep mode
pmu_to_standbymode	pmu work at standby mode
pmu_wakeup_pin_enable	enable wakeup pin
pmu_wakeup_pin_disable	disable wakeup pin
pmu_backup_write_enable	enable backup domain write
pmu_backup_write_disable	disable backup domain write
pmu_flag_get	get flag state
pmu_flag_clear	clear flag bit

pmu_deinit

The description of pmu_deinit is shown as below:

Table 3-354. Function pmu_deinit

Function name	pmu_deinit
Function prototype	void pmu_deinit(void);
Function descriptions	deinitialize the PMU
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Input parameter{in}	
-	-
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* reset PMU */
```

```
pmu_deinit();
```

pmu_lvd_select

The description of pmu_lvd_select is shown as below:

Table 3-355. Function pmu_lvd_select

Function name	pmu_lvd_select
Function prototype	void pmu_lvd_select(uint32_t lvd_t_n);
Function descriptions	select low voltage detector threshold
Precondition	-
The called functions	-
Input parameter{in}	
lvd_t_n	voltage threshold value
PMU_LVDT_0	voltage threshold is 2.2V
PMU_LVDT_1	voltage threshold is 2.3V
PMU_LVDT_2	voltage threshold is 2.4V
PMU_LVDT_3	voltage threshold is 2.5V
PMU_LVDT_4	voltage threshold is 2.6V
PMU_LVDT_5	voltage threshold is 2.7V
PMU_LVDT_6	voltage threshold is 2.8V
PMU_LVDT_7	voltage threshold is 2.9V
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* select low voltage detector threshold as 2.9V */
```

```
pmu_lvd_select (PMU_LVDT_7);
```

pmu_ldo_output_select

The description of pmu_ldo_output_select is shown as below:

Table 3-356. Function pmu_ldo_output_select

Function name	pmu_ldo_output_select
Function prototype	void pmu_ldo_output_select(uint32_t ldo_output);
Function descriptions	internal voltage regulator (LDO) output voltage select

Precondition	-
The called functions	-
Input parameter{in}	
ldo_output	output voltage mode
<i>PMU_LDOVS_LOW</i>	output low voltage mode
<i>PMU_LDOVS_NORMAL</i>	output normal voltage mode
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* select output low voltage mode */
pmu_ldo_output_select (PMU_LDOVS_LOW);
```

pmu_lvd_disable

The description of pmu_lvd_disable is shown as below:

Table 3-357. Function pmu_lvd_disable

Function name	pmu_lvd_disable
Function prototype	void pmu_lvd_disable (void);
Function descriptions	disable PMU lvd
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable PMU lvd */
pmu_lvd_disable ();
```

pmu_to_sleepmode

The description of pmu_to_sleepmode is shown as below:

Table 3-358. Function pmu_to_sleepmode

Function name	pmu_to_sleepmode
Function prototype	void pmu_to_sleepmode(uint8_t sleepmodecmd);

Function descriptions	PMU work at sleep mode
Precondition	-
The called functions	-
Input parameter{in}	
sleepmodecmd	command to enter sleep mode
<i>WFI_CMD</i>	use WFI command
<i>WFE_CMD</i>	use WFE command
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* PMU work at sleep mode */
```

```
pmu_to_sleepmode (WFI_CMD);
```

pmu_to_deepsleepmode

The description of pmu_to_deepsleepmode is shown as below:

Table 3-359. Function pmu_to_deepsleepmode

Function name	pmu_to_deepsleepmode
Function prototype	void pmu_to_deepsleepmode(uint32_t ldo,uint8_t deepsleepmodecmd);
Function descriptions	PMU work at deepsleep mode
Precondition	-
The called functions	-
Input parameter{in}	
ldo	ldo work mode
<i>PMU_LDO_NORMAL</i>	LDO normal work when pmu enter deepsleep mode
<i>PMU_LDO_LOWPOWER</i>	LDO work at low power mode when pmu enter deepsleep mode
Input parameter{in}	
deepsleepmodecmd	command to enter deepsleep mode
<i>WFI_CMD</i>	use WFI command
<i>WFE_CMD</i>	use WFE command
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* PMU work at deepsleep mode */
```

```
pmu_to_deepsleepmode (PMU_LDO_NORMAL, WFI_CMD);
```

pmu_to_standbymode

The description of pmu_to_standbymode is shown as below:

Table 3-360. Function pmu_to_standbymode

Function name	pmu_to_standbymode
Function prototype	void pmu_to_standbymode(void);
Function descriptions	pmu work at standby mode
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* PMU work at standby mode */
pmu_to_standby ();
```

pmu_wakeup_pin_enable

The description of pmu_wakeup_pin_enable is shown as below:

Table 3-361. Function pmu_wakeup_pin_enable

Function name	pmu_wakeup_pin_enable
Function prototype	void pmu_wakeup_pin_enable(void);
Function descriptions	enable wakeup pin
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable wakeup pin */
pmu_wakeup_pin_enable ();
```


pmu_wakeup_pin_disable

The description of pmu_wakeup_pin_disable is shown as below:

Table 3-362. Function pmu_wakeup_pin_disable

Function name	pmu_wakeup_pin_disable
Function prototype	void pmu_wakeup_pin_disable (void);
Function descriptions	disable wakeup pin
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable wakeup pin */
pmu_wakeup_pin_disable ();
```

pmu_backup_write_enable

The description of pmu_backup_write_enable is shown as below:

Table 3-363. Function pmu_backup_write_enable

Function name	pmu_backup_write_enable
Function prototype	void pmu_backup_write_enable (void);
Function descriptions	enable backup domain write
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable backup domain write */
pmu_backup_write_enable ();
```

pmu_backup_write_disable

The description of pmu_backup_write_disable is shown as below:

Table 3-364. Function pmu_backup_write_disable

Function name	pmu_backup_write_disable
Function prototype	void pmu_backup_write_disable (void);
Function descriptions	disable backup domain write
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable backup domain write */
pmu_backup_write_disable ();
```

pmu_flag_get

The description of pmu_flag_get is shown as below:

Table 3-365. Function pmu_flag_get

Function name	pmu_flag_get
Function prototype	FlagStatus pmu_flag_get(uint32_t flag);
Function descriptions	get flag state
Precondition	-
The called functions	-
Input parameter{in}	
flag	flag
<i>PMU_FLAG_WAKEUP</i>	wakeup flag
<i>PMU_FLAG_STANDBY</i>	standby flag
<i>PMU_FLAG_LVD</i>	low voltage detector status flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get flag state */
FlagStatus status;
```

```
status = pmu_flag_get (PMU_FLAG_WAKEUP);
```

pmu_flag_clear

The description of pmu_flag_clear is shown as below:

Table 3-366. Function pmu_flag_clear

Function name	pmu_flag_clear
Function prototype	void pmu_flag_clear(uint32_t flag_reset);
Function descriptions	clear flag bit
Precondition	-
The called functions	-
Input parameter{in}	
flag_reset	flag
PMU_FLAG_RESET_WAKEUP	reset wakeup flag
PMU_FLAG_RESET_STANDBY	reset standby flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear flag bit */
```

```
pmu_flag_clear (PMU_FLAG_RESET_WAKEUP);
```

3.18. RCU

RCU is the reset and clock unit. Reset Control includes the control of three kinds of reset: power reset, system reset and backup domain reset. The Clock Control unit provides a range of frequencies and clock functions. The RCU registers are listed in chapter [3.18.1](#), the RCU firmware functions are introduced in chapter [3.18.2](#).

3.18.1. Descriptions of Peripheral registers

Table 3-367. RCU Registers

Registers	Descriptions
RCU_CTL	Control register
RCU_CFG0	Clock configuration register 0
RCU_INT	Clock interrupt register
RCU_APB2RST	APB2 reset register
RCU_APB1RST	APB1 reset register

Registers	Descriptions
RCU_AHBEN	AHB enable register
RCU_APB2EN	APB2 enable register
RCU_APB1EN	APB1 enable register
RCU_BDCTL	Backup domain control register
RCU_RSTSCK	Reset source/clock register
RCU_AHBRST	AHB reset register
RCU_CFG1	Clock configuration register 1
RCU_DSV	Deep-sleep mode voltage register
RCU_ADDCTL	Additional clock control register
RCU_ADDINT	Additional clock interrupt register
RCU_ADDAPB1RST	APB1 additional reset register
RCU_ADDAPB1EN	APB1 additional enable register

3.18.2. Descriptions of Peripheral functions

Table 3-368. RCU firmware function

Function name	Function description
rcu_deinit	deinitialize the RCU
rcu_periph_clock_enable	enable the peripherals clock
rcu_periph_clock_disable	disable the peripherals clock
rcu_periph_clock_sleep_enable	enable the peripherals clock when in sleep mode
rcu_periph_clock_sleep_disable	disable the peripherals clock when in sleep mode
rcu_periph_reset_enable	enable the peripherals reset
rcu_periph_reset_disable	disable the peripheral reset
rcu_bkp_reset_enable	enable the BKP domain reset
rcu_bkp_reset_disable	disable the BKP domain reset
rcu_system_clock_source_config	configure the system clock source
rcu_system_clock_source_get	get the system clock source
rcu_ahb_clock_config	configure the AHB clock prescaler selection
rcu_apb1_clock_config	configure the APB1 clock prescaler selection
rcu_apb2_clock_config	configure the APB2 clock prescaler selection
rcu_ckout0_config	configure the CK_OUT0 clock source
rcu_pll_config	configure the main PLL clock
rcu_pllpresel_config	configure the PLL clock source preselection
rcu_predv0_config	configure the PREDV0 division factor
rcu_predv1_config	configure the PREDV1 division factor
rcu_pll1_config	configure the PLL1 clock
rcu_pll2_config	configure the PLL2 clock
rcu_adc_clock_config	configure the ADC prescaler factor
rcu_usb_clock_config	configure the USB prescaler factor
rcu_rtc_clock_config	configure the RTC clock source selection

Function name	Function description
rcu_i2s1_clock_config	configure the I2S1 clock source selection
rcu_i2s2_clock_config	configure the I2S2 clock source selection
rcu_ck48m_clock_config	configure the CK48M clock selection
rcu_flag_get	get the clock stabilization and peripheral reset flags
rcu_all_reset_flag_clear	clear all the reset flag
rcu_interrupt_flag_get	get the clock stabilization interrupt and ckm flags
rcu_interrupt_flag_clear	clear the interrupt flags
rcu_interrupt_enable	enable the stabilization interrupt
rcu_interrupt_disable	disable the stabilization interrupt
rcu_lxtal_drive_capability_config	configure the LXTAL drive capability
rcu_osci_stab_wait	wait for oscillator stabilization flags is SET or oscillator startup is timeout
rcu_osci_on	turn on the oscillator
rcu_osci_off	turn off the oscillator
rcu_osci_bypass_mode_enable	enable the oscillator bypass mode
rcu_osci_bypass_mode_disable	disable the oscillator bypass mode
rcu_hxtal_clock_monitor_enable	enable the HXTAL clock monitor
rcu_hxtal_clock_monitor_disable	disable the HXTAL clock monitor
rcu_irc8m_adjust_value_set	set the IRC8M adjust value
rcu_deepsleep_voltage_set	set the deep-sleep mode voltage value
rcu_clock_freq_get	get the system clock, bus clock frequency

Enum rcu_periph_enum

Table 3-369. Enum rcu_periph_enum

enum name	Function description
RCU_DMA0	DMA0 clock
RCU_DMA1	DMA1 clock
RCU_CRC	CRC clock
RCU_EXMC	EXMC clock
RCU_USBFS	USBFS clock
RCU_TIMER1	TIMER1 clock
RCU_TIMER2	TIMER2 clock
RCU_TIMER3	TIMER3 clock
RCU_TIMER4	TIMER4 clock
RCU_TIMER5	TIMER5 clock
RCU_TIMER6	TIMER6 clock
RCU_TIMER11	TIMER11 clock
RCU_TIMER12	TIMER12 clock
RCU_TIMER13	TIMER13 clock
RCU_WWDGT	WWDGT clock
RCU_SPI1	SPI1 clock

enum name	Function description
RCU_SPI2	SPI2 clock
RCU_USART1	USART1 clock
RCU_USART2	USART2 clock
RCU_UART3	UART3 clock
RCU_UART4	UART4 clock
RCU_I2C0	I2C0 clock
RCU_I2C1	I2C1 clock
RCU_CAN0	CAN0 clock
RCU_CAN1	CAN1 clock
RCU_BKPI	BKPI clock
RCU_PMU	PMU clock
RCU_DAC	DAC clock
RCU_RTC	RTC clock
RCU_CTC	CTC clock
RCU_AF	alternate function clock
RCU_GPIOA	GPIOA clock
RCU_GPIOB	GPIOB clock
RCU_GPIOC	GPIOC clock
RCU_GPIOD	GPIOD clock
RCU_GPIOE	GPIOE clock
RCU_ADC0	ADC0 clock
RCU_ADC1	ADC1 clock
RCU_TIMER0	TIMER0 clock
RCU_SPI0	SPI0 clock
RCU_TIMER7	TIMER7 clock
RCU_USART0	USART0 clock
RCU_TIMER8	TIMER8 clock
RCU_TIMER9	TIMER9 clock
RCU_TIMER10	TIMER10 clock

Enum rcu_periph_sleep_enum

Table 3-370. Enum rcu_periph_sleep_enum

enum name	Function description
RCU_SRAM_SLP	SRAM clock when sleep mode
RCU_FMC_SLP	FMC clock when sleep mode

Enum rcu_periph_reset_enum

Table 3-371. Enum rcu_periph_reset_enum

enum name	Function description
RCU_USBFSRST	USBFS clock reset

enum name	Function description
RCU_TIMER1RST	TIMER1 clock reset
RCU_TIMER2RST	TIMER2 clock reset
RCU_TIMER3RST	TIMER3 clock reset
RCU_TIMER4RST	TIMER4 clock reset
RCU_TIMER5RST	TIMER5 clock reset
RCU_TIMER6RST	TIMER6 clock reset
RCU_TIMER11RST	TIMER11 clock reset
RCU_TIMER12RST	TIMER12 clock reset
RCU_TIMER13RST	TIMER13 clock reset
RCU_WWDGTRST	WWDGT clock reset
RCU_SPI1RST	SPI1 clock reset
RCU_SPI2RST	SPI2 clock reset
RCU_USART1RST	USART1 clock reset
RCU_USART2RST	USART2 clock reset
RCU_UART3RST	UART3 clock reset
RCU_UART4RST	UART4 clock reset
RCU_I2C0RST	I2C0 clock reset
RCU_I2C1RST	I2C1 clock reset
RCU_CAN0RST	CAN0 clock reset
RCU_CAN1RST	CAN1 clock reset
RCU_BKPIRST	BKPI clock reset
RCU_PMURST	PMU clock reset
RCU_DACRST	DAC clock reset
RCU_CTCRST	CTC clock reset
RCU_AFRST	alternate function clock reset
RCU_GPIOARST	GPIOA clock reset
RCU_GPIOBRST	GPIOB clock reset
RCU_GPIOCRST	GPIOC clock reset
RCU_GPIODRST	GPIOD clock reset
RCU_GPIOERST	GPIOE clock reset
RCU_ADC0RST	ADC0 clock reset
RCU_ADC1RST	ADC1 clock reset
RCU_TIMER0RST	TIMER0 clock reset
RCU_SPI0RST	SPI0 clock reset
RCU_TIMER7RST	TIMER7 clock reset
RCU_USART0RST	USART0 clock reset
RCU_TIMER8RST	TIMER8 clock reset
RCU_TIMER9RST	TIMER9 clock reset
RCU_TIMER10RST	TIMER10 clock reset

Enum rcu_flag_enum

Table 3-372. Enum rcu_flag_enum

enum name	Function description
RCU_FLAG_IRC8MSTB	IRC8M stabilization flags
RCU_FLAG_HXTALSTB	HXTAL stabilization flags
RCU_FLAG_PLLSTB	PLL stabilization flags
RCU_FLAG_PLL1STB	PLL1 stabilization flags
RCU_FLAG_PLL2STB	PLL2 stabilization flags
RCU_FLAG_LXTALSTB	LXTAL stabilization flags
RCU_FLAG_IRC40KSTB	IRC40K stabilization flags
RCU_FLAG_IRC48MSTB	IRC48M stabilization flags
RCU_FLAG_EPRST	external PIN reset flags
RCU_FLAG_PORRST	power reset flags
RCU_FLAG_SWRST	software reset flags
RCU_FLAG_FWDGTRST	FWDGT reset flags
RCU_FLAG_WWDGTRST	WWDGT reset flags
RCU_FLAG_LPRST	low-power reset flags

Enum rcu_int_flag_enum

Table 3-373. Enum rcu_int_flag_enum

enum name	Function description
RCU_INT_FLAG_IRC40KSTB	IRC40K stabilization interrupt flag
RCU_INT_FLAG_LXTALSTB	LXTAL stabilization interrupt flag
RCU_INT_FLAG_IRC8MSTB	IRC8M stabilization interrupt flag
RCU_INT_FLAG_HXTALSTB	HXTAL stabilization interrupt flag
RCU_INT_FLAG_PLLSTB	PLL stabilization interrupt flag
RCU_INT_FLAG_PLL1STB	PLL1 stabilization interrupt flag
RCU_INT_FLAG_PLL2STB	PLL2 stabilization interrupt flag

enum name	Function description
STB	
RCU_INT_FLAG_CKM	HXTAL clock stuck interrupt flag
RCU_INT_FLAG_IRC4 8MSTB	IRC48M stabilization interrupt flag

Enum rcu_int_flag_clear_enum

Table 3-374. Enum rcu_int_flag_clear_enum

enum name	Function description
RCU_INT_FLAG_IRC4 0KSTB_CLR	IRC40K stabilization interrupt flags clear
RCU_INT_FLAG_LXTA LSTB_CLR	LXTAL stabilization interrupt flags clear
RCU_INT_FLAG_IRC8 MSTB_CLR	IRC8M stabilization interrupt flags clear
RCU_INT_FLAG_HXTA LSTB_CLR	HXTAL stabilization interrupt flags clear
RCU_INT_FLAG_PLLS TB_CLR	PLL stabilization interrupt flags clear
RCU_INT_FLAG_PLL1 STB_CLR	PLL1 stabilization interrupt flags clear
RCU_INT_FLAG_PLL2 STB_CLR	PLL2 stabilization interrupt flags clear
RCU_INT_FLAG_CKM _CLR	CKM interrupt flags clear
RCU_INT_FLAG_IRC4 8MSTB_CLR	internal 48 MHz RC oscillator stabilization interrupt clear

Enum rcu_int_enum

Table 3-375. Enum rcu_int_enum

enum name	Function description
RCU_INT_IRC40KSTB	IRC40K stabilization interrupt
RCU_INT_LXTALSTB	LXTAL stabilization interrupt
RCU_INT_IRC8MSTB	IRC8M stabilization interrupt
RCU_INT_HXTALSTB	HXTAL stabilization interrupt
RCU_INT_PLLSTB	PLL stabilization interrupt
RCU_INT_PLL1STB	PLL1 stabilization interrupt
RCU_INT_PLL2STB	PLL2 stabilization interrupt
RCU_INT_IRC48MSTB	internal 48 MHz RC oscillator stabilization interrupt

Enum rcu_osci_type_enum

Table 3-376. Enum rcu_osci_type_enum

enum name	Function description
RCU_HXTAL	HXTAL
RCU_LXTAL	LXTAL
RCU_IRC8M	IRC8M
RCU_IRC48M	IRC48M
RCU_IRC40K	IRC40K
RCU_PLL_CK	PLL
RCU_PLL1_CK	PLL1
RCU_PLL2_CK	PLL2

Enum rcu_clock_freq_enum

Table 3-377. Enum rcu_clock_freq_enum

enum name	Function description
CK_SYS	system clock
CK_AHB	AHB clock
CK_APB1	APB1 clock
CK_APB2	APB2 clock

rcu_deinit

The description of rcu_deinit is shown as below:

Table 3-378. Function rcu_deinit

Function name	rcu_deinit
Function prototype	void rcu_deinit(void);
Function descriptions	deinitialize the RCU, reset the value of all RCU registers into initial values
Precondition	-
The called functions	rcu_osci_stab_wait
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset RCU */
rcu_deinit();
```

rcu_periph_clock_enable

The description of rcu_periph_clock_enable is shown as below:

Table 3-379. Function rcu_periph_clock_enable

Function name	rcu_periph_clock_enable
Function prototype	void rcu_periph_clock_enable(rcu_periph_enum periph);
Function descriptions	enable the peripherals clock
Precondition	-
The called functions	-
Input parameter{in}	
periph	RCU peripherals, refer to Table 3-369. Enum rcu_periph_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the USART0 clock */
rcu_periph_clock_enable(RCU_USART0);
```

rcu_periph_clock_disable

The description of rcu_periph_clock_disable is shown as below:

Table 3-380. Function rcu_periph_clock_disable

Function name	rcu_periph_clock_disable
Function prototype	void rcu_periph_clock_disable(rcu_periph_enum periph);
Function descriptions	disable the peripherals clock
Precondition	-
The called functions	-
Input parameter{in}	
periph	RCU peripherals, refer to Table 3-369. Enum rcu_periph_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the USART0 clock */
rcu_periph_clock_disable(RCU_USART0);
```

rcu_periph_clock_sleep_enable

The description of rcu_periph_clock_sleep_enable is shown as below:

Table 3-381. Function rcu_periph_clock_sleep_enable

Function name	rcu_periph_clock_sleep_enable
Function prototype	void rcu_periph_clock_sleep_enable(rcu_periph_sleep_enum periph);
Function descriptions	enable the peripherals clock when in sleep mode
Precondition	-
The called functions	-
Input parameter{in}	
periph	RCU peripherals, refer to Table 3-370. Enum rcu_periph_sleep_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the FMC clock when in sleep mode */
rcu_periph_clock_sleep_enable(RCU_FMC_SLP);
```

rcu_periph_clock_sleep_disable

The description of rcu_periph_clock_sleep_disable is shown as below:

Table 3-382. Function rcu_periph_clock_sleep_disable

Function name	rcu_periph_clock_sleep_disable
Function prototype	void rcu_periph_clock_sleep_disable(rcu_periph_sleep_enum periph);
Function descriptions	disable the peripherals clock when in sleep mode
Precondition	-
The called functions	-
Input parameter{in}	
periph	RCU peripherals, refer to Table 3-370. Enum rcu_periph_sleep_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the FMC clock when in sleep mode */
rcu_periph_clock_sleep_disable(RCU_FMC_SLP);
```

rcu_periph_reset_enable

The description of rcu_periph_reset_enable is shown as below:

Table 3-383. Function rcu_periph_reset_enable

Function name	rcu_periph_reset_enable
Function prototype	void rcu_periph_reset_enable(rcu_periph_reset_enum periph_reset);
Function descriptions	enable the peripherals reset
Precondition	-
The called functions	-
Input parameter{in}	
periph_reset	RCU peripherals reset, refer to Table 3-371. Enum rcu_periph_reset_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable SPI0 reset */
rcu_periph_reset_enable(RCU_SPI0RST);
```

rcu_periph_reset_disable

The description of rcu_periph_reset_disable is shown as below:

Table 3-384. Function rcu_periph_reset_disable

Function name	rcu_periph_reset_disable
Function prototype	void rcu_periph_reset_disable(rcu_periph_reset_enum periph_reset);
Function descriptions	disable the peripheral reset
Precondition	-
The called functions	-
Input parameter{in}	
periph_reset	RCU peripherals reset, refer to Table 3-371. Enum rcu_periph_reset_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable SPI0 reset */
rcu_periph_reset_disable(RCU_SPI0RST);
```

rcu_bkp_reset_enable

The description of rcu_bkp_reset_enable is shown as below:

Table 3-385. Function rcu_bkp_reset_enable

Function name	rcu_bkp_reset_enable
Function prototype	void rcu_bkp_reset_enable(void);
Function descriptions	enable the BKP domain reset
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset the BKP domain */
rcu_bkp_reset_enable();
```

rcu_bkp_reset_disable

The description of rcu_bkp_reset_disable is shown as below:

Table 3-386. Function rcu_bkp_reset_disable

Function name	rcu_bkp_reset_disable
Function prototype	void rcu_bkp_reset_disable(void);
Function descriptions	disable the BKP domain reset
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the BKP domain reset */
rcu_bkp_reset_disable();
```

rcu_system_clock_source_config

The description of rcu_system_clock_source_config is shown as below:

Table 3-387. Function rcu_system_clock_source_config

Function name	rcu_system_clock_source_config
Function prototype	void rcu_system_clock_source_config(uint32_t ck_sys);
Function descriptions	configure the system clock source
Precondition	-
The called functions	-
Input parameter{in}	
ck_sys	system clock source select
<i>RCU_CKSYSSRC_IRC8M</i>	select CK_IRC8M as the CK_SYS source
<i>RCU_CKSYSSRC_HXTAL</i>	select CK_HXTAL as the CK_SYS source
<i>RCU_CKSYSSRC_PLL</i>	select CK_PLL as the CK_SYS source
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the CK_HXTAL as the CK_SYS source */
rcu_system_clock_source_config(RCU_CKSYSSRC_HXTAL);
```

rcu_system_clock_source_get

The description of rcu_system_clock_source_get is shown as below:

Table 3-388. Function rcu_system_clock_source_get

Function name	rcu_system_clock_source_get
Function prototype	uint32_t rcu_system_clock_source_get(void);
Function descriptions	get the system clock source
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint32_t	RCU_SCSS_IRC8M/RCU_SCSS_HXTAL/RCU_SCSS_PLL

Example:

```
uint32_t temp_cksys_status;

/* get the CK_SYS source */

temp_cksys_status = rcu_system_clock_source_get();
```

rcu_ahb_clock_config

The description of rcu_ahb_clock_config is shown as below:

Table 3-389. Function rcu_ahb_clock_config

Function name	rcu_ahb_clock_config
Function prototype	void rcu_ahb_clock_config(uint32_t ck_ahb);
Function descriptions	configure the AHB clock prescaler selection
Precondition	-
The called functions	-
Input parameter{in}	
ck_ahb	AHB clock prescaler selection
<i>RCU_AHB_CKSYS_DIVx</i>	select CK_SYS / x, (x=1, 2, 4, 8, 16, 64, 128, 256, 512)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure CK_SYS/128 */

rcu_ahb_clock_config(RCU_AHB_CKSYS_DIV128);
```

rcu_apb1_clock_config

The description of rcu_apb1_clock_config is shown as below:

Table 3-390. Function rcu_apb1_clock_config

Function name	rcu_apb1_clock_config
Function prototype	void rcu_apb1_clock_config(uint32_t ck_apb1);
Function descriptions	configure the APB1 clock prescaler selection
Precondition	-
The called functions	-
Input parameter{in}	
ck_apb1	APB1 clock prescaler selection
<i>RCU_APB1_CKAHB_DIV1</i>	select CK_AHB as CK_APB1
<i>RCU_APB1_CKAHB_DIV2</i>	select CK_AHB/2 as CK_APB1

<i>RCU_APB1_CKAHB_D</i> IV4	select CK_AHB/4 as CK_APB1
<i>RCU_APB1_CKAHB_D</i> IV8	select CK_AHB/8 as CK_APB1
<i>RCU_APB1_CKAHB_D</i> IV16	select CK_AHB/16 as CK_APB1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure CK_AHB/16 as CK_APB1 */
```

```
rcu_apb1_clock_config(RCU_APB1_CKAHB_DIV16);
```

rcu_apb2_clock_config

The description of rcu_apb2_clock_config is shown as below:

Table 3-391. Function rcu_apb2_clock_config

Function name	rcu_apb2_clock_config
Function prototype	void rcu_apb2_clock_config(uint32_t ck_apb2);
Function descriptions	configure the APB2 clock prescaler selection
Precondition	-
The called functions	-
Input parameter{in}	
ck_apb2	APB2 clock prescaler selection
<i>RCU_APB2_CKAHB_D</i> IV1	select CK_AHB as CK_APB2
<i>RCU_APB2_CKAHB_D</i> IV2	select CK_AHB/2 as CK_APB2
<i>RCU_APB2_CKAHB_D</i> IV4	select CK_AHB/4 as CK_APB2
<i>RCU_APB2_CKAHB_D</i> IV8	select CK_AHB/8 as CK_APB2
<i>RCU_APB2_CKAHB_D</i> IV16	select CK_AHB/16 as CK_APB2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure CK_AHB/8 as CK_APB2 */
```

```
rcu_apb2_clock_config(RCU_APB2_CKAHB_DIV8);
```

rcu_ckout0_config

The description of rcu_ckout0_config is shown as below:

Table 3-392. Function rcu_ckout0_config

Function name	rcu_ckout0_config
Function prototype	void rcu_ckout0_config(uint32_t ckout0_src);
Function descriptions	configure the CK_OUT0 clock source
Precondition	-
The called functions	-
Input parameter{in}	
ckout0_src	CK_OUT0 clock source selection
RCU_CKOUT0SRC_NONE	no clock selected
RCU_CKOUT0SRC_CKSYS	select system clock CK_SYS
RCU_CKOUT0SRC_IRC8M	select high speed 8M internal oscillator clock
RCU_CKOUT0SRC_HXTAL	select HXTAL
RCU_CKOUT0SRC_CKPLL_DIV2	select (CK_PLL / 2) clock
RCU_CKOUT0SRC_CKPLL1	select CK_PLL1 clock
RCU_CKOUT0SRC_CKPLL2_DIV2	select (CK_PLL2 / 2) clock
RCU_CKOUT0SRC_CKPLL2	select CK_PLL2 clock
RCU_CKOUT0SRC_IRC48M	select IRC48M clock
RCU_CKOUT0SRC_IRC48M_DIV8	select (IRC48M / 8) clock
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the HXTAL as CK_OUT0 clock source */
```

```
rcu_ckout0_config(RCU_CKOUT0SRC_HXTAL);
```

rcu_pll_config

The description of rcu_pll_config is shown as below:

Table 3-393. Function rcu_pll_config

Function name	rcu_pll_config
Function prototype	void rcu_pll_config(uint32_t pll_src, uint32_t pll_mul);
Function descriptions	configure the main PLL clock
Precondition	-
The called functions	-
Input parameter{in}	
pll_src	PLL clock source selection
<i>RCU_PLLSRC_IRC8M_DIV2</i>	IRC8M/2 clock is selected as source clock of PLL
<i>RCU_PLLSRC_HXTAL_IRC48M</i>	HXTAL or IRC48M is selected as source clock of PLL
Input parameter{in}	
pll_mul	PLL clock multiplication factor
<i>RCU_PLL_MULx</i>	PLL clock * x (x = 2..14, 6.5, 16..31)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the PLL */
```

```
rcu_pll_config(RCU_PLLSRC_HXTAL, RCU_PLL_MUL10);
```

rcu_pllpresel_config

The description of rcu_pllpresel_config is shown as below:

Table 3-394. Function rcu_pllpresel_config

Function name	rcu_pllpresel_config
Function prototype	void rcu_pllpresel_config(uint32_t pll_presel);
Function descriptions	configure the PLL clock source preselection
Precondition	-
The called functions	-
Input parameter{in}	
pll_presel	PLL clock source preselection
<i>RCU_PLLPRESRC_HXTAL</i>	HXTAL selected as PREDV0 source clock
<i>RCU_PLLPRESRC_IRC48M</i>	CK_PLL selected as PREDV0 input source clock

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the PLL clock source preselection */
```

```
rcu_pllpreselel_config (RCU_PLLPRESRC_HXTAL);
```

rcu_predv0_config

The description of rcu_predv0_config is shown as below:

Table 3-395. Function rcu_predv0_config

Function name	rcu_predv0_config
Function prototype	void rcu_predv0_config(uint32_t predv0_source, uint32_t predv0_div);
Function descriptions	configure the PREDV0 division factor
Precondition	-
The called functions	-
Input parameter{in}	
predv0_source	PREDV0 input clock source selection
RCU_PREDV0SRC_HXTAL_IRC48M	select HXTAL or IRC48M as PREDV0 input source clock
RCU_PREDV0SRC_CKPLL1	select CK_PLL1 as PREDV0 input source clock
Input parameter{in}	
predv0_div	PREDV0 division factor
RCU_PREDV0_DIVx	PREDV0 input source clock is divided x (x=1..16)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the PREDV0 division factor */
```

```
rcu_predv0_config(RCU_PREDV0SRC_HXTAL_IRC48M, RCU_PREDV0_DIV4);
```

rcu_predv1_config

The description of rcu_predv1_config is shown as below:

Table 3-396. Function rcu_predv1_config

Function name	rcu_predv1_config
Function prototype	void rcu_predv1_config(uint32_t predv1_div);

Function descriptions	configure the PREDV1 division factor
Precondition	-
The called functions	-
Input parameter{in}	
predv1_div	PREDV1 division factor
<i>RCU_PREDV1_DIVx</i>	PREDV1 input source clock is divided x (x=1..16)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the PREDV1 division factor */
rcu_predv1_config(RCU_PREDV1_DIV8);
```

rcu_pll1_config

The description of rcu_pll1_config is shown as below:

Table 3-397. Function rcu_pll1_config

Function name	rcu_pll1_config
Function prototype	void rcu_pll1_config(uint32_t pll_mul);
Function descriptions	configure the PLL1 clock
Precondition	-
The called functions	-
Input parameter{in}	
pll_mul	PLL clock multiplication factor
<i>RCU_PLL1_MULx</i>	PLL1 clock * x, (x = 8..16, 20)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the PLL1 clock */
rcu_pll1_config(RCU_PLL1_MUL8);
```

rcu_pll2_config

The description of rcu_pll2_config is shown as below:

Table 3-398. Function rcu_pll2_config

Function name	rcu_pll2_config
Function prototype	void rcu_pll2_config(uint32_t pll_mul)

Function descriptions	configure the PLL2 clock
Precondition	-
The called functions	-
Input parameter{in}	
pll_mul	PLL clock multiplication factor
<i>RCU_PLL2_MULx</i>	PLL2 clock * x, (x = 8..16, 20)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the PLL2 clock */
```

```
rcu_pll2_config(RCU_PLL2_MUL8);
```

rcu_adc_clock_config

The description of rcu_adc_clock_config is shown as below:

Table 3-399. Function rcu_adc_clock_config

Function name	rcu_adc_clock_config
Function prototype	void rcu_adc_clock_config(uint32_t adc_psc);
Function descriptions	configure the ADC prescaler factor
Precondition	-
The called functions	-
Input parameter{in}	
adc_psc	ADC prescaler factor
<i>RCU_CKADC_CKAPB2_DIV2</i>	$CK_ADC = CK_APB2 / 2$
<i>RCU_CKADC_CKAPB2_DIV4</i>	$CK_ADC = CK_APB2 / 4$
<i>RCU_CKADC_CKAPB2_DIV6</i>	$CK_ADC = CK_APB2 / 6$
<i>RCU_CKADC_CKAPB2_DIV8</i>	$CK_ADC = CK_APB2 / 8$
<i>RCU_CKADC_CKAPB2_DIV12</i>	$CK_ADC = CK_APB2 / 12$
<i>RCU_CKADC_CKAPB2_DIV16</i>	$CK_ADC = CK_APB2 / 16$
<i>RCU_CKADC_CKAHB_DIV3</i>	$CK_ADC = CK_AHB / 3$
<i>RCU_CKADC_CKAHB_DIV5</i>	$CK_ADC = CK_AHB / 5$

<i>RCU_CKADC_CKAHB_DIV7</i>	$CK_ADC = CK_AHB / 7$
<i>RCU_CKADC_CKAHB_DIV9</i>	$CK_ADC = CK_AHB / 9$
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the ADC prescaler factor */
```

```
rcu_adc_clock_config(RCU_CKADC_CKAPB2_DIV8);
```

rcu_usb_clock_config

The description of rcu_usb_clock_config is shown as below:

Table 3-400. Function rcu_usb_clock_config

Function name	rcu_usb_clock_config
Function prototype	void rcu_usb_clock_config(uint32_t usb_psc);
Function descriptions	configure the USB prescaler factor
Precondition	-
The called functions	-
Input parameter{in}	
usb_psc	USB prescaler factor
<i>RCU_CKUSB_CKPLL_DIV1_5</i>	$CK_USBFS = CK_PLL / 1.5$
<i>RCU_CKUSB_CKPLL_DIV1</i>	$CK_USBFS = CK_PLL / 1$
<i>RCU_CKUSB_CKPLL_DIV2_5</i>	$CK_USBFS = CK_PLL / 2.5$
<i>RCU_CKUSB_CKPLL_DIV2</i>	$CK_USBFS = CK_PLL / 2$
<i>RCU_CKUSB_CKPLL_DIV3</i>	$CK_USBFS = CK_PLL / 3$
<i>RCU_CKUSB_CKPLL_DIV3_5</i>	$CK_USBFS = CK_PLL / 3.5$
<i>RCU_CKUSB_CKPLL_DIV4</i>	$CK_USBFS = CK_PLL / 4$
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the USB prescaler factor */

rcu_usb_clock_config(RCU_CKUSB_CKPLL_DIV2_5);
```

rcu_rtc_clock_config

The description of rcu_rtc_clock_config is shown as below:

Table 3-401. Function rcu_rtc_clock_config

Function name	rcu_rtc_clock_config
Function prototype	void rcu_rtc_clock_config(uint32_t rtc_clock_source);
Function descriptions	configure the RTC clock source selection
Precondition	-
The called functions	-
Input parameter{in}	
rtc_clock_source	RTC clock source selection
RCU_RTCSRC_NONE	no clock selected
RCU_RTCSRC_LXTAL	select CK_LXTAL as RTC source clock
RCU_RTCSRC_IRC40K	select CK_IRC40K as RTC source clock
RCU_RTCSRC_HXTAL_DIV_128	select CK_HXTAL/128 as RTC source clock
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the RTC clock source selection */

rcu_rtc_clock_config(RCU_RTCSRC_IRC40K);
```

rcu_i2s1_clock_config

The description of rcu_i2s1_clock_config is shown as below:

Table 3-402. Function rcu_i2s1_clock_config

Function name	rcu_i2s1_clock_config
Function prototype	void rcu_i2s1_clock_config(uint32_t i2s_clock_source);
Function descriptions	configure the I2S1 clock source selection
Precondition	-
The called functions	-
Input parameter{in}	
i2s_clock_source	I2S clock source selection

<i>RCU_I2S1SRC_CKSYS</i>	select system clock as I2S1 source clock
<i>RCU_I2S1SRC_CKPLL2_MUL2</i>	select CK_PLL2 * 2 as I2S1 source clock
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the I2S1 clock source selection */
```

```
rcu_i2s1_clock_config(RCU_I2S1SRC_CKPLL2_MUL2);
```

rcu_i2s2_clock_config

The description of rcu_i2s2_clock_config is shown as below:

Table 3-403. Function rcu_i2s2_clock_config

Function name	rcu_i2s2_clock_config
Function prototype	void rcu_i2s2_clock_config(uint32_t i2s_clock_source);
Function descriptions	configure the I2S2 clock source selection
Precondition	-
The called functions	-
Input parameter{in}	
i2s_clock_source	I2S clock source selection
<i>RCU_I2S2SRC_CKSYS</i>	select system clock as I2S2 source clock
<i>RCU_I2S2SRC_CKPLL2_MUL2</i>	select CK_PLL2 * 2 as I2S2 source clock
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the I2S2 clock source selection */
```

```
rcu_i2s2_clock_config(RCU_I2S2SRC_CKPLL2_MUL2);
```

rcu_ck48m_clock_config

The description of rcu_ck48m_clock_config is shown as below:

Table 3-404. Function rcu_ck48m_clock_config

Function name	rcu_ck48m_clock_config
----------------------	------------------------

Function prototype	void rcu_ck48m_clock_config(uint32_t ck48m_clock_source);
Function descriptions	configure the CK48M clock source selection
Precondition	-
The called functions	-
Input parameter{in}	
ck48m_clock_source	CK48M clock source selection
<i>RCU_CK48MSRC_CKPLL</i>	CK_PLL selected as CK48M source clock
<i>RCU_CK48MSRC_IRC48M</i>	CK_IRC48M selected as CK48M source clock
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the CK48M clock source selection */
rcu_ck48m_clock_config(RCU_CK48MSRC_CKPLL);
```

rcu_flag_get

The description of rcu_flag_get is shown as below:

Table 3-405. Function rcu_flag_get

Function name	rcu_flag_get
Function prototype	FlagStatus rcu_flag_get(rcu_flag_enum flag);
Function descriptions	get the clock stabilization and peripheral reset flags
Precondition	-
The called functions	-
Input parameter{in}	
flag	the clock stabilization and peripheral reset flags, refer to Table 3-372. Enum rcu_flag_enum
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get the clock stabilization flag */
if(RESET != rcu_flag_get(RCU_FLAG_LXTALSTB)){
}
```

rcu_all_reset_flag_clear

The description of rcu_all_reset_flag_clear is shown as below:

Table 3-406. Function rcu_all_reset_flag_clear

Function name	rcu_all_reset_flag_clear
Function prototype	void rcu_all_reset_flag_clear(void);
Function descriptions	clear all the reset flag
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear all the reset flag */
rcu_all_reset_flag_clear();
```

rcu_interrupt_flag_get

The description of rcu_interrupt_flag_get is shown as below:

Table 3-407. Function rcu_interrupt_flag_get

Function name	rcu_interrupt_flag_get
Function prototype	FlagStatus rcu_interrupt_flag_get(rcu_int_flag_enum int_flag);
Function descriptions	get the clock stabilization interrupt and ckm flags
Precondition	-
The called functions	-
Input parameter{in}	
int_flag	interrupt and ckm flags, refer to Table 3-373. Enum rcu_int_flag_enum
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get the clock stabilization interrupt flag */
if(SET == rcu_interrupt_flag_get(RCU_INT_FLAG_HXTALSTB)){
}
```

rcu_interrupt_flag_clear

The description of rcu_interrupt_flag_clear is shown as below:

Table 3-408. Function rcu_interrupt_flag_clear

Function name	rcu_interrupt_flag_clear
Function prototype	void rcu_interrupt_flag_clear(rcu_int_flag_clear_enum int_flag_clear)
Function descriptions	clear the interrupt flags
Precondition	-
The called functions	-
Input parameter{in}	
int_flag_clear	clock stabilization and stuck interrupt flags clear, refer to Table 3-374. Enum rcu_int_flag_clear_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear the interrupt HXTAL stabilization interrupt flag */
rcu_interrupt_flag_clear(RCU_INT_FLAG_HXTALSTB_CLR);
```

rcu_interrupt_enable

The description of rcu_interrupt_enable is shown as below:

Table 3-409. Function rcu_interrupt_enable

Function name	rcu_interrupt_enable
Function prototype	void rcu_interrupt_enable(rcu_int_enum stab_int);
Function descriptions	enable the stabilization interrupt
Precondition	-
The called functions	-
Input parameter{in}	
stab_int	clock stabilization interrupt, refer to Table 3-375. Enum rcu_int_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the HXTAL stabilization interrupt */
rcu_interrupt_enable(RCU_INT_HXTALSTB);
```

rcu_interrupt_disable

The description of rcu_interrupt_disable is shown as below:

Table 3-410. Function rcu_interrupt_disable

Function name	rcu_interrupt_disable
Function prototype	void rcu_interrupt_disable(rcu_int_enum stab_int);
Function descriptions	disable the stabilization interrupt
Precondition	-
The called functions	-
Input parameter{in}	
stab_int	clock stabilization interrupt, refer to Table 3-375. Enum rcu_int_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the HXTAL stabilization interrupt */
rcu_interrupt_disable(RCU_INT_HXTALSTB);
```

rcu_lxtal_drive_capability_config

The description of rcu_lxtal_drive_capability_config is shown as below:

Table 3-411. Function rcu_lxtal_drive_capability_config

Function name	rcu_lxtal_drive_capability_config
Function prototype	void rcu_lxtal_drive_capability_config(uint32_t lxtal_dricap);
Function descriptions	configure the LXTAL drive capability
Precondition	-
The called functions	-
Input parameter{in}	
lxtal_dricap	drive capability of LXTAL
<i>RCU_LXTAL_LOWDRI</i>	lower driving capability
<i>RCU_LXTAL_MED_LOWDRI</i>	medium low driving capability
<i>RCU_LXTAL_MED_HI_GHDRI</i>	medium high driving capability
<i>RCU_LXTAL_HIGHDRI</i>	higher driving capability
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the LXTAL drive capability */  
  
rcu_lxtal_drive_capability_config (RCU_LXTAL_LOWDRI);
```

rcu_osci_stab_wait

The description of rcu_osci_stab_wait is shown as below:

Table 3-412. Function rcu_osci_stab_wait

Function name	rcu_osci_stab_wait
Function prototype	ErrStatus rcu_osci_stab_wait(rcu_osci_type_enum osci);
Function descriptions	wait for oscillator stabilization flags is SET or oscillator startup is timeout
Precondition	-
The called functions	-
Input parameter{in}	
osci	oscillator types, refer to Table 3-376. Enum rcu_osci_type_enum
Output parameter{out}	
-	-
Return value	
ErrStatus	SUCCESS or ERROR

Example:

```
/* wait for oscillator stabilization flag */  
  
if(SUCCESS == rcu_osci_stab_wait(RCU_HXTAL)){  
  
}
```

rcu_osci_on

The description of rcu_osci_on is shown as below:

Table 3-413. Function rcu_osci_on

Function name	rcu_osci_on
Function prototype	void rcu_osci_on(rcu_osci_type_enum osci);
Function descriptions	turn on the oscillator
Precondition	-
The called functions	-
Input parameter{in}	
osci	oscillator types, refer to Table 3-376. Enum rcu_osci_type_enum
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* turn on the high speed crystal oscillator */  
  
rcu_osci_on(RCU_HXTAL);
```

rcu_osci_off

The description of rcu_osci_off is shown as below:

Table 3-414. Function rcu_osci_off

Function name	rcu_osci_off
Function prototype	void rcu_osci_off(rcu_osci_type_enum osci);
Function descriptions	turn off the oscillator
Precondition	-
The called functions	-
Input parameter{in}	
osci	oscillator types, refer to Table 3-376. Enum rcu_osci_type_enum
RCU_HXTAL	high speed crystal oscillator(HXTAL)
RCU_LXTAL	low speed crystal oscillator(LXTAL)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* turn off the high speed crystal oscillator */  
  
rcu_osci_off(RCU_HXTAL);
```

rcu_osci_bypass_mode_enable

The description of rcu_osci_bypass_mode_enable is shown as below:

Table 3-415. Function rcu_osci_bypass_mode_enable

Function name	rcu_osci_bypass_mode_enable
Function prototype	void rcu_osci_bypass_mode_enable(rcu_osci_type_enum osci);
Function descriptions	enable the oscillator bypass mode
Precondition	HXTALEN or LXTALEN must be reset before it
The called functions	-
Input parameter{in}	
osci	oscillator types, refer to Table 3-376. Enum rcu_osci_type_enum
RCU_HXTAL	high speed crystal oscillator(HXTAL)
RCU_LXTAL	low speed crystal oscillator(LXTAL)
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* enable the high speed crystal oscillator bypass mode */
```

```
rcu_osci_bypass_mode_enable(RCU_HXTAL);
```

rcu_osci_bypass_mode_disable

The description of rcu_osci_bypass_mode_disable is shown as below:

Table 3-416. Function rcu_osci_bypass_mode_disable

Function name	rcu_osci_bypass_mode_disable
Function prototype	void rcu_osci_bypass_mode_disable(rcu_osci_type_enum osci);
Function descriptions	disable the oscillator bypass mode
Precondition	HXTALEN or LXTALEN must be reset before it
The called functions	-
Input parameter{in}	
osci	oscillator types, refer to Table 3-376. Enum rcu_osci_type_enum
RCU_HXTAL	high speed crystal oscillator(HXTAL)
RCU_LXTAL	low speed crystal oscillator(LXTAL)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the high speed crystal oscillator bypass mode */
```

```
rcu_osci_bypass_mode_disable(RCU_HXTAL);
```

rcu_hxtal_clock_monitor_enable

The description of rcu_hxtal_clock_monitor_enable is shown as below:

Table 3-417. Function rcu_hxtal_clock_monitor_enable

Function name	rcu_hxtal_clock_monitor_enable
Function prototype	void rcu_hxtal_clock_monitor_enable(void);
Function descriptions	enable the HXTAL clock monitor
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* enable the HXTAL clock monitor */
```

```
rcu_hxtal_clock_monitor_enable();
```

rcu_hxtal_clock_monitor_disable

The description of rcu_hxtal_clock_monitor_disable is shown as below:

Table 3-418. Function rcu_hxtal_clock_monitor_disable

Function name	rcu_hxtal_clock_monitor_disable
Function prototype	void rcu_hxtal_clock_monitor_disable(void);
Function descriptions	disable the HXTAL clock monitor
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the HXTAL clock monitor */
```

```
rcu_hxtal_clock_monitor_disable();
```

rcu_irc8m_adjust_value_set

The description of rcu_irc8m_adjust_value_set is shown as below:

Table 3-419. Function rcu_irc8m_adjust_value_set

Function name	rcu_irc8m_adjust_value_set
Function prototype	void rcu_irc8m_adjust_value_set(uint32_t irc8m_adjval);
Function descriptions	set the IRC8M adjust value
Precondition	-
The called functions	-
Input parameter{in}	
irc8m_adjval	IRC8M adjust value, must be between 0 and 0x1F
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set the IRC8M adjust value */  
  
rcu_irc8m_adjust_value_set(0x10);
```

rcu_deepsleep_voltage_set

The description of rcu_deepsleep_voltage_set is shown as below:

Table 3-420. Function rcu_deepsleep_voltage_set

Function name	rcu_deepsleep_voltage_set
Function prototype	void rcu_deepsleep_voltage_set(uint32_t dsvol);
Function descriptions	set the deep-sleep mode voltage value
Precondition	-
The called functions	-
Input parameter{in}	
dsvol	deep sleep mode voltage
RCU_DEEPSLEEP_V_1_0	the core voltage is 1.0V in deep-sleep mode
RCU_DEEPSLEEP_V_0_9	the core voltage is 0.9V in deep-sleep mode
RCU_DEEPSLEEP_V_0_8	the core voltage is 0.8V in deep-sleep mode
RCU_DEEPSLEEP_V_1_2	the core voltage is 1.2V in deep-sleep mode
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set the deep-sleep mode voltage */  
  
rcu_deepsleep_voltage_set(RCU_DEEPSLEEP_V_1_0);
```

rcu_clock_freq_get

The description of rcu_clock_freq_get is shown as below:

Table 3-421. Function rcu_clock_freq_get

Function name	rcu_clock_freq_get
Function prototype	uint32_t rcu_clock_freq_get(rcu_clock_freq_enum clock);
Function descriptions	get the system clock, bus clock frequency
Precondition	-
The called functions	-

Input parameter{in}	
clock	the clock frequency which to get
<i>CK_SYS</i>	system clock frequency
<i>CK_AHB</i>	AHB clock frequency
<i>CK_APB1</i>	APB1 clock frequency
<i>CK_APB2</i>	APB2 clock frequency
Output parameter{out}	
-	-
Return value	
ck_freq	clock frequency of system, AHB, APB1, APB2

Example:

```
uint32_t temp_freq;

/* get the system clock frequency */

temp_freq = rcu_clock_freq_get(CK_SYS);
```

3.19. RTC

The Real-time Clock (RTC) is usually used as a clock-calendar. The ones in the Backup Domain consist of a 32-bit up-counter, an alarm, a prescaler, a divider and the RTC clock configuration register. The RTC registers are listed in chapter [3.19.1](#), the FWDGT firmware functions are introduced in chapter [3.19.2](#).

3.19.1. Descriptions of Peripheral registers

RTC registers are listed in the table shown as below:

Table 3-422. RTC Registers

Registers	Descriptions
RTC_INTEN	Interrupt enable register
RTC_CTL	Control register
RTC_PSCH	Prescaler high register
RTC_PSCL	Prescaler low register
RTC_DIVH	Divider high register
RTC_DIVL	Divider low register
RTC_CNTH	counter high register
RTC_CNTL	counter low register
RTC_ALRMH	Alarm high register
RTC_ALRML	Alarm low register

3.19.2. Descriptions of Peripheral functions

RTC firmware functions are listed in the table shown as below:

Table 3-423. RTC firmware function

Function name	Function description
rtc_configuration_mode_enter	enter RTC configuration mode
rtc_configuration_mode_exit	exit RTC configuration mode
rtc_counter_set	set RTC counter value
rtc_prescaler_set	set RTC prescaler value
rtc_lwoff_wait	wait RTC last write operation finished flag set
rtc_register_sync_wait	wait RTC registers synchronized flag set
rtc_alarm_config	set RTC alarm value
rtc_counter_get	get RTC counter value
rtc_divider_get	get RTC divider value
rtc_flag_get	get RTC flag status
rtc_flag_clear	clear RTC flag status
rtc_interrupt_flag_get	get RTC interrupt flag status
rtc_interrupt_flag_clear	clear RTC interrupt flag status
rtc_interrupt_enable	enable RTC interrupt
rtc_interrupt_disable	disable RTC interrupt

rtc_configuration_mode_enter

The description of rtc_configuration_mode_enter is shown as below:

Table 3-424. Function rtc_configuration_mode_enter

Function name	rtc_configuration_mode_enter
Function prototype	void rtc_configuration_mode_enter(void);
Function descriptions	enter RTC configuration mode
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enter RTC configuration mode */
rtc_configuration_mode_enter( );
```

rtc_configuration_mode_exit

The description of rtc_configuration_mode_exit is shown as below:

Table 3-425. Function rtc_configuration_mode_exit

Function name	rtc_configuration_mode_exit
Function prototype	void rtc_configuration_mode_exit(void);
Function descriptions	exit RTC configuration mode
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* exit RTC configuration mode */
rtc_configuration_mode_exit ( );
```

rtc_counter_set

The description of rtc_counter_set is shown as below:

Table 3-426. Function rtc_counter_set

Function name	rtc_counter_set
Function prototype	void rtc_counter_set(uint32_t cnt);
Function descriptions	set RTC counter value
Precondition	-
The called functions	-
Input parameter{in}	
cnt	RTC counter value (0-0xFFFF FFFF)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* wait until last write operation on RTC registers has finished */
rtc_lwoff_wait( );

/* set counter value to 0xFFFF */
rtc_counter_set (0xFFFF);
```

rtc_prescaler_set

The description of rtc_prescaler_set is shown as below:

Table 3-427. Function rtc_prescaler_set

Function name	rtc_interrupt_rtc_prescaler_set
Function prototype	void rtc_prescaler_set(uint32_t psc);
Function descriptions	set RTC prescaler value
Precondition	before using this function, you must call rtc_lwoff_wait () function (wait until LWOFF flag is set).
The called functions	rtc_configuration_mode_enter / rtc_configuration_mode_exit
Input parameter{in}	
psc	RTC prescaler value (0-0x000F FFFF)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* wait until last write operation on RTC registers has finished */
rtc_lwoff_wait( );

/* set RTC prescaler value to 0x7FFFF */
rtc_prescaler_set (0x7FFFF);
```

rtc_lwoff_wait

The description of rtc_lwoff_wait is shown as below:

Table 3-428. Function rtc_lwoff_wait

Function name	rtc_lwoff_wait
Function prototype	void rtc_lwoff_wait(void);
Function descriptions	wait RTC last write operation finished flag set
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* wait until last write operation on RTC registers has finished */
```

```
rtc_lwoff_wait( );

/* enable the RTC second interrupt */

rtc_interrupt_enable(RTC_INT_SECOND);
```

rtc_register_sync_wait

The description of rtc_register_sync_wait is shown as below:

Table 3-429. Function rtc_register_sync_wait

Function name	rtc_register_sync_wait
Function prototype	void rtc_register_sync_wait(void);
Function descriptions	wait RTC registers synchronized flag set
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* wait for RTC registers synchronization */

rtc_register_sync_wait( );
```

rtc_alarm_config

The description of rtc_alarm_config is shown as below:

Table 3-430. Function rtc_alarm_config

Function name	rtc_alarm_config
Function prototype	void rtc_alarm_config(uint32_t alarm);
Function descriptions	set RTC alarm value
Precondition	before using this function, you must call rtc_lwoff_wait () function (wait until LWOFF flag is set). -
The called functions	rtc_configuration_mode_enter / rtc_configuration_mode_exit
Input parameter{in}	
alarm	RTC alarm value (0-0xFFFF FFFF)
Output parameter{out}	
-	-
Return value	
-	-

Example:

/* wait until last write operation on RTC registers has finished */

```
rtc_lwoff_wait( );
```

/* set alarm value to 0xFFFF */

```
rtc_alarm_config (0xFFFF);
```

rtc_counter_get

The description of rtc_counter_get is shown as below:

Table 3-431. Function rtc_counter_get

Function name	rtc_counter_get
Function prototype	uint32_t rtc_counter_get(void);
Function descriptions	get RTC counter value
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint32_t	the value of RTC counter

Example:

/* get the counter value */

```
uint32_t rtc_counter_value;
```

```
rtc_counter_value = rtc_counter_get ( );
```

rtc_divider_get

The description of rtc_divider_get is shown as below:

Table 3-432. Function rtc_divider_get

Function name	rtc_divider_get
Function prototype	uint32_t rtc_divider_get(void);
Function descriptions	get RTC divider value
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	

uint32_t	the value of RTC divider
-----------------	--------------------------

Example:

```
/* get the current RTC divider value */

uint32_t rtc_divider_value;

rtc_divider_value = rtc_divider_get ( );
```

rtc_flag_get

The description of rtc_flag_getrtc_interrupt_enable is shown as below:

Table 3-433. Function rtc_flag_get

Function name	rtc_flag_get
Function prototype	FlagStatus rtc_flag_get(uint32_t flag);
Function descriptions	get RTC flag status
Precondition	-
The called functions	-
Input parameter{in}	
flag	specify which RTC flag status to get
<i>RTC_FLAG_SECOND</i>	second interrupt flag
<i>RTC_FLAG_ALARM</i>	alarm interrupt flag
<i>RTC_FLAG_OVERFLOW W</i>	overflow interrupt flag
<i>RTC_FLAG_RSYN</i>	registers synchronized flag
<i>RTC_FLAG_LWOF</i>	last write operation finished flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get the RTC overflow interrupt status */

FlagStatus alarm_status;

alarm_status = rtc_flag_get (RTC_FLAG_ALARM);
```

rtc_flag_clear

The description of rtc_flag_clear is shown as below:

Table 3-434. Function rtc_flag_clear

Function name	rtc_flag_clear
Function prototype	void rtc_flag_clear(uint32_t flag);
Function descriptions	clear RTC flag status

Precondition	-
The called functions	-
Input parameter{in}	
flag	specify which RTC flag status to clear
<i>RTC_FLAG_SECOND</i>	second interrupt flag
<i>RTC_FLAG_ALARM</i>	alarm interrupt flag
<i>RTC_FLAG_OVERFLOW</i>	overflow interrupt flag
<i>RTC_FLAG_RSYN</i>	registers synchronized flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear the RTC alarm flag */
```

```
rtc_flag_clear (RTC_FLAG_ALARM);
```

rtc_interrupt_flag_get

The description of `rtc_interrupt_flag_get` is shown as below:

Table 3-435. Function `rtc_interrupt_flag_get`

Function name	<code>rtc_interrupt_flag_get</code>
Function prototype	<code>FlagStatus rtc_interrupt_flag_get(uint32_t flag);</code>
Function descriptions	get RTC interrupt flag status
Precondition	-
The called functions	-
Input parameter{in}	
flag	specify which RTC interrupt flag status to get
<i>RTC_INT_FLAG_SECOND</i>	second interrupt flag
<i>RTC_INT_FLAG_ALARM</i>	alarm interrupt flag
<i>RTC_INT_FLAG_OVERFLOW</i>	overflow interrupt flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get the RTC alarm interrupt status */
```

```
FlagStatus alarm_status;
```

```
alarm_status = rtc_interrupt_flag_get (RTC_INT_FLAG_ALARM);
```

rtc_interrupt_flag_clear

The description of rtc_interrupt_flag_clear is shown as below:

Table 3-436. Function rtc_interrupt_flag_clear

Function name	rtc_interrupt_flag_clear
Function prototype	void rtc_interrupt_flag_clear(uint32_t flag);
Function descriptions	clear RTC interrupt flag status
Precondition	-
The called functions	-
Input parameter{in}	
flag	specify which RTC interrupt flag status to clear
<i>RTC_INT_FLAG_SEC OND</i>	second interrupt flag
<i>RTC_INT_FLAG_ALAR M</i>	alarm interrupt flag
<i>RTC_INT_FLAG_OVE RFLOW</i>	overflow interrupt flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear the RTC alarm interrupt flag */
```

```
rtc_interrupt_flag_clear (RTC_INT_FLAG_ALARM);
```

rtc_interrupt_enable

The description of rtc_interrupt_enable is shown as below:

Table 3-437. Function rtc_interrupt_enable

Function name	rtc_interrupt_enable
Function prototype	void rtc_interrupt_enable(uint32_t interrupt);
Function descriptions	enable RTC interrupt
Precondition	before using this function, you must call rtc_lwoff_wait () function (wait until LWOFF flag is set).
The called functions	-
Input parameter{in}	
interrupt	specify which RTC interrupt to enable
<i>RTC_INT_SECOND</i>	second interrupt

<i>RTC_INT_ALARM</i>	alarm interrupt
<i>RTC_INT_OVERFLOW</i>	overflow interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* wait until last write operation on RTC registers has finished */
```

```
rtc_lwoff_wait( );
```

```
/* enable the RTC second interrupt */
```

```
rtc_interrupt_enable(RTC_INT_SECOND);
```

rtc_interrupt_disable

The description of `rtc_interrupt_disable` is shown as below:

Table 3-438. Function `rtc_interrupt_disable`

Function name	<code>rtc_interrupt_disable</code>
Function prototype	<code>void rtc_interrupt_disable(uint32_t interrupt);</code>
Function descriptions	disable RTC interrupt
Precondition	before using this function, you must call <code>rtc_lwoff_wait ()</code> function (wait until LWOFF flag is set).
The called functions	-
Input parameter{in}	
interrupt	specify which RTC interrupt to disable
<i>RTC_INT_SECOND</i>	second interrupt
<i>RTC_INT_ALARM</i>	alarm interrupt
<i>RTC_INT_OVERFLOW</i>	overflow interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* wait until last write operation on RTC registers has finished */
```

```
rtc_lwoff_wait( );
```

```
/* disable the RTC second interrupt */
```

```
rtc_interrupt_disable(RTC_INT_SECOND);
```

3.20. SPI

The SPI/I2S module can communicate with external devices using the SPI protocol or the I2S audio protocol. The SPI/I2S registers are listed in chapter [3.20.1](#), the SPI/I2S firmware functions are introduced in chapter [3.20.2](#).

3.20.1. Descriptions of Peripheral registers

SPI/I2S registers are listed in the table shown as below:

Table 3-439. SPI/I2S Registers

Registers	Descriptions
SPI_CTL0	SPI control register 0
SPI_CTL1	SPI control register 1
SPI_STAT	SPI status register
SPI_DATA	SPI data register
SPI_CRCPOLY	SPI CRC polynomial register
SPI_RCRC	SPI receive CRC register
SPI_TCRC	SPI transmit CRC register
SPI_I2SCTL	SPI/I2S control register
SPI_I2SPSC	SPI/I2S clock prescaler register
SPI_QCTL	Quad-SPI mode control register

3.20.2. Descriptions of Peripheral functions

SPI/I2S firmware functions are listed in the table shown as below:

Table 3-440. SPI/I2S firmware function

Function name	Function description
spi_i2s_deinit	reset SPI and I2S peripheral
spi_struct_para_init	initialize the parameters of SPI struct with the default values
spi_init	initialize SPI peripheral parameter
spi_enable	enable SPI
spi_disable	disable SPI
i2s_init	initialize I2S peripheral parameter
i2s_psc_config	configure I2S peripheral prescaler
i2s_enable	enable I2S
i2s_disable	disable I2S
spi_nss_output_enable	enable SPI NSS output function
spi_nss_output_disable	disable SPI NSS output function
spi_nss_internal_high	SPI NSS pin high level in software mode
spi_nss_internal_low	SPI NSS pin low level in software mode
spi_dma_enable	enable SPI DMA function
spi_dma_disable	disable SPI DMA function
spi_i2s_data_frame_format_config	configure SPI/I2S data frame format
spi_i2s_data_transmit	SPI transmit data
spi_i2s_data_receive	SPI receive data
spi_bidirectional_transfer_config	configure SPI bidirectional transfer direction
spi_crc_polynomial_set	set SPI CRC polynomial
spi_crc_polynomial_get	get SPI CRC polynomial
spi_crc_on	turn on SPI CRC function
spi_crc_off	turn off SPI CRC function
spi_crc_next	SPI next data is CRC value
spi_crc_get	get SPI CRC send value or receive value
spi_ti_mode_enable	enable SPI TI mode
spi_ti_mode_disable	disable SPI TI mode
spi_nssp_mode_enable	enable SPI NSS pulse mode
spi_nssp_mode_disable	disable SPI NSS pulse mode
spi_quad_enable	enable quad wire SPI
spi_quad_disable	disable quad wire SPI
spi_quad_write_enable	enable quad wire SPI write
spi_quad_read_enable	enable quad wire SPI read
spi_quad_io23_output_enable	enable quad wire SPI_IO2 and SPI_IO3 pin output
spi_quad_io23_output_disable	disable quad wire SPI_IO2 and SPI_IO3 pin output
spi_i2s_interrupt_enable	enable SPI and I2S interrupt
spi_i2s_interrupt_disable	disable SPI and I2S interrupt
spi_i2s_interrupt_flag_get	get SPI and I2S interrupt status
spi_i2s_flag_get	get SPI and I2S flag status
spi_crc_error_clear	clear SPI CRC error flag status

Structure spi_parameter_struct

Table 3-441. spi_parameter_struct

Member name	Function description
device_mode	SPI master or slave (SPI_MASTER, SPI_SLAVE)
trans_mode	SPI transtype (SPI_TRANSMODE_FULLDUPLEX, SPI_TRANSMODE_RECEIVEONLY, SPI_TRANSMODE_BDRECEIVE, SPI_TRANSMODE_BDTRANSMIT)
frame_size	SPI frame size (SPI_FRAME_SIZE_16BIT, SPI_FRAME_SIZE_8BIT)
nss	SPI NSS control by hardware or software (SPI_NSS_SOFT, SPI_NSS_HARD)
endian	SPI big endian or little endian (SPI_ENDIAN_MSB, SPI_ENDIAN_LSB)
clock_polarity_phase	SPI clock phase and polarity (SPI_CLOCK_PL_LOW_PH_1EDGE, SPI_CLOCK_PL_HIGH_PH_1EDGE, SPI_CLOCK_PL_LOW_PH_2EDGE, SPI_CLOCK_PL_HIGH_PH_2EDGE)
prescale	SPI prescale factor (SPI_PSC_n (n=2,4,8,16,32,64,128,256))

spi_i2s_deinit

The description of spi_i2s_deinit is shown as below:

Table 3-442. Function spi_i2s_deinit

Function name	spi_i2s_deinit
Function prototype	void spi_i2s_deinit(uint32_t spi_periph);
Function descriptions	reset SPI and I2S peripheral
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Input parameter{in}	
spi_periph	SPI/I2S peripheral
<i>SPIx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset SPI0 */
spi_i2s_deinit(SPI0);
```

spi_struct_para_init

The description of spi_struct_para_init is shown as below:

Table 3-443. Function spi_struct_para_init

Function name	spi_struct_para_init
Function prototype	void spi_struct_para_init(spi_parameter_struct* spi_struct);
Function descriptions	initialize the parameters of SPI struct with the default values
Precondition	-
The called functions	-
Input parameter{in}	
*spi_struct	a spi_parameter_struct address
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* initialize the parameters of SPI */
spi_parameter_struct spi_init_struct;
spi_struct_para_init(&spi_init_struct);
```

spi_init

The description of spi_init is shown as below:

Table 3-444. Function spi_init

Function name	spi_init
Function prototype	void spi_init(uint32_t spi_periph, spi_parameter_struct* spi_struct);
Function descriptions	initialize SPI peripheral parameter
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Input parameter{in}	
spi_struct	SPI parameter initialization struct, the structure members can refer to members of the structure Table 3-441. spi_parameter_struct
Output parameter{out}	
-	-
Return value	
-	-

Example:


```
/* initialize SPI0 */
```

```
spi_parameter_struct spi_init_struct;
```

```
spi_init_struct.trans_mode      = SPI_TRANSMODE_BDTRANSMIT;
```

```
spi_init_struct.device_mode     = SPI_MASTER;
```

```
spi_init_struct.frame_size      = SPI_FRAME_SIZE_8BIT;
```

```
spi_init_struct.clock_polarity_phase = SPI_CK_PL_HIGH_PH_2EDGE;
```

```
spi_init_struct.nss             = SPI_NSS_SOFT;
```

```
spi_init_struct.prescale        = SPI_PSC_8;
```

```
spi_init_struct.endian          = SPI_ENDIAN_MSB;
```

```
spi_init(SPI0, &spi_init_struct);
```

spi_enable

The description of spi_enable is shown as below:

Table 3-445. Function spi_enable

Function name	spi_enable
Function prototype	void spi_enable(uint32_t spi_periph);
Function descriptions	enable SPI
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable SPI0 */
```

```
spi_enable(SPI0);
```

spi_disable

The description of spi_disable is shown as below:

Table 3-446. Function spi_disable

Function name	spi_disable
Function prototype	void spi_disable(uint32_t spi_periph);

Function descriptions	disable SPI
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable SPI0 */
spi_disable(SPI0);
```

i2s_init

The description of i2s_init is shown as below:

Table 3-447. Function i2s_init

Function name	i2s_init
Function prototype	void i2s_init(uint32_t spi_periph, uint32_t mode, uint32_t standard, uint32_t ckpl);
Function descriptions	initialize I2S peripheral parameter
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	I2S peripheral
<i>SPIx</i>	x=1,2
Input parameter{in}	
mode	I2S operation mode
<i>I2S_MODE_SLAVETX</i>	I2S slave transmit mode
<i>I2S_MODE_SLAVEX</i>	I2S slave receive mode
<i>I2S_MODE_MASTERTX</i>	I2S master transmit mode
<i>I2S_MODE_MASTERR</i>	I2S master receive mode
Input parameter{in}	
standard	I2S standard
<i>I2S_STD_PHILLIPS</i>	I2S phillips standard
<i>I2S_STD_MSB</i>	I2S MSB standard
<i>I2S_STD_LSB</i>	I2S LSB standard
<i>I2S_STD_PCMSHORT</i>	I2S PCM short standard

<i>I2S_STD_PCMLONG</i>	I2S PCM long standard
Input parameter{in}	
ckpl	I2S idle state clock polarity
<i>I2S_CKPL_LOW</i>	I2S clock polarity low level
<i>I2S_CKPL_HIGH</i>	I2S clock polarity high level
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* initialize I2S1 */
```

```
i2s_init(SPI1, I2S_MODE_MASTERTX, I2S_STD_PHILLIPS, I2S_CKPL_LOW);
```

i2s_psc_config

The description of i2s_psc_config is shown as below:

Table 3-448. Function i2s_psc_config

Function name	i2s_psc_config
Function prototype	void i2s_psc_config(uint32_t spi_periph, uint32_t audiosample, uint32_t frameformat, uint32_t mckout);
Function descriptions	configure I2S prescaler
Precondition	-
The called functions	rcu_clock_freq_get
Input parameter{in}	
spi_periph	I2S peripheral
<i>SPIx</i>	x=1,2
Input parameter{in}	
audiosample	I2S audio sample rate
<i>I2S_AUDIOSAMPLE_8K</i>	audio sample rate is 8KHz
<i>I2S_AUDIOSAMPLE_11K</i>	audio sample rate is 11KHz
<i>I2S_AUDIOSAMPLE_16K</i>	audio sample rate is 16KHz
<i>I2S_AUDIOSAMPLE_22K</i>	audio sample rate is 22KHz
<i>I2S_AUDIOSAMPLE_32K</i>	audio sample rate is 32KHz
<i>I2S_AUDIOSAMPLE_44K</i>	audio sample rate is 44KHz
<i>I2S_AUDIOSAMPLE_48K</i>	audio sample rate is 48KHz

8K	
I2S_AUDIOSAMPLE_9 6K	audio sample rate is 96KHz
I2S_AUDIOSAMPLE_1 92K	audio sample rate is 192KHz
Input parameter{in}	
frameformat	I2S data length and channel length
I2S_FRAMEFORMAT_ DT16B_CH16B	I2S data length is 16 bit and channel length is 16 bit
I2S_FRAMEFORMAT_ DT16B_CH32B	I2S data length is 16 bit and channel length is 32 bit
I2S_FRAMEFORMAT_ DT24B_CH32B	I2S data length is 24 bit and channel length is 32 bit
I2S_FRAMEFORMAT_ DT32B_CH32B	I2S data length is 32 bit and channel length is 32 bit
Input parameter{in}	
mckout	I2S master clock output
I2S_MCKOUT_ENABL E	I2S master clock output enable
I2S_MCKOUT_DISABL E	I2S master clock output disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure I2S1 prescaler */
```

```
i2s_psc_config(SPI1, I2S_AUDIOSAMPLE_44K, I2S_FRAMEFORMAT_DT16B_CH16B,  
I2S_MCKOUT_DISABLE);
```

i2s_enable

The description of i2s_enable is shown as below:

Table 3-449. Function i2s_enable

Function name	i2s_enable
Function prototype	void i2s_enable(uint32_t spi_periph);
Function descriptions	enable I2S
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	I2S peripheral

<i>SPIx</i>	<i>x</i> =1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable I2S1*/
i2s_enable(SPI1);
```

i2s_disable

The description of i2s_disable is shown as below:

Table 3-450. Function i2s_disable

Function name	i2s_disable
Function prototype	void i2s_disable(uint32_t spi_periph);
Function descriptions	disable I2S
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	I2S peripheral
<i>SPIx</i>	<i>x</i> =1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable I2S1*/
i2s_disable(SPI1);
```

spi_nss_output_enable

The description of spi_nss_output_enable is shown as below:

Table 3-451. Function spi_nss_output_enable

Function name	spi_nss_output_enable
Function prototype	void spi_nss_output_enable(uint32_t spi_periph);
Function descriptions	enable SPI NSS output function
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral

<i>SPIx</i>	<i>x=0,1,2</i>
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable SPI0 NSS output */
spi_nss_output_enable(SPI0);
```

spi_nss_output_disable

The description of spi_nss_output_disable is shown as below:

Table 3-452. Function spi_nss_output_disable

Function name	spi_nss_output_disable
Function prototype	void spi_nss_output_disable(uint32_t spi_periph);
Function descriptions	disable SPI NSS output function
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	<i>x=0,1,2</i>
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable SPI0 NSS output */
spi_nss_output_disable(SPI0);
```

spi_nss_internal_high

The description of spi_nss_internal_high is shown as below:

Table 3-453. Function spi_nss_internal_high

Function name	spi_nss_internal_high
Function prototype	void spi_nss_internal_high(uint32_t spi_periph);
Function descriptions	SPI NSS pin high level in software mode
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral

<i>SPIx</i>	<i>x=0,1,2</i>
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* SPI0 NSS pin is pulled high level in software mode */
```

```
spi_nss_internal_high(SPI0);
```

spi_nss_internal_low

The description of spi_nss_internal_low is shown as below:

Table 3-454. Function spi_nss_internal_low

Function name	spi_nss_internal_low
Function prototype	void spi_nss_internal_low(uint32_t spi_periph);
Function descriptions	SPI NSS pin low level in software mode
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	<i>x=0,1,2</i>
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* SPI0 NSS pin is pulled low level in software mode */
```

```
spi_nss_internal_low(SPI0);
```

spi_dma_enable

The description of spi_dma_enable is shown as below:

Table 3-455. Function spi_dma_enable

Function name	spi_dma_enable
Function prototype	void spi_dma_enable(uint32_t spi_periph, uint8_t dma);
Function descriptions	enable SPI DMA function
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral

<i>SPIx</i>	x=0,1,2
Input parameter{in}	
dma	SPI DMA mode
<i>SPI_DMA_TRANSMIT</i>	SPI transmit data use DMA
<i>SPI_DMA_RECEIVE</i>	SPI receive data use DMA
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable SPI0 transmit data DMA function */
spi_dma_enable(SPI0, SPI_DMA_TRANSMIT);
```

spi_dma_disable

The description of spi_dma_disable is shown as below:

Table 3-456. Function spi_dma_disable

Function name	spi_dma_disable
Function prototype	void spi_dma_disable(uint32_t spi_periph, uint8_t dma);
Function descriptions	disable SPI DMA function
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Input parameter{in}	
dma	SPI DMA mode
<i>SPI_DMA_TRANSMIT</i>	SPI transmit data use DMA
<i>SPI_DMA_RECEIVE</i>	SPI receive data use DMA
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable SPI0 transmit data DMA function */
spi_dma_disable(SPI0, SPI_DMA_TRANSMIT);
```

spi_i2s_data_frame_format_config

The description of spi_i2s_data_frame_format_config is shown as below:

Table 3-457. Function spi_i2s_data_frame_format_config

Function name	spi_i2s_data_frame_format_config
Function prototype	void spi_i2s_data_frame_format_config(uint32_t spi_periph, uint16_t frame_format);
Function descriptions	configure SPI/I2S data frame format
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Input parameter{in}	
frame_format	SPI frame size
<i>SPI_FRAME_SIZE_16BIT</i>	SPI frame size is 16 bits
<i>SPI_FRAME_SIZE_8BIT</i>	SPI frame size is 8 bits
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure SPI1/I2S1 data frame format size is 16 bits */
```

```
spi_i2s_data_frame_format_config(SPI1, SPI_FRAME_SIZE_16BIT);
```

spi_i2s_data_transmit

The description of spi_i2s_data_transmit is shown as below:

Table 3-458. Function spi_i2s_data_transmit

Function name	spi_i2s_data_transmit
Function prototype	void spi_i2s_data_transmit(uint32_t spi_periph, uint16_t data);
Function descriptions	SPI transmit data
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Input parameter{in}	
data	16-bit data
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* SPI0 transmit data */
```

```
spi_i2s_data_transmit(SPI0, spi0_send_array[send_n]);
```

spi_i2s_data_receive

The description of spi_i2s_data_receive is shown as below:

Table 3-459. Function spi_i2s_data_receive

Function name	spi_i2s_data_receive
Function prototype	uint16_t spi_i2s_data_receive(uint32_t spi_periph);
Function descriptions	SPI receive data
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
uint16_t	16-bit data

Example:

```
/* SPI0 receive data */
```

```
spi0_receive_array[receive_n] = spi_i2s_data_receive(SPI0);
```

spi_bidirectional_transfer_config

The description of spi_bidirectional_transfer_config is shown as below:

Table 3-460. Function spi_bidirectional_transfer_config

Function name	spi_bidirectional_transfer_config
Function prototype	void spi_bidirectional_transfer_config(uint32_t spi_periph, uint32_t transfer_direction);
Function descriptions	configure SPI bidirectional transfer direction
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Input parameter{in}	
transfer_direction	SPI transfer direction
<i>SPI_BIDIRECTIONAL_</i>	SPI work in transmit-only mode

<i>TRANSMIT</i>	
<i>SPI_BIDIRECTIONAL_RECEIVE</i>	SPI work in receive-only mode
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* SPI0 works in transmit-only mode */
```

```
spi_bidirectional_transfer_config(SPI0, SPI_BIDIRECTIONAL_TRANSMIT);
```

spi_crc_polynomial_set

The description of spi_crc_polynomial_set is shown as below:

Table 3-461. Function spi_crc_polynomial_set

Function name	spi_crc_polynomial_set
Function prototype	void spi_crc_polynomial_set(uint32_t spi_periph, uint16_t crc_poly);
Function descriptions	set SPI CRC polynomial
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Input parameter{in}	
crc_poly	CRC polynomial value
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set SPI0 CRC polynomial */
```

```
spi_crc_polynomial_set(SPI0,CRC_VALUE);
```

spi_crc_polynomial_get

The description of spi_crc_polynomial_get is shown as below:

Table 3-462. Function spi_crc_polynomial_get

Function name	spi_crc_polynomial_get
Function prototype	uint16_t spi_crc_polynomial_get(uint32_t spi_periph);
Function descriptions	get SPI CRC polynomial

Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
uint16_t	16-bit CRC polynomial (0-0xFFFF)

Example:

```
/* get SPI0 CRC polynomial */
uint16_t crc_val;
crc_val = spi_crc_polynomial_get(SPI0);
```

spi_crc_on

The description of spi_crc_on is shown as below:

Table 3-463. Function spi_crc_on

Function name	spi_crc_on
Function prototype	void spi_crc_on(uint32_t spi_periph);
Function descriptions	turn on SPI CRC function
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* turn on SPI0 CRC function */
spi_crc_on(SPI0);
```

spi_crc_off

The description of spi_crc_off is shown as below:

Table 3-464. Function spi_crc_off

Function name	spi_crc_off
----------------------	-------------

Function prototype	void spi_crc_off(uint32_t spi_periph);
Function descriptions	turn off SPI CRC function
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* turn off SPI0 CRC function */
```

```
spi_crc_off(SPI0);
```

spi_crc_next

The description of spi_crc_next is shown as below:

Table 3-465. Function spi_crc_next

Function name	spi_crc_next
Function prototype	void spi_crc_next(uint32_t spi_periph);
Function descriptions	SPI next data is CRC value
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* SPI0 next data is CRC value */
```

```
spi_crc_next(SPI0);
```

spi_crc_get

The description of spi_crc_get is shown as below:

Table 3-466. Function spi_crc_get

Function name	spi_crc_get
----------------------	-------------

Function prototype	uint16_t spi_crc_get(uint32_t spi_periph, uint8_t crc);
Function descriptions	get SPI CRC send value or receive value
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Input parameter{in}	
crc	SPI crc value
<i>SPI_CRC_TX</i>	get transmit crc value
<i>SPI_CRC_RX</i>	get receive crc value
Output parameter{out}	
-	-
Return value	
uint16_t	16-bit CRC value (0-0xFFFF)

Example:

```
/* get SPI0 CRC send value */
uint16_t crc_val;
crc_val = spi_crc_get(SPI0, SPI_CRC_TX);
```

spi_ti_mode_enable

The description of spi_ti_mode_enable is shown as below:

Table 3-467. Function spi_ti_mode_enable

Function name	spi_ti_mode_enable
Function prototype	void spi_ti_mode_enable(uint32_t spi_periph);
Function descriptions	enable SPI TI mode
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable SPI0 TI mode */
spi_ti_mode_enable(SPI0);
```

spi_ti_mode_disable

The description of spi_ti_mode_disable is shown as below:

Table 3-468. Function spi_ti_mode_disable

Function name	spi_ti_mode_disable
Function prototype	void spi_ti_mode_disable(uint32_t spi_periph);
Function descriptions	disable SPI TI mode
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable SPI0 TI mode */
spi_ti_mode_disable(SPI0);
```

spi_nssp_mode_enable

The description of spi_nssp_mode_enable is shown as below:

Table 3-469. Function spi_nssp_mode_enable

Function name	spi_nssp_mode_enable
Function prototype	void spi_nssp_mode_enable(uint32_t spi_periph);
Function descriptions	enable SPI NSS pulse mode
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable SPI0 NSS pulse mode */
spi_nssp_mode_enable(SPI0);
```

spi_nssp_mode_disable

The description of spi_nssp_mode_disable is shown as below:

Table 3-470. Function spi_nssp_mode_disable

Function name	spi_nssp_mode_disable
Function prototype	void spi_nssp_mode_disable(uint32_t spi_periph);
Function descriptions	disable SPI NSS pulse mode
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable SPI0 NSS pulse mode */
spi_nssp_mode_disable(SPI0);
```

spi_quad_enable

The description of spi_quad_enable is shown as below:

Table 3-471. Function spi_quad_enable

Function name	spi_quad_enable
Function prototype	void spi_quad_enable(uint32_t spi_periph);
Function descriptions	enable quad wire SPI
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable SPI0 quad wire mode */
spi_quad_enable(SPI0);
```


spi_quad_disable

The description of spi_quad_disable is shown as below:

Table 3-472. Function spi_quad_disable

Function name	spi_quad_disable
Function prototype	spi_quad_disable(uint32_t spi_periph);
Function descriptions	disable quad wire SPI
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable SPI0 quad wire mode */
```

```
spi_quad_disable(SPI0);
```

spi_quad_write_enable

The description of spi_quad_write_enable is shown as below:

Table 3-473. Function spi_quad_write_enable

Function name	spi_quad_write_enable
Function prototype	void spi_quad_write_enable(uint32_t spi_periph);
Function descriptions	enable quad wire SPI write
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable SPI0 quad wire write */
```

```
spi_quad_write_enable(SPI0);
```

spi_quad_read_enable

The description of spi_quad_read_enable is shown as below:

Table 3-474. Function spi_quad_read_enable

Function name	spi_quad_read_enable
Function prototype	void spi_quad_read_enable(uint32_t spi_periph);
Function descriptions	enable quad wire SPI read
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable SPI0 quad wire read */
```

```
spi_quad_read_enable(SPI0);
```

spi_quad_io23_output_enable

The description of spi_quad_io23_output_enable is shown as below:

Table 3-475. Function spi_quad_io23_output_enable

Function name	spi_quad_io23_output_enable
Function prototype	void spi_quad_io23_output_enable(uint32_t spi_periph);
Function descriptions	enable SPI_IO2 and SPI_IO3 pin output
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable SPI0 SPI_IO2 and SPI_IO3 pin output */
```

```
spi_quad_io23_output_enable(SPI0);
```

spi_quad_io23_output_disable

The description of spi_quad_io23_output_disable is shown as below:

Table 3-476. Function spi_quad_io23_output_disable

Function name	spi_quad_io23_output_disable
Function prototype	void spi_quad_io23_output_disable(uint32_t spi_periph);
Function descriptions	disable SPI_IO2 and SPI_IO3 pin output
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable SPI0 SPI_IO2 and SPI_IO3 pin output */
```

```
spi_quad_io23_output_disable(SPI0);
```

spi_i2s_interrupt_enable

The description of spi_i2s_interrupt_enable is shown as below:

Table 3-477. Function spi_i2s_interrupt_enable

Function name	spi_i2s_interrupt_enable
Function prototype	void spi_i2s_interrupt_enable(uint32_t spi_periph, uint8_t interrupt);
Function descriptions	enable SPI and I2S interrupt
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Input parameter{in}	
interrupt	SPI/I2S interrupt
<i>SPI_I2S_INT_TBE</i>	transmit buffer empty interrupt
<i>SPI_I2S_INT_RBNE</i>	receive buffer not empty interrupt
<i>SPI_I2S_INT_ERR</i>	CRC error,configuration error,reception overrun error, transmission underrun error and format error interrupt
Output parameter{out}	
-	-
Return value	

Example:

```
/* enable SPI0 transmit buffer empty interrupt */
```

```
spi_i2s_interrupt_enable(SPI0, SPI_I2S_INT_TBE);
```

spi_i2s_interrupt_disable

The description of spi_i2s_interrupt_disable is shown as below:

Table 3-478. Function spi_i2s_interrupt_disable

Function name	spi_i2s_interrupt_disable
Function prototype	void spi_i2s_interrupt_disable(uint32_t spi_periph, uint8_t interrupt);
Function descriptions	disable SPI and I2S interrupt
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Input parameter{in}	
interrupt	SPI/I2S interrupt
<i>SPI_I2S_INT_TBE</i>	transmit buffer empty interrupt
<i>SPI_I2S_INT_RBNE</i>	receive buffer not empty interrupt
<i>SPI_I2S_INT_ERR</i>	CRC error,configuration error,reception overrun error, transmission underrun error and format error interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable SPI0 transmit buffer empty interrupt */
```

```
spi_i2s_interrupt_disable(SPI0, SPI_I2S_INT_TBE);
```

spi_i2s_interrupt_flag_get

The description of spi_i2s_interrupt_flag_get is shown as below:

Table 3-479. Function spi_i2s_interrupt_flag_get

Function name	spi_i2s_interrupt_flag_get
Function prototype	FlagStatus spi_i2s_interrupt_flag_get(uint32_t spi_periph, uint8_t interrupt);
Function descriptions	get SPI and I2S interrupt status
Precondition	-
The called functions	-

Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Input parameter{in}	
interrupt	SPI/I2S interrupt flag status
<i>SPI_I2S_INT_FLAG_TBE</i>	transmit buffer empty interrupt
<i>SPI_I2S_INT_FLAG_RBNE</i>	receive buffer not empty interrupt
<i>SPI_I2S_INT_FLAG_RXORERR</i>	overrun interrupt
<i>SPI_INT_FLAG_CONFERR</i>	config error interrupt
<i>SPI_INT_FLAG_CRCERR</i>	CRC error interrupt
<i>I2S_INT_FLAG_TXURERR</i>	underrun error interrupt
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```

/* get SPI0 transmit buffer empty interrupt status */

if(RESET != spi_i2s_interrupt_flag_get(SPI0, SPI_I2S_INT_FLAG_TBE)){
    while(RESET == spi_i2s_flag_get(SPI0, SPI_FLAG_TBE));
    spi_i2s_data_transmit(SPI0, spi0_send_array[send_n++]);
}

```

spi_i2s_flag_get

The description of spi_i2s_flag_get is shown as below:

Table 3-480. Function spi_i2s_flag_get

Function name	spi_i2s_flag_get
Function prototype	FlagStatus spi_i2s_flag_get(uint32_t spi_periph, uint32_t flag);
Function descriptions	get SPI and I2S flag status
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2

Input parameter{in}	
flag	SPI/I2S flag status
<i>SPI_FLAG_TBE</i>	transmit buffer empty flag
<i>SPI_FLAG_RBNE</i>	receive buffer not empty flag
<i>SPI_FLAG_TRANS</i>	transmit on-going flag
<i>SPI_I2S_INT_FLAG_RXORERR</i>	receive overrun error flag
<i>SPI_FLAG_CONFERR</i>	mode config error flag
<i>SPI_FLAG_CRCERR</i>	CRC error flag
<i>I2S_FLAG_RXORERR</i>	overrun error flag
<i>I2S_FLAG_TXURERR</i>	underrun error flag
<i>I2S_FLAG_CH</i>	channel side flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get SPI0 transmit buffer empty flag status */
while(RESET == spi_i2s_flag_get(SPI0, SPI_FLAG_TBE));
spi_i2s_data_transmit(SPI0, spi0_send_array[send_n++]);
```

spi_crc_error_clear

The description of spi_crc_error_clear is shown as below:

Table 3-481. Function spi_crc_error_clear

Function name	spi_crc_error_clear
Function prototype	void spi_crc_error_clear(uint32_t spi_periph);
Function descriptions	clear SPI CRC error flag status
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear SPI0 CRC error flag status */
```

```
spl_crc_error_clear(SPI0);
```

3.21. TIMER

The timers have a 16-bit counter that can be used as an unsigned counter and supports both input capture and output compare. Timers (TIMERx) are divided into five sorts: advanced timer (TIMERx, x=0, 7), general level0 timer (TIMERx, x=1, 2, 3, 4), general level1 timer (TIMERx, x=8, 11), general level2 timer (TIMERx, x=9, 10, 12, 13), Basic timer (TIMERx, x=5, 6). The specific functions of different types of timer are different. The TIMER registers are listed in chapter [3.21.1](#), the TIMER firmware functions are introduced in chapter [3.21.2](#).

3.21.1. Descriptions of Peripheral registers

TIMERx registers are listed in the table shown as below:

Table 3-482. TIMERx Registers

Registers	Descriptions
TIMER_CTL0	Control register 0
TIMER_CTL1	Control register 1
TIMER_SMCFG	Slave mode configuration register
TIMER_DMAINTEN	DMA and interrupt enable register
TIMER_INTF	Interrupt flag register
TIMER_SWEVG	Software event generation register
TIMER_CHCTL0	Channel control register 0
TIMER_CHCTL1	Channel control register 1
TIMER_CHCTL2	Channel control register 2
TIMER_CNT	Counter register
TIMER_PSC	Prescaler register
TIMER_CAR	Counter auto reload register
TIMER_CREP	Counter repetition register
TIMER_CH0CV	Channel 0 capture/compare value register
TIMER_CH1CV	Channel 1 capture/compare value register
TIMER_CH2CV	Channel 2 capture/compare value register
TIMER_CH3CV	Channel 3 capture/compare value register
TIMER_CCHP	Channel complementary protection register
TIMER_DMACFG	DMA configuration register
TIMER_DMATB	DMA transfer buffer register
TIMER_CFG	Configuration register

3.21.2. Descriptions of Peripheral functions

The description format of firmware functions are shown as below:

Table 3-483. TIMERx firmware function

Function name	Function description
timer_deinit	deinit a timer
timer_struct_para_init	initialize the parameters of TIMER init parameter struct with the default values
timer_init	initialize TIMER counter
timer_enable	enable a timer
timer_disable	disable a timer
timer_auto_reload_shadow_enable	enable the auto reload shadow function
timer_auto_reload_shadow_disable	disable the auto reload shadow function
timer_update_event_enable	enable the update event
timer_update_event_disable	disable the update event
timer_counter_alignment	set TIMER counter alignment mode
timer_counter_up_direction	set TIMER counter up direction
timer_counter_down_direction	set TIMER counter down direction
timer_prescaler_config	configure TIMER prescaler
timer_repetition_value_config	configure TIMER repetition register value
timer_autoreload_value_config	configure TIMER autoreload register value
timer_counter_value_config	configure TIMER counter register value
timer_counter_read	read TIMER counter value
timer_prescaler_read	read TIMER prescaler value
timer_single_pulse_mode_config	configure TIMER single pulse mode
timer_update_source_config	configure TIMER update source
timer_dma_enable	enable the TIMER DMA
timer_dma_disable	disable the TIMER DMA
timer_channel_dma_request_source_select	channel DMA request source selection
timer_dma_transfer_config	configure the TIMER DMA transfer
timer_event_software_generate	software generate events
timer_break_struct_para_init	initialize the parameters of TIMER break parameter struct with the default values
timer_break_config	configure TIMER break function
timer_break_enable	enable TIMER break function
timer_break_disable	disable TIMER break function
timer_automatic_output_enable	enable TIMER output automatic function
timer_automatic_output_disable	disable TIMER output automatic function
timer_primary_output_config	configure TIMER primary output function
timer_channel_control_shadow_config	channel capture/compare control shadow register enable
timer_channel_control_shadow_update_config	configure TIMER channel control shadow register update control
timer_channel_output_struct	initialize the parameters of TIMER channel output

Function name	Function description
_para_init	parameter struct with the default values
timer_channel_output_config	configure TIMER channel output function
timer_channel_output_mode_config	configure TIMER channel output compare mode
timer_channel_output_pulse_value_config	configure TIMER channel output pulse value
timer_channel_output_shadow_config	configure TIMER channel output shadow function
timer_channel_output_fast_config	configure TIMER channel output fast function
timer_channel_output_clear_config	configure TIMER channel output clear function
timer_channel_output_polarity_config	configure TIMER channel output polarity
timer_channel_complementary_output_polarity_config	configure TIMER channel complementary output polarity
timer_channel_output_state_config	configure TIMER channel enable state
timer_channel_complementary_output_state_config	configure TIMER channel complementary output enable state
timer_channel_input_struct_para_init	initialize the parameters of TIMER channel input parameter struct with the default values
timer_input_capture_config	configure TIMER input capture parameter
timer_channel_input_capture_prescaler_config	configure TIMER channel input capture prescaler value
timer_channel_capture_value_register_read	read TIMER channel capture compare register value
timer_input_pwm_capture_config	configure TIMER input pwm capture function
timer_hall_mode_config	configure TIMER hall sensor mode
timer_input_trigger_source_select	select TIMER input trigger source
timer_master_output_trigger_source_select	select TIMER master mode output trigger source
timer_slave_mode_select	select TIMER slave mode
timer_master_slave_mode_config	configure TIMER master slave mode
timer_external_trigger_config	configure TIMER external trigger input
timer_quadrature_decoder_mode_config	configure TIMER quadrature decoder mode
timer_internal_clock_config	configure TIMER internal clock mode
timer_internal_trigger_as_external_clock_config	configure TIMER the internal trigger as external clock input
timer_external_trigger_as_external_clock_config	configure TIMER the external trigger as external clock input
timer_external_clock_mode0_config	configure TIMER the external clock mode 0
timer_external_clock_mode1_config	configure TIMER the external clock mode 1
timer_external_clock_mode1_disable	disable TIMER the external clock mode 1

Function name	Function description
timer_write_chxval_register_config	configure TIMER write CHxVAL register selection
timer_output_value_selection_config	configure TIMER output value selection
timer_interrupt_enable	enable the TIMER interrupt
timer_interrupt_disable	disable the TIMER interrupt
timer_interrupt_flag_get	get timer interrupt flag
timer_interrupt_flag_clear	clear TIMER interrupt flag
timer_flag_get	get TIMER flags
timer_flag_clear	clear TIMER flags

Structure timer_parameter_struct

Table 3-484. Structure timer_parameter_struct

Member name	Function description
prescaler	prescaler value (0~65535)
alignedmode	aligned mode (TIMER_COUNTER_EDGE, TIMER_COUNTER_CENTER_DOWN, TIMER_COUNTER_CENTER_UP, TIMER_COUNTER_CENTER_BOTH)
counterdirection	counter direction (TIMER_COUNTER_UP, TIMER_COUNTER_DOWN)
period	period value (0~65535)
clockdivision	clock division value (TIMER_CKDIV_DIV1, TIMER_CKDIV_DIV2, TIMER_CKDIV_DIV4)
repetitioncounter	the counter repetition value (0~255)

Structure timer_break_parameter_struct

Table 3-485. Structure timer_break_parameter_struct

Member name	Function description
runoffstate	run mode off-state (TIMER_ROS_STATE_ENABLE, TIMER_ROS_STATE_DISABLE)
ideloffstate	idle mode off-state (TIMER_IOS_STATE_ENABLE, TIMER_IOS_STATE_DISABLE)
deadtime	dead time (0~255)
breakpolarity	break polarity (TIMER_BREAK_POLARITY_LOW, TIMER_BREAK_POLARITY_HIGH)
outputautostate	output automatic enable (TIMER_OUTAUTO_ENABLE, TIMER_OUTAUTO_DISABLE)
protectmode	complementary register protect control (TIMER_CCHP_PROT_OFF, TIMER_CCHP_PROT_0, TIMER_CCHP_PROT_1, TIMER_CCHP_PROT_2)
breakstate	break enable (TIMER_BREAK_ENABLE, TIMER_BREAK_DISABLE)

Structure timer_oc_parameter_struct

Table 3-486. Structure timer_oc_parameter_struct

Member name	Function description
outputstate	channel output state (TIMER_CCX_ENABLE, TIMER_CCX_DISABLE)
outputnstate	channel complementary output state (TIMER_CCXN_ENABLE, TIMER_CCXN_DISABLE)
ocpolarity	channel output polarity (TIMER_OC_POLARITY_HIGH, TIMER_OC_POLARITY_LOW)
ocnpolarity	channel complementary output polarity (TIMER_OCN_POLARITY_HIGH, TIMER_OCN_POLARITY_LOW)
ocidlestate	idle state of channel output (TIMER_OC_IDLE_STATE_LOW, TIMER_OC_IDLE_STATE_HIGH)
ocnidlestate	idle state of channel complementary output (TIMER_OCN_IDLE_STATE_LOW, TIMER_OCN_IDLE_STATE_HIGH)

Structure timer_ic_parameter_struct

Table 3-487. Structure timer_ic_parameter_struct

Member name	Function description
icpolarity	channel input polarity (TIMER_IC_POLARITY_RISING, TIMER_IC_POLARITY_FALLING, TIMER_IC_POLARITY_BOTH_EDGE)
icselection	channel input mode selection (TIMER_IC_SELECTION_DIRECTTI, TIMER_IC_SELECTION_INDIRECTTI, TIMER_IC_SELECTION_ITS)
icprescaler	channel input capture prescaler (TIMER_IC_PSC_DIV1, TIMER_IC_PSC_DIV2, TIMER_IC_PSC_DIV4, TIMER_IC_PSC_DIV8)
icfilter	channel input capture filter control (0~15)

timer_deinit

The description of timer_deinit is shown as below:

Table 3-488. Function timer_deinit

Function name	timer_deinit
Function prototype	void timer_deinit(uint32_t timer_periph);
Function descriptions	deinit a TIMER
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Input parameter{in}	
timer_periph	TIMER peripheral
TIMERx(x=0..13)	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* reset TIMER0 */
```

```
timer_deinit (TIMER0);
```

timer_struct_para_init

The description of timer_struct_para_init is shown as below:

Table 3-489. Function timer_struct_para_init

Function name	timer_struct_para_init
Function prototype	void timer_struct_para_init(timer_parameter_struct* initpara);
Function descriptions	initialize the parameters of TIMER init parameter struct with the default values
Precondition	-
The called functions	-
Input parameter{in}	
initpara	TIMER init parameter struct, the structure members can refer to Table 3-484. Structure timer_parameter_struct .
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* initialize TIMER init parameter struct with a default value */
```

```
timer_parameter_struct timer_initpara;
```

```
timer_struct_para_init(timer_initpara);
```

timer_init

The description of timer_init is shown as below:

Table 3-490. Function timer_init

Function name	timer_init
Function prototype	void timer_init(uint32_t timer_periph, timer_parameter_struct* initpara);
Function descriptions	initialize TIMER counter
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..13)</i>	TIMER peripheral selection

Input parameter{in}	
initpara	TIMER init parameter struct, the structure members can refer to Table 3-484. Structure timer parameter struct .
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* initialize TIMER0 */

timer_parameter_struct timer_initpara;

timer_initpara.prescaler      = 107;

timer_initpara.alignedmode    = TIMER_COUNTER_EDGE;

timer_initpara.counterdirection = TIMER_COUNTER_UP;

timer_initpara.period         = 999;

timer_initpara.clockdivision   = TIMER_CKDIV_DIV1;

timer_initpara.repetitioncounter = 1;

timer_init(TIMER0,&timer_initpara);

```

timer_enable

The description of timer_enable is shown as below:

Table 3-491. Function timer_enable

Function name	timer_enable
Function prototype	void timer_enable(uint32_t timer_periph);
Function descriptions	enable a timer
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..13)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* enable TIMER0 */

timer_enable (TIMER0);

```

timer_disable

The description of timer_disable is shown as below:

Table 3-492. Function timer_disable

Function name	timer_disable
Function prototype	void timer_disable(uint32_t timer_periph);
Function descriptions	disable a timer
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..13)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable TIMER0 */
timer_disable (TIMER0);
```

timer_auto_reload_shadow_enable

The description of timer_auto_reload_shadow_enable is shown as below:

Table 3-493. Function timer_auto_reload_shadow_enable

Function name	timer_auto_reload_shadow_enable
Function prototype	void timer_auto_reload_shadow_enable(uint32_t timer_periph);
Function descriptions	enable the auto reload shadow function
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..13)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the TIMER0 auto reload shadow function */
timer_auto_reload_shadow_enable (TIMER0);
```

timer_auto_reload_shadow_disable

The description of timer_auto_reload_shadow_disable is shown as below:

Table 3-494. Function timer_auto_reload_shadow_disable

Function name	timer_auto_reload_shadow_disable
Function prototype	void timer_auto_reload_shadow_disable (uint32_t timer_periph);
Function descriptions	disable the auto reload shadow function
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..13)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the TIMER0 auto reload shadow function */
```

```
timer_auto_reload_shadow_disable (TIMER0);
```

timer_update_event_enable

The description of timer_update_event_enable is shown as below:

Table 3-495. Function timer_update_event_enable

Function name	timer_update_event_enable
Function prototype	void timer_update_event_enable(uint32_t timer_periph);
Function descriptions	enable the update event
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..13)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable TIMER0 the update event */
```

```
timer_update_event_enable (TIMER0);
```

timer_update_event_disable

The description of timer_update_event_disable is shown as below:

Table 3-496. Function timer_update_event_disable

Function name	timer_update_event_disable
Function prototype	void timer_update_event_disable (uint32_t timer_periph);
Function descriptions	disable the update event
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..13)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable TIMER0 the update event */
timer_update_event_disable (TIMER0);
```

timer_counter_alignment

The description of timer_counter_alignment is shown as below:

Table 3-497. Function timer_counter_alignment

Function name	timer_counter_alignment
Function prototype	void timer_counter_alignment(uint32_t timer_periph, uint16_t aligned);
Function descriptions	set TIMER counter alignment mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7..13)</i>	TIMER peripheral selection
Input parameter{in}	
aligned	alignment mode
<i>TIMER_COUNTER_EDGE</i>	No center-aligned mode (edge-aligned mode). The direction of the counter is specified by the DIR bit.
<i>TIMER_COUNTER_COUNTER_DOWN</i>	Center-aligned and counting down assert mode. The counter counts under center aligned and channel is configured in output mode (CHxMS=00 in <i>TIMERx_CHCTL0</i> register). Only when the counter is counting down, compare interrupt flag of channels can be set.
<i>TIMER_COUNTER_COUNTER_UP</i>	Center-aligned and counting up assert mode. The counter counts under

<i>NTER_UP</i>	center aligned and channel is configured in output mode (CHxMS=00 in TIMERx_CHCTL0register). Only when the counter is counting up, compare interrupt flag of channels can be set.
<i>TIMER_COUNTER_CE NTER_BOTH</i>	Center-aligned and counting up/down assert mode. The counter counts under center-aligned and channel is configured in output mode (CHxMS=00 in TIMERx_CHCTL0 register). Both when the counter is counting up and counting down, compare interrupt flag of channels can be set.
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set TIMER0 counter center-aligned and counting up assert mode */
timer_counter_alignment (TIMER0, TIMER_COUNTER_CENTER_UP);
```

timer_counter_up_direction

The description of timer_counter_up_direction is shown as below:

Table 3-498. Function timer_counter_up_direction

Function name	timer_counter_up_direction
Function prototype	void timer_counter_up_direction(uint32_t timer_periph);
Function descriptions	set TIMER counter up direction
Precondition	set TIMER counter no center-aligned mode (edge-aligned mode)
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7..13)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set TIMER0 counter up direction */
timer_counter_up_direction (TIMER0);
```

timer_counter_down_direction

The description of timer_counter_down_direction is shown as below:

Table 3-499. timer_counter_down_direction

Function name	timer_counter_down_direction
----------------------	------------------------------

Function prototype	void timer_counter_ down _direction(uint32_t timer_periph);
Function descriptions	set TIMER counter down direction
Precondition	set TIMER counter no center-aligned mode (edge-aligned mode)
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7..13)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set TIMER0 counter down direction */
```

```
timer_counter_down_direction (TIMER0);
```

timer_prescaler_config

The description of timer_prescaler_config is shown as below:

Table 3-500. Function timer_prescaler_config

Function name	timer_prescaler_config
Function prototype	void timer_prescaler_config(uint32_t timer_periph, uint16_t prescaler, uint8_t pscreload);
Function descriptions	configure TIMER prescaler
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..13)</i>	TIMER peripheral selection
Input parameter{in}	
prescaler	prescaler value (0~65535)
Input parameter{in}	
pscreload	prescaler reload mode
<i>TIMER_PSC_RELOAD_NOW</i>	the prescaler is loaded right now
<i>TIMER_PSC_RELOAD_UPDATE</i>	the prescaler is loaded at the next update event
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 prescaler */
```

```
timer_prescaler_config (TIMER0, 3000, TIMER_PSC_RELOAD_NOW);
```

timer_repetition_value_config

The description of timer_repetition_value_config is shown as below:

Table 3-501. Function timer_repetition_value_config

Function name	timer_repetition_value_config
Function prototype	void timer_repetition_value_config(uint32_t timer_periph, uint16_t repetition);
Function descriptions	configure TIMER repetition register value
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0,7)</i>	TIMER peripheral selection
Input parameter{in}	
repetition	the counter repetition value (0~255)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 repetition register value */
```

```
timer_repetition_value_config (TIMER0, 98);
```

timer_autoreload_value_config

The description of timer_autoreload_value_config is shown as below:

Table 3-502. Function timer_autoreload_value_config

Function name	timer_autoreload_value_config
Function prototype	void timer_autoreload_value_config(uint32_t timer_periph, uint16_t autoreload);
Function descriptions	configure TIMER autoreload register value
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..13)</i>	TIMER peripheral selection
Input parameter{in}	
autoreload	the counter auto-reload value (0-0xFFFF)

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER autoreload register value */
timer_autoreload_value_config (TIMER0, 3000);
```

timer_counter_value_config

The description of timer_counter_value_config is shown as below:

Table 3-503. Function timer_counter_value_config

Function name	timer_counter_value_config
Function prototype	void timer_counter_value_config(uint32_t timer_periph, uint16_t counter);
Function descriptions	configure TIMER counter register value
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..13)</i>	TIMER peripheral selection
Input parameter{in}	
counter	the counter value (0-0xFFFF)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 counter register value */
timer_counter_value_config (TIMER0);
```

timer_counter_read

The description of timer_counter_read is shown as below:

Table 3-504. Function timer_counter_read

Function name	timer_counter_read
Function prototype	uint32_t timer_counter_read(uint32_t timer_periph);
Function descriptions	read TIMER counter value
Precondition	-
The called functions	-
Input parameter{in}	

timer_periph	TIMER peripheral
<i>TIMERx(x=0..13)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
uint32_t	counter value(0x0000~0xFFFF)

Example:

```
/* read TIMER0 counter value */

uint32_t i = 0;

i = timer_counter_read (TIMER0);
```

timer_prescaler_read

The description of timer_prescaler_read is shown as below:

Table 3-505. Function timer_prescaler_read

Function name	timer_prescaler_read
Function prototype	uint16_t timer_prescaler_read(uint32_t timer_periph);
Function descriptions	read TIMER prescaler value
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..13)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
uint16_t	prescaler register value (0x0000~0xFFFF)

Example:

```
/* read TIMER0 prescaler value */

uint16_t i = 0;

i = timer_prescaler_read (TIMER0);
```

timer_single_pulse_mode_config

The description of timer_single_pulse_mode_config is shown as below:

Table 3-506. Function timer_single_pulse_mode_config

Function name	timer_single_pulse_mode_config
Function prototype	void timer_single_pulse_mode_config(uint32_t timer_periph, uint8_t spmode);

Function descriptions	configure TIMER single pulse mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..11)</i>	TIMER peripheral selection
Input parameter{in}	
spmode	pulse mode
<i>TIMER_SP_MODE_SINGLE</i>	single pulse mode
<i>TIMER_SP_MODE_REPETITIVE</i>	repetitive pulse mode
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 single pulse mode */
```

```
timer_single_pulse_mode_config (TIMER0, TIMER_SP_MODE_SINGLE);
```

timer_update_source_config

The description of timer_update_source_config is shown as below:

Table 3-507. Function timer_update_source_config

Function name	timer_update_source_config
Function prototype	void timer_update_source_config(uint32_t timer_periph, uint32_t update);
Function descriptions	configure TIMER update source
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..13)</i>	TIMER peripheral selection
Input parameter{in}	
update	update source
<i>TIMER_UPDATE_SRC_GLOBAL</i>	Any of the following events generate an update interrupt or DMA request: <ul style="list-style-type: none"> - The UPG bit is set - The counter generates an overflow or underflow event - The slave mode controller generates an update event
<i>TIMER_UPDATE_SRC_REGULAR</i>	Only counter overflow/underflow generates an update interrupt or DMA request.
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* configure TIMER update only by counter overflow/underflow */
```

```
timer_update_source_config (TIMER0, TIMER_UPDATE_SRC_REGULAR);
```

timer_dma_enable

The description of timer_dma_enable is shown as below:

Table 3-508. Function timer_dma_enable

Function name	timer_dma_enable
Function prototype	void timer_dma_enable(uint32_t timer_periph, uint16_t dma);
Function descriptions	enable the TIMER DMA
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
dma	timer DMA source enable
<i>TIMER_DMA_UPD</i>	update DMA enable, TIMERx(x=0..7)
<i>TIMER_DMA_CH0D</i>	channel 0 DMA enable, TIMERx(x=0..4,7)
<i>TIMER_DMA_CH1D</i>	channel 1 DMA enable, TIMERx(x=0..4,7)
<i>TIMER_DMA_CH2D</i>	channel 2 DMA enable, TIMERx(x=0..4,7)
<i>TIMER_DMA_CH3D</i>	channel 3 DMA enable, TIMERx(x=0..4,7)
<i>TIMER_DMA_CMTD</i>	commutation DMA request enable, TIMERx(x=0,7)
<i>TIMER_DMA_TRGD</i>	trigger DMA enable, TIMERx(x=0..4,7)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the TIMER0 update DMA */
```

```
timer_dma_enable (TIMER0, TIMER_DMA_UPD);
```

timer_dma_disable

The description of timer_dma_disable is shown as below:

Table 3-509. Function timer_dma_disable

Function name	timer_dma_disable
Function prototype	void timer_dma_disable (uint32_t timer_periph, uint16_t dma);
Function descriptions	disable the TIMER DMA
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
dma	timer DMA source disable
<i>TIMER_DMA_UPD</i>	update DMA disable, <i>TIMERx</i> (x=0..7)
<i>TIMER_DMA_CH0D</i>	channel 0 DMA disable, <i>TIMERx</i> (x=0..4,7)
<i>TIMER_DMA_CH1D</i>	channel 1 DMA disable, <i>TIMERx</i> (x=0..4,7)
<i>TIMER_DMA_CH2D</i>	channel 2 DMA disable, <i>TIMERx</i> (x=0..4,7)
<i>TIMER_DMA_CH3D</i>	channel 3 DMA disable, <i>TIMERx</i> (x=0..4,7)
<i>TIMER_DMA_CMTD</i>	commutation DMA request disable, <i>TIMERx</i> (x=0,7)
<i>TIMER_DMA_TRGD</i>	trigger DMA disable, <i>TIMERx</i> (x=0..4,7)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the TIMER0 update DMA */
```

```
timer_dma_disable (TIMER0, TIMER_DMA_UPD);
```

timer_channel_dma_request_source_select

The description of timer_channel_dma_request_source_select is shown as below:

Table 3-510. Function timer_channel_dma_request_source_select

Function name	timer_channel_dma_request_source_select
Function prototype	void timer_channel_dma_request_source_select(uint32_t timer_periph, uint32_t dma_request);
Function descriptions	channel DMA request source selection
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	TIMER peripheral selection
Input parameter{in}	
dma_request	channel DMA request source selection

<i>TIMER_DMAREQUEST_CHANNELEVENT</i>	DMA request of channel n is sent when channel y event occurs
<i>TIMER_DMAREQUEST_UPDATEEVENT</i>	DMA request of channel n is sent when update event occurs
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* TIMER0 channel DMA request of channel n is sent when channel y event occurs */
timer_channel_dma_request_source_select(TIMER0,
TIMER_DMAREQUEST_CHANNELEVENT);
```

timer_dma_transfer_config

The description of timer_dma_transfer_config is shown as below:

Table 3-511. Function timer_dma_transfer_config

Function name	timer_dma_transfer_config
Function prototype	void timer_dma_transfer_config(uint32_t timer_periph, uint32_t dma_baseaddr, uint32_t dma_lenth);
Function descriptions	configure the TIMER DMA transfer
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
dma_baseaddr	DMA transfer access start address
<i>TIMER_DMACFG_DMA_TA_CTL0</i>	DMA transfer address is TIMER_CTL0, TIMERx(x=0..4,7)
<i>TIMER_DMACFG_DMA_TA_CTL1</i>	DMA transfer address is TIMER_CTL1, TIMERx(x=0..4,7)
<i>TIMER_DMACFG_DMA_TA_SMCFG</i>	DMA transfer address is TIMER_SMCFG, TIMERx(x=0..4,7)
<i>TIMER_DMACFG_DMA_TA_DMAINTEN</i>	DMA transfer address is TIMER_DMAINTEN, TIMERx(x=0..4,7)
<i>TIMER_DMACFG_DMA_TA_INTF</i>	DMA transfer address is TIMER_INTF, TIMERx(x=0..4,7)
<i>TIMER_DMACFG_DMA_TA_SWEVG</i>	DMA transfer address is TIMER_SWEVG, TIMERx(x=0..4,7)
<i>TIMER_DMACFG_DMA</i>	DMA transfer address is TIMER_CHCTL0, TIMERx(x=0..4,7)

<i>TA_CHCTL0</i>	
<i>TIMER_DMACFG_DMA TA_CHCTL1</i>	DMA transfer address is <i>TIMER_CHCTL1</i> , <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_DMACFG_DMA TA_CHCTL2</i>	DMA transfer address is <i>TIMER_CHCTL2</i> , <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_DMACFG_DMA TA_CNT</i>	DMA transfer address is <i>TIMER_CNT</i> , <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_DMACFG_DMA TA_PSC</i>	DMA transfer address is <i>TIMER_PSC</i> , <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_DMACFG_DMA TA_CAR</i>	MA transfer address is <i>TIMER_CAR</i> , <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_DMACFG_DMA TA_CREP</i>	DMA transfer address is <i>TIMER_CREP</i> , <i>TIMERx</i> (<i>x</i> =0,7)
<i>TIMER_DMACFG_DMA TA_CH0CV</i>	DMA transfer address is <i>TIMER_CH0CV</i> , <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_DMACFG_DMA TA_CH1CV</i>	DMA transfer address is <i>TIMER_CH1CV</i> , <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_DMACFG_DMA TA_CH2CV</i>	DMA transfer address is <i>TIMER_CH2CV</i> , <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_DMACFG_DMA TA_CH3CV</i>	DMA transfer address is <i>TIMER_CH3CV</i> , <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_DMACFG_DMA TA_CCHP</i>	DMA transfer address is <i>TIMER_CCHP</i> , <i>TIMERx</i> (<i>x</i> =0,7)
<i>TIMER_DMACFG_DMA TA_DMACFG</i>	DMA transfer address is <i>TIMER_DMACFG</i> , <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_DMACFG_DMA TA_DMATB</i>	DMA transfer address is <i>TIMER_DMATB</i> , <i>TIMERx</i> (<i>x</i> =0..4,7)
Input parameter{in}	
dma_lenth	DMA transfer count
<i>TIMER_DMACFG_DMA TC_xTRANSFER</i>	<i>x</i> =1..18, DMA transfer <i>x</i> time
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the TIMER0 DMA transfer */
```

```
timer_dma_transfer_config(TIMER0, TIMER_DMACFG_DMATA_CTL0,  
TIMER_DMACFG_DMATC_5TRANSFER);
```

timer_event_software_generate

The description of timer_event_software_generate is shown as below:

Table 3-512. Function timer_event_software_generate

Function name	timer_event_software_generate
Function prototype	void timer_event_software_generate(uint32_t timer_periph, uint16_t event);
Function descriptions	software generate events
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
event	the timer software event generation sources
<i>TIMER_EVENT_SRC_UPG</i>	update event, TIMERx(x=0..13)
<i>TIMER_EVENT_SRC_CH0G</i>	channel 0 capture or compare event generation, TIMERx(x=0..4,7..13)
<i>TIMER_EVENT_SRC_CH1G</i>	channel 1 capture or compare event generation, TIMERx(x=0..4,7,8,11)
<i>TIMER_EVENT_SRC_CH2G</i>	channel 2 capture or compare event generation, TIMERx(x=0..4,7)
<i>TIMER_EVENT_SRC_CH3G</i>	channel 3 capture or compare event generation, TIMERx(x=0..4,7)
<i>TIMER_EVENT_SRC_CMTG</i>	channel commutation event generation, TIMERx(x=0,7)
<i>TIMER_EVENT_SRC_TRIGG</i>	trigger event generation, TIMERx(x=0..4,7,8,11)
<i>TIMER_EVENT_SRC_BREAKG</i>	break event generation, TIMERx(x=0,7)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* software generate update event*/
```

```
timer_event_software_generate (TIMER0, TIMER_EVENT_SRC_UPG);
```

timer_break_struct_para_init

The description of timer_break_struct_para_init is shown as below:

Table 3-513. Function timer_break_struct_para_init

Function name	timer_break_struct_para_init
Function prototype	void timer_break_struct_para_init(timer_break_parameter_struct* breakpara);
Function descriptions	initialize the parameters of TIMER break parameter struct with the default values
Precondition	-
The called functions	-
Input parameter{in}	
breakpara	TIMER break parameter struct, the structure members can refer to Table 3-485. Structure timer break parameter struct.
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* initialize TIMER break parameter struct with a default value */
```

```
timer_break_parameter_struct timer_breakpara;
```

```
timer_break_struct_para_init(timer_breakpara);
```

timer_break_config

The description of timer_break_config is shown as below:

Table 3-514. Function timer_break_config

Function name	timer_break_config
Function prototype	void timer_break_config(uint32_t timer_periph, timer_break_parameter_struct* breakpara);
Function descriptions	configure TIMER break function
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0,7)</i>	TIMER peripheral selection
Input parameter{in}	
breakpara	TIMER break parameter struct, the structure members can refer to Table 3-485. Structure timer break parameter struct.
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 break function */

timer_break_parameter_struct timer_breakpara;

timer_breakpara.runoffstate      = TIMER_ROS_STATE_DISABLE;
timer_breakpara.ideloffstate     = TIMER_IOS_STATE_DISABLE ;
timer_breakpara.deadtime         = 255;
timer_breakpara.breakpolarity    = TIMER_BREAK_POLARITY_LOW;
timer_breakpara.outputautostate  = TIMER_OUTAUTO_ENABLE;
timer_breakpara.protectmode       = TIMER_CCHP_PROT_0;
timer_breakpara.breakstate       = TIMER_BREAK_ENABLE;

timer_break_config(TIMER0, &timer_breakpara);
```

timer_break_enable

The description of timer_break_enable is shown as below:

Table 3-515. Function timer_break_enable

Function name	timer_break_enable
Function prototype	void timer_break_enable(uint32_t timer_periph);
Function descriptions	enable TIMER break function
Precondition	This function can be called only when PROT [1:0] bit-filed in TIMERx_CCHP register is 00.
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0,7)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable TIMER0 break function*/

timer_break_enable (TIMER0);
```

timer_break_disable

The description of timer_break_disable is shown as below:

Table 3-516. Function timer_break_disable

Function name	timer_break_disable
Function prototype	void timer_break_disable(uint32_t timer_periph);
Function descriptions	disable TIMER break function
Precondition	This function can be called only when PROT [1:0] bit-filed in TIMERx_CCHP register is 00.
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0,7)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable TIMER0 break function*/
```

```
timer_break_disable (TIMER0);
```

timer_automatic_output_enable

The description of timer_automatic_output_enable is shown as below:

Table 3-517. Function timer_automatic_output_enable

Function name	timer_automatic_output_enable
Function prototype	void timer_automatic_output_enable(uint32_t timer_periph);
Function descriptions	enable TIMER output automatic function
Precondition	This function can be called only when PROT [1:0] bit-filed in TIMERx_CCHP register is 00.
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0,7)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable TIMER0 output automatic function */
```

```
timer_automatic_output_enable (TIMER0);
```

timer_automatic_output_disable

The description of timer_automatic_output_disable is shown as below:

Table 3-518. Function timer_automatic_output_disable

Function name	timer_automatic_output_disable
Function prototype	void timer_automatic_output_disable (uint32_t timer_periph);
Function descriptions	disable TIMER output automatic function
Precondition	This function can be called only when PROT [1:0] bit-filed in TIMERx_CCHP register is 00.
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0,7)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable TIMERO0 output automatic function */
```

```
timer_automatic_output_disable (TIMER0);
```

timer_primary_output_config

The description of timer_primary_output_config is shown as below:

Table 3-519. Function timer_primary_output_config

Function name	timer_primary_output_config
Function prototype	void timer_primary_output_config(uint32_t timer_periph, ControlStatus newvalue);
Function descriptions	configure TIMER primary output function
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0,7)</i>	TIMER peripheral selection
Input parameter{in}	
newvalue	control value
<i>ENABLE</i>	enable function
<i>DISABLE</i>	disable function
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* enable TIMER0 primary output function */
```

```
timer_primary_output_config (TIMER0, ENABLE);
```

timer_channel_control_shadow_config

The description of timer_channel_control_shadow_config is shown as below:

Table 3-520. Function timer_channel_control_shadow_config

Function name	timer_channel_control_shadow_config
Function prototype	void timer_channel_control_shadow_config(uint32_t timer_periph, ControlStatus newvalue);
Function descriptions	channel commutation control shadow register enable
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0,7)</i>	TIMER peripheral selection
Input parameter{in}	
newvalue	control value
<i>ENABLE</i>	enable function
<i>DISABLE</i>	disable function
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* channel capture/compare control shadow register enable */
```

```
timer_channel_control_shadow_config (TIMER0, ENABLE);
```

timer_channel_control_shadow_update_config

The description of timer_channel_control_shadow_update_config is shown as below:

Table 3-521. Function timer_channel_control_shadow_update_config

Function name	timer_channel_control_shadow_update_config
Function prototype	void timer_channel_control_shadow_update_config(uint32_t timer_periph, uint8_t ccuctl);
Function descriptions	configure commutation control shadow register update control
Precondition	-
The called functions	-

Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0,7)</i>	TIMER peripheral selection
Input parameter{in}	
ccuctl	channel control shadow register update control
<i>TIMER_UPDATECTL_CCU</i>	the shadow registers update by when CMTG bit is set
<i>TIMER_UPDATECTL_CUTRI</i>	the shadow registers update by when CMTG bit is set or an rising edge of TRGI occurs
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel control shadow register update when CMTG bit is set */
timer_channel_control_shadow_update_config (TIMER0, TIMER_UPDATECTL_CCU);
```

timer_channel_output_struct_para_init

The description of timer_channel_output_struct_para_init is shown as below:

Table 3-522. Function timer_channel_output_struct_para_init

Function name	timer_channel_output_struct_para_init
Function prototype	void timer_channel_output_struct_para_init(timer_oc_parameter_struct* ocpa);
Function descriptions	initialize the parameters of TIMER channel output parameter struct with the default values
Precondition	-
The called functions	-
Input parameter{in}	
ocpara	TIMER channel output parameter struct, the structure members can refer to Table 3-486. Structure timer oc parameter struct .
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* initialize TIMER channel output parameter struct with a default value */
timer_oc_parameter_struct timer_ocinitpara;
timer_channel_output_struct_para_init(timer_ocinitpara);
```

timer_channel_output_config

The description of timer_channel_output_config is shown as below:

Table 3-523. Function timer_channel_output_config

Function name	timer_channel_output_config
Function prototype	void timer_channel_output_config(uint32_t timer_periph, uint16_t channel, timer_oc_parameter_struct* ocpara);
Function descriptions	configure TIMER channel output function
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx(x=0..4,7..13))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx(x=0..4,7,8,11))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx(x=0..4,7))
<i>TIMER_CH_3</i>	IMER channel 3 (TIMERx(x=0..4,7))
Input parameter{in}	
ocpara	TIMER channel output parameter struct, the structure members can refer to Table 3-486. Structure timer_oc_parameter_struct.
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* configure TIMER0 channel 0 output function */

timer_oc_parameter_struct timer_ocinitpara;

timer_ocinitpara.outputstate = TIMER_CCX_ENABLE;

timer_ocinitpara.outputnstate = TIMER_CCXN_ENABLE;

timer_ocinitpara.ocpolarity = TIMER_OC_POLARITY_HIGH;

timer_ocinitpara.ocnpolarity = TIMER_OCN_POLARITY_HIGH;

timer_ocinitpara.ocidlestate = TIMER_OC_IDLE_STATE_HIGH;

timer_ocinitpara.ocnidlestate = TIMER_OCN_IDLE_STATE_LOW;

timer_channel_output_config(TIMER0, TIMER_CH_0, &timer_ocinitpara);

```

timer_channel_output_mode_config

The description of timer_channel_output_mode_config is shown as below:

Table 3-524. Function timer_channel_output_mode_config

Function name	timer_channel_output_mode_config
Function prototype	void timer_channel_output_mode_config(uint32_t timer_periph, uint16_t channel, uint16_t ocmode);
Function descriptions	configure TIMER channel output compare mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx(x=0..4,7..13))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx(x=0..4,7,8,11))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx(x=0..4,7))
<i>TIMER_CH_3</i>	IMER channel 3 (TIMERx(x=0..4,7))
Input parameter{in}	
ocmode	channel output compare mode
<i>TIMER_OC_MODE_TIMING</i>	timing mode
<i>TIMER_OC_MODE_ACTIVE</i>	set the channel output
<i>TIMER_OC_MODE_INACTIVE</i>	clear the channel output
<i>TIMER_OC_MODE_TOGGLE</i>	toggle on match
<i>TIMER_OC_MODE_LOW</i>	force low mode
<i>TIMER_OC_MODE_HIGH</i>	force high mode
<i>TIMER_OC_MODE_PWM0</i>	PWM mode 0
<i>TIMER_OC_MODE_PWM1</i>	PWM mode 1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel PWM 0 mode */
```

```
timer_channel_output_mode_config(TIMER0, TIMER_CH_0, TIMER_OC_MODE_PWM0);
```

timer_channel_output_pulse_value_config

The description of timer_channel_output_pulse_value_config is shown as below:

Table 3-525. Function timer_channel_output_pulse_value_config

Function name	timer_channel_output_pulse_value_config
Function prototype	void timer_channel_output_pulse_value_config(uint32_t timer_periph, uint16_t channel, uint32_t pulse);
Function descriptions	configure TIMER channel output pulse value
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx(x=0..4,7..13))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx(x=0..4,7,8,11))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx(x=0..4,7))
<i>TIMER_CH_3</i>	IMER channel 3 (TIMERx(x=0..4,7))
Input parameter{in}	
pulse	channel output pulse value (0~65535)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 output pulse value */
```

```
timer_channel_output_pulse_value_config(TIMER0, TIMER_CH_0, 399);
```

timer_channel_output_shadow_config

The description of timer_channel_output_shadow_config is shown as below:

Table 3-526. Function timer_channel_output_shadow_config

Function name	timer_channel_output_shadow_config
Function prototype	void timer_channel_output_shadow_config(uint32_t timer_periph, uint16_t channel, uint16_t ocshadow);
Function descriptions	configure TIMER channel output shadow function
Precondition	-

The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx(x=0..4,7..13))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx(x=0..4,7,8,11))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx(x=0..4,7))
<i>TIMER_CH_3</i>	IMER channel 3 (TIMERx(x=0..4,7))
Input parameter{in}	
ocshadow	channel output shadow state
<i>TIMER_OC_SHADOW_ENABLE</i>	channel output shadow state enable
<i>TIMER_OC_SHADOW_DISABLE</i>	channel output shadow state disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/*configure TIMER0 channel 0 output shadow function */
```

```
timer_channel_output_shadow_config (TIMER0, TIMER_CH_0,  
TIMER_OC_SHADOW_ENABLE);
```

timer_channel_output_fast_config

The description of timer_channel_output_fast_config is shown as below:

Table 3-527. Function timer_channel_output_fast_config

Function name	timer_channel_output_fast_config
Function prototype	void timer_channel_output_fast_config(uint32_t timer_periph, uint16_t channel, uint16_t ocfast);
Function descriptions	configure TIMER channel output fast function
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx(x=0..4,7..13))

<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx(x=0..4,7,8,11))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx(x=0..4,7))
<i>TIMER_CH_3</i>	TIMER channel 3 (TIMERx(x=0..4,7))
Input parameter{in}	
ocfast	channel output fast function
<i>TIMER_OC_FAST_ENA BLE</i>	channel output fast function enable
<i>TIMER_OC_FAST_DIS ABLE</i>	channel output fast function disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 output fast function */
```

```
timer_channel_output_fast_config (TIMER0, TIMER_CH_0, TIMER_OC_FAST_ENABLE);
```

timer_channel_output_clear_config

The description of timer_channel_output_clear_config is shown as below:

Table 3-528. Function timer_channel_output_clear_config

Function name	timer_channel_output_clear_config
Function prototype	void timer_channel_output_clear_config(uint32_t timer_periph, uint16_t channel, uint16_t occlear);
Function descriptions	configure TIMER channel output clear function
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER periph
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx(x=0..4,7..13))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx(x=0..4,7,8,11))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx(x=0..4,7))
<i>TIMER_CH_3</i>	TIMER channel 3 (TIMERx(x=0..4,7))
Input parameter{in}	
occlear	channel output clear function
<i>TIMER_OC_CLEAR_EN ABLE</i>	channel output clear function enable
<i>TIMER_OC_CLEAR_DI</i>	channel output clear function disable

<i>SABLE</i>	
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 output clear function */
```

```
timer_channel_output_clear_config (TIMER0, TIMER_CH_0,  
TIMER_OC_CLEAR_ENABLE);
```

timer_channel_output_polarity_config

The description of timer_channel_output_polarity_config is shown as below:

Table 3-529. Function timer_channel_output_polarity_config

Function name	timer_channel_output_polarity_config
Function prototype	void timer_channel_output_polarity_config(uint32_t timer_periph, uint16_t channel, uint16_t ocpolarity);
Function descriptions	configure TIMER channel output polarity
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx(x=0..4,7..13))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx(x=0..4,7,8,11))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx(x=0..4,7))
<i>TIMER_CH_3</i>	IMER channel 3 (TIMERx(x=0..4,7))
Input parameter{in}	
ocpolarity	channel output polarity
<i>TIMER_OC_POLARITY_HIGH</i>	channel output polarity is high
<i>TIMER_OC_POLARITY_LOW</i>	channel output polarity is low
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 output polarity */
```

```
timer_channel_output_polarity_config (TIMER0, TIMER_CH_0,  
TIMER_OC_POLARITY_HIGH);
```

timer_channel_complementary_output_polarity_config

The description of timer_channel_complementary_output_polarity_config is shown as below:

Table 3-530. Function timer_channel_complementary_output_polarity_config

Function name	timer_channel_complementary_output_polarity_config
Function prototype	void timer_channel_complementary_output_polarity_config(uint32_t timer_periph, uint16_t channel, uint16_t ocpolarity);
Function descriptions	configure TIMER channel complementary output polarity
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0,7)</i>	TIMER peripheral selection
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0
<i>TIMER_CH_1</i>	TIMER channel 1
<i>TIMER_CH_2</i>	TIMER channel 2
Input parameter{in}	
ocpolarity	channel complementary output polarity
<i>TIMER_OCN_POLARITY_HIGH</i>	channel complementary output polarity is high
<i>TIMER_OCN_POLARITY_LOW</i>	channel complementary output polarity is low
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 complementary output polarity */
```

```
timer_channel_complementary_output_polarity_config (TIMER0, TIMER_CH_0,  
TIMER_OCN_POLARITY_HIGH);
```

timer_channel_output_state_config

The description of timer_channel_output_state_config is shown as below:

Table 3-531. Function timer_channel_output_state_config

Function name	timer_channel_output_state_config
Function prototype	void timer_channel_output_state_config(uint32_t timer_periph, uint16_t channel, uint32_t state);
Function descriptions	configure TIMER channel enable state
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx(x=0..4,7..13))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx(x=0..4,7,8,11))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx(x=0..4,7))
<i>TIMER_CH_3</i>	IMER channel 3 (TIMERx(x=0..4,7))
Input parameter{in}	
state	TIMER channel enable state
<i>TIMER_CCX_ENABLE</i>	channel enable
<i>TIMER_CCX_DISABLE</i>	channel disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 enable state */
```

```
timer_channel_output_state_config (TIMER0, TIMER_CH_0, TIMER_CCX_ENABLE);
```

timer_channel_complementary_output_state_config

The description of timer_channel_complementary_output_state_config is shown as below:

Table 3-532. Function timer_channel_complementary_output_state_config

Function name	timer_channel_complementary_output_state_config
Function prototype	void timer_channel_complementary_output_state_config(uint32_t timer_periph, uint16_t channel, uint16_t ocnstate);
Function descriptions	configure TIMER channel complementary output enable state
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0,7)</i>	TIMER peripheral selection

Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0
<i>TIMER_CH_1</i>	TIMER channel 1
<i>TIMER_CH_2</i>	TIMER channel 2
Input parameter{in}	
state	TIMER channel complementary output enable state
<i>TIMER_CCXN_ENABLE</i>	channel complementary enable
<i>TIMER_CCXN_DISABLE</i>	channel complementary disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 complementary output enable state */
```

```
timer_channel_complementary_output_state_config (TIMER0, TIMER_CH_0,  
TIMER_CCXN_ENABLE);
```

timer_channel_input_struct_para_init

The description of timer_channel_input_struct_para_init is shown as below:

Table 3-533. Function timer_channel_input_struct_para_init

Function name	timer_channel_input_struct_para_init
Function prototype	void timer_channel_input_struct_para_init(timer_ic_parameter_struct* icpara);
Function descriptions	initialize the parameters of TIMER channel input parameter struct with the default values
Precondition	-
The called functions	-
Input parameter{in}	
icpara	TIMER channel input parameter struct, the structure members can refer to Table 3-487. Structure timer_ic_parameter_struct .
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* initialize TIMER channel input parameter struct with a default value */
```

```
timer_ic_parameter_struct timer_icinitpara;
```

```
timer_channel_input_struct_para_init(timer_icinitpara);
```

timer_input_capture_config

The description of timer_input_capture_config is shown as below:

Table 3-534. Function timer_input_capture_config

Function name	timer_input_capture_config
Function prototype	void timer_input_capture_config(uint32_t timer_periph, uint16_t channel, timer_ic_parameter_struct* icpara);
Function descriptions	configure TIMER input capture parameter
Precondition	-
The called functions	timer_channel_input_capture_prescaler_config
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx(x=0..4,7..13))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx(x=0..4,7,8,11))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx(x=0..4,7))
<i>TIMER_CH_3</i>	IMER channel 3 (TIMERx(x=0..4,7))
Input parameter{in}	
icpara	TIMER channel input parameter struct, the structure members can refer to Table 3-487. Structure timer_ic_parameter_struct .
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 input capture parameter */
timer_ic_parameter_struct timer_icinitpara;
timer_icinitpara.icpolarity = TIMER_IC_POLARITY_RISING;
timer_icinitpara.icselection = TIMER_IC_SELECTION_DIRECTTTI;
timer_icinitpara.icprescaler = TIMER_IC_PSC_DIV1;
timer_icinitpara.icfilter = 0x0;
timer_input_capture_config(TIMER0, TIMER_CH_0, &timer_icinitpara);
```

timer_channel_input_capture_prescaler_config

The description of timer_channel_input_capture_prescaler_config is shown as below:

Table 3-535. Function timer_channel_input_capture_prescaler_config

Function name	timer_channel_input_capture_prescaler_config
Function prototype	void timer_channel_input_capture_prescaler_config(uint32_t timer_periph, uint16_t channel, uint16_t prescaler);
Function descriptions	configure TIMER channel input capture prescaler value
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx(x=0..4,7..13))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx(x=0..4,7,8,11))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx(x=0..4,7))
<i>TIMER_CH_3</i>	IMER channel 3 (TIMERx(x=0..4,7))
Input parameter{in}	
prescaler	channel input capture prescaler value
<i>TIMER_IC_PSC_DIV1</i>	no prescaler
<i>TIMER_IC_PSC_DIV2</i>	divided by 2
<i>TIMER_IC_PSC_DIV4</i>	divided by 4
<i>TIMER_IC_PSC_DIV8</i>	divided by 8
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 input capture prescaler value */
```

```
timer_channel_input_capture_prescaler_config (TIMER0, TIMER_CH_0,  
TIMER_IC_PSC_DIV2);
```

timer_channel_capture_value_register_read

The description of timer_channel_capture_value_register_read is shown as below:

Table 3-536. Function timer_channel_capture_value_register_read

Function name	timer_channel_capture_value_register_read
Function prototype	uint32_t timer_channel_capture_value_register_read(uint32_t timer_periph, uint16_t channel);

Function descriptions	read TIMER channel capture compare register value
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx(x=0..4,7..13))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx(x=0..4,7,8,11))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx(x=0..4,7))
<i>TIMER_CH_3</i>	IMER channel 3 (TIMERx(x=0..4,7))
Output parameter{out}	
-	-
Return value	
uint32_t	channel capture compare register value (0x0000~0xFFFF)

Example:

```
/* read TIMER0 channel 0 capture compare register value */
```

```
uint32_t ch0_value = 0;
```

```
ch0_value = timer_channel_capture_value_register_read (TIMER0, TIMER_CH_0);
```

timer_input_pwm_capture_config

The description of timer_input_pwm_capture_config is shown as below:

Table 3-537. Function timer_input_pwm_capture_config

Function name	timer_input_pwm_capture_config
Function prototype	void timer_input_pwm_capture_config(uint32_t timer_periph, uint16_t channel, timer_ic_parameter_struct* icpwm);
Function descriptions	configure TIMER input pwm capture function
Precondition	-
The called functions	timer_channel_input_capture_prescaler_config
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7,8,11)</i>	TIMER peripheral selection
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0
<i>TIMER_CH_1</i>	TIMER channel 1
Input parameter{in}	
icpwm	TIMER channel input pwm parameter struct, the structure members can refer to Table 3-487. Structure timer_ic_parameter_struct.

Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* configure TIMER0 input pwm capture parameter */

timer_ic_parameter_struct timer_icinitpara;

timer_icinitpara.icpolarity = TIMER_IC_POLARITY_RISING;

timer_icinitpara.icselection = TIMER_IC_SELECTION_DIRECTTTI;

timer_icinitpara.icprescaler = TIMER_IC_PSC_DIV1;

timer_icinitpara.icfilter = 0x0;

timer_input_pwm_capture_config (TIMER0, TIMER_CH_0, &timer_icinitpara);

```

timer_hall_mode_config

The description of timer_hall_mode_config is shown as below:

Table 3-538. Function timer_hall_mode_config

Function name	timer_hall_mode_config
Function prototype	void timer_hall_mode_config(uint32_t timer_periph, uint8_t hallmode);
Function descriptions	configure TIMER hall sensor mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
TIMERx(x=0..4,7)	TIMER peripheral selection
Input parameter{in}	
hallmode	TIMER hall sensor mode state
TIMER_HALLINTERFA CE_ENABLE	TIMER hall sensor mode enable
TIMER_HALLINTERFA CE_DISABLE	TIMER hall sensor mode disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* configure TIMER0 hall sensor mode */

```

timer_hall_mode_config (TIMER0, TIMER_HALLINTERFACE_ENABLE);

timer_input_trigger_source_select

The description of timer_input_trigger_source_select is shown as below:

Table 3-539. Function timer_input_trigger_source_select

Function name	timer_input_trigger_source_select
Function prototype	void timer_input_trigger_source_select(uint32_t timer_periph, uint32_t intrigger);
Function descriptions	select TIMER input trigger source
Precondition	SMC[2:0] = 000
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
intrigger	trigger selection
<i>TIMER_SMCFG_TRGS EL_ITI0</i>	Internal trigger input 0 (ITI0, TIMERx(x=0..4,7,8,11))
<i>TIMER_SMCFG_TRGS EL_ITI1</i>	Internal trigger input 0 (ITI1, TIMERx(x=0..4,7,8,11))
<i>TIMER_SMCFG_TRGS EL_ITI2</i>	Internal trigger input 0 (ITI2, TIMERx(x=0..4,7,8,11))
<i>TIMER_SMCFG_TRGS EL_ITI3</i>	Internal trigger input 0 (ITI3, TIMERx(x=0..4,7,8,11))
<i>TIMER_SMCFG_TRGS EL_CIOF_ED</i>	CIO edge flag (CIOF_ED, TIMERx(x=0..4,7,8,11))
<i>TIMER_SMCFG_TRGS EL_CIOFE0</i>	channel 0 input Filtered output (CIOFE0, TIMERx(x=0..4,7,8,11))
<i>TIMER_SMCFG_TRGS EL_C1FE1</i>	channel 1 input Filtered output (C1FE1, TIMERx(x=0..4,7,8,11))
<i>TIMER_SMCFG_TRGS EL_ETIFP</i>	External trigger input filter output(ETIFP, TIMERx(x=0..4,7))
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* select TIMER0 input trigger source */
```

```
timer_input_trigger_source_select (TIMER0, TIMER_SMCFG_TRGSEL_ITI0);
```

timer_master_output_trigger_source_select

The description of timer_master_output_trigger_source_select is shown as below:

Table 3-540. Function timer_master_output_trigger_source_select

Function name	timer_master_output_trigger_source_select
Function prototype	void timer_master_output_trigger_source_select(uint32_t timer_periph, uint32_t outrigger);
Function descriptions	select TIMER master mode output trigger source
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0,7)</i>	TIMER peripheral selection
Input parameter{in}	
outrigger	master mode control
<i>TIMER_TRI_OUT_SRC_RESET</i>	Reset. When the UPG bit in the <i>TIMERx_SWEVG</i> register is set or a reset is generated by the slave mode controller, a TRGO pulse occurs. And in the latter case, the signal on TRGO is delayed compared to the actual reset
<i>TIMER_TRI_OUT_SRC_ENABLE</i>	Enable. This mode is useful to start several timers at the same time or to control a window in which a slave timer is enabled. In this mode the master mode controller selects the counter enable signal as TRGO. The counter enable signal is set when CEN control bit is set or the trigger input in pause mode is high. There is a delay between the trigger input in pause mode and the TRGO output, except if the master-slave mode is selected.
<i>TIMER_TRI_OUT_SRC_UPDATE</i>	Update. In this mode the master mode controller selects the update event as TRGO.
<i>TIMER_TRI_OUT_SRC_CC0</i>	Capture/compare pulse. In this mode the master mode controller generates a TRGO pulse when a capture or a compare match occurred in channel 0.
<i>TIMER_TRI_OUT_SRC_O0CPRE</i>	Compare. In this mode the master mode controller selects the O0CPRE signal is used as TRGO.
<i>TIMER_TRI_OUT_SRC_O1CPRE</i>	Compare. In this mode the master mode controller selects the O1CPRE signal is used as TRGO.
<i>TIMER_TRI_OUT_SRC_O2CPRE</i>	Compare. In this mode the master mode controller selects the O2CPRE signal is used as TRGO.
<i>TIMER_TRI_OUT_SRC_O3CPRE</i>	Compare. In this mode the master mode controller selects the O3CPRE signal is used as TRGO.
Output parameter{out}	
-	-
Return value	
-	-

Example:


```
/* select TIMER0 master mode output trigger source */
```

```
timer_master_output_trigger_source_select (TIMER0, TIMER_TRI_OUT_SRC_RESET);
```

timer_slave_mode_select

The description of timer_slave_mode_select is shown as below:

Table 3-541. Function timer_slave_mode_select

Function name	timer_slave_mode_select
Function prototype	void timer_slave_mode_select(uint32_t timer_periph, uint32_t slavemode);
Function descriptions	select TIMER slave mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7,8,11)</i>	TIMER peripheral selection
Input parameter{in}	
slavemode	slave mode
<i>TIMER_SLAVE_MODE_DISABLE</i>	slave mode disable
<i>TIMER_QUAD_DECODER_MODE0</i>	quadrature decoder mode 0
<i>TIMER_QUAD_DECODER_MODE1</i>	quadrature decoder mode 1
<i>TIMER_QUAD_DECODER_MODE2</i>	quadrature decoder mode 2
<i>TIMER_SLAVE_MODE_RESTART</i>	restart mode
<i>TIMER_SLAVE_MODE_PAUSE</i>	pause mode
<i>TIMER_SLAVE_MODE_EVENT</i>	event mode
<i>TIMER_SLAVE_MODE_EXTERNAL0</i>	external clock mode 0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* select TIMER0 slave mode */
```

```
timer_slave_mode_select (TIMER0, TIMER_QUAD_DECODER_MODE0);
```

timer_master_slave_mode_config

The description of timer_master_slave_mode_config is shown as below:

Table 3-542. Function timer_master_slave_mode_config

Function name	timer_master_slave_mode_config
Function prototype	void timer_master_slave_mode_config(uint32_t timer_periph, uint8_t masterslave);
Function descriptions	configure TIMER master slave mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7,8,11)</i>	TIMER peripheral selection
Input parameter{in}	
masterslave	master slave mode state
<i>TIMER_MASTER_SLAVE_MODE_ENABLE</i>	master slave mode enable
<i>TIMER_MASTER_SLAVE_MODE_DISABLE</i>	master slave mode disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 master slave mode */
```

```
timer_master_slave_mode_config (TIMER0, TIMER_MASTER_SLAVE_MODE_ENABLE);
```

timer_external_trigger_config

The description of timer_external_trigger_config is shown as below:

Table 3-543. Function timer_external_trigger_config

Function name	timer_external_trigger_config
Function prototype	void timer_external_trigger_config(uint32_t timer_periph, uint32_t extprescaler, uint32_t expolarity, uint32_t extfilter);
Function descriptions	configure TIMER external trigger input
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7)</i>	TIMER peripheral selection
Input parameter{in}	

extprescaler	external trigger prescaler
<i>TIMER_EXT_TRI_PSC_OFF</i>	no divided
<i>TIMER_EXT_TRI_PSC_DIV2</i>	divided by 2
<i>TIMER_EXT_TRI_PSC_DIV4</i>	divided by 4
<i>TIMER_EXT_TRI_PSC_DIV8</i>	divided by 8
Input parameter{in}	
expolarity	external trigger polarity
<i>TIMER_ETP_FALLING</i>	active low or falling edge active
<i>TIMER_ETP_RISING</i>	active high or rising edge active
Input parameter{in}	
extfilter	external trigger filter control (0~15)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 external trigger input */
```

```
timer_external_trigger_config (TIMER0, TIMER_EXT_TRI_PSC_DIV2,  
TIMER_ETP_FALLING, 10);
```

timer_quadrature_decoder_mode_config

The description of timer_quadrature_decoder_mode_config is shown as below:

Table 3-544. Function timer_quadrature_decoder_mode_config

Function name	timer_quadrature_decoder_mode_config
Function prototype	void timer_quadrature_decoder_mode_config(uint32_t timer_periph, uint32_t decomode, uint16_t ic0polarity, uint16_t ic1polarity);
Function descriptions	configure TIMER quadrature decoder mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7)</i>	TIMER peripheral selection
Input parameter{in}	
decomode	quadrature decoder mode
<i>TIMER_QUAD_DECODER_MODE0</i>	counter counts on CI0FE0 edge depending on CI1FE1 level

<i>TIMER_QUAD_DECODER_MODE1</i>	counter counts on CI1FE1 edge depending on CI0FE0 level
<i>TIMER_QUAD_DECODER_MODE2</i>	counter counts on both CI0FE0 and CI1FE1 edges depending on the level of the other input
Input parameter{in}	
ic0polarity	IC0 polarity
<i>TIMER_IC_POLARITY_RISING</i>	capture rising edge
<i>TIMER_IC_POLARITY_FALLING</i>	capture falling edge
Input parameter{in}	
ic1polarity	IC1 polarity
<i>TIMER_IC_POLARITY_RISING</i>	capture rising edge
<i>TIMER_IC_POLARITY_FALLING</i>	capture falling edge
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 quadrature decoder mode */
```

```
timer_quadrature_decoder_mode_config (TIMER0, TIMER_QUAD_DECODER_MODE0,  
TIMER_IC_POLARITY_RISING, TIMER_IC_POLARITY_RISING);
```

timer_internal_clock_config

The description of timer_internal_clock_config is shown as below:

Table 3-545. Function timer_internal_clock_config

Function name	timer_internal_clock_config
Function prototype	void timer_internal_clock_config(uint32_t timer_periph);
Function descriptions	configure TIMER internal clock mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7,8,11)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 internal clock mode */
```

```
timer_internal_clock_config (TIMER0);
```

timer_internal_trigger_as_external_clock_config

The description of timer_internal_trigger_as_external_clock_config is shown as below:

Table 3-546. Function timer_internal_trigger_as_external_clock_config

Function name	timer_internal_trigger_as_external_clock_config
Function prototype	void timer_internal_trigger_as_external_clock_config(uint32_t timer_periph, uint32_t intrigger);
Function descriptions	configure TIMER the internal trigger as external clock input
Precondition	-
The called functions	timer_input_trigger_source_select
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7,8,11)</i>	TIMER peripheral selection
Input parameter{in}	
intrigger	trigger selection
<i>TIMER_SMCFG_TRGS_EL_ITI0</i>	Internal trigger input 0 (ITI0)
<i>TIMER_SMCFG_TRGS_EL_ITI1</i>	Internal trigger input 0 (ITI1)
<i>TIMER_SMCFG_TRGS_EL_ITI2</i>	Internal trigger input 0 (ITI2)
<i>TIMER_SMCFG_TRGS_EL_ITI3</i>	Internal trigger input 0 (ITI3)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 the internal trigger ITI0 as external clock input */
```

```
timer_internal_trigger_as_external_clock_config (TIMER0, TIMER_SMCFG_TRGSEL_ITI0);
```

timer_external_trigger_as_external_clock_config

The description of timer_external_trigger_as_external_clock_config is shown as below:

Table 3-547. Function timer_external_trigger_as_external_clock_config

Function name	timer_external_trigger_as_external_clock_config
----------------------	---

Function prototype	void timer_external_trigger_as_external_clock_config(uint32_t timer_periph, uint32_t extrigger, uint16_t expolarity, uint32_t extfilter);
Function descriptions	configure TIMER the external trigger as external clock input
Precondition	-
The called functions	timer_input_trigger_source_select
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7,8,11)</i>	TIMER peripheral selection
Input parameter{in}	
extrigger	external trigger selection
<i>TIMER_SMCFG_TRGS EL_CIOF_ED</i>	CIO edge flag (CIOF_ED)
<i>TIMER_SMCFG_TRGS EL_CIOFE0</i>	channel 0 input Filtered output (CIOFE0)
<i>TIMER_SMCFG_TRGS EL_C1FE1</i>	channel 1 input Filtered output (C1FE1)
Input parameter{in}	
expolarity	external trigger polarity
<i>TIMER_IC_POLARITY_ RISING</i>	active high or rising edge active
<i>TIMER_IC_POLARITY_ FALLING</i>	active low or falling edge active
Input parameter{in}	
extfilter	external trigger filter control (0~15)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 the external trigger CIOFE0 as external clock input */
```

```
timer_external_trigger_as_external_clock_config (TIMER0,  
TIMER_SMCFG_TRGSEL_CIOFE0, TIMER_IC_POLARITY_RISING, 0);
```

timer_external_clock_mode0_config

The description of timer_external_clock_mode0_config is shown as below:

Table 3-548. Function timer_external_clock_mode0_config

Function name	timer_external_clock_mode0_config
Function prototype	void timer_external_clock_mode0_config(uint32_t timer_periph, uint32_t extprescaler, uint32_t expolarity, uint32_t extfilter);
Function descriptions	configure TIMER the external clock mode0

Precondition	-
The called functions	timer_external_trigger_config
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7,8,11)</i>	TIMER peripheral selection
Input parameter{in}	
extprescaler	ETI external trigger prescaler
<i>TIMER_EXT_TRI_PSC_OFF</i>	no divided
<i>TIMER_EXT_TRI_PSC_DIV2</i>	divided by 2
<i>TIMER_EXT_TRI_PSC_DIV4</i>	divided by 4
<i>TIMER_EXT_TRI_PSC_DIV8</i>	divided by 8
Input parameter{in}	
expolarity	ETI external trigger polarity
<i>TIMER_ETP_FALLING</i>	active low or falling edge active
<i>TIMER_ETP_RISING</i>	active high or rising edge active
Input parameter{in}	
extfilter	ETI external trigger filter control (0~15)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 the external clock mode0 */
```

```
timer_external_clock_mode0_config (TIMER0, TIMER_EXT_TRI_PSC_DIV2,  
TIMER_ETP_FALLING, 0);
```

timer_external_clock_mode1_config

The description of timer_external_clock_mode1_config is shown as below:

Table 3-549. Function timer_external_clock_mode1_config

Function name	timer_external_clock_mode1_config
Function prototype	void timer_external_clock_mode1_config(uint32_t timer_periph, uint32_t extprescaler, uint32_t expolarity, uint32_t extfilter);
Function descriptions	configure TIMER the external clock mode1
Precondition	-
The called functions	timer_external_trigger_config
Input parameter{in}	

timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7)</i>	TIMER peripheral selection
Input parameter{in}	
extprescaler	ETI external trigger prescaler
<i>TIMER_EXT_TRI_PSC_OFF</i>	no divided
<i>TIMER_EXT_TRI_PSC_DIV2</i>	divided by 2
<i>TIMER_EXT_TRI_PSC_DIV4</i>	divided by 4
<i>TIMER_EXT_TRI_PSC_DIV8</i>	divided by 8
Input parameter{in}	
expolarity	ETI external trigger polarity
<i>TIMER_ETP_FALLING</i>	active low or falling edge active
<i>TIMER_ETP_RISING</i>	active high or rising edge active
Input parameter{in}	
extfilter	ETI external trigger filter control (0~15)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 the external clock mode1 */
```

```
timer_external_clock_mode1_config (TIMER0, TIMER_EXT_TRI_PSC_DIV2,  
TIMER_ETP_FALLING, 0);
```

timer_external_clock_mode1_disable

The description of timer_external_clock_mode1_disable is shown as below:

Table 3-550. Function timer_external_clock_mode1_disable

Function name	timer_external_clock_mode1_disable
Function prototype	void timer_external_clock_mode1_disable(uint32_t timer_periph);
Function descriptions	disable TIMER the external clock mode1
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7)</i>	TIMER peripheral selection
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* disable TIMER0 the external clock mode1 */
```

```
timer_external_clock_mode1_disable (TIMER0);
```

timer_write_chxval_register_config

The description of timer_write_chxval_register_config is shown as below:

Table 3-551. Function timer_write_chxval_register_config

Function name	timer_write_chxval_register_config
Function prototype	void timer_write_chxval_register_config(uint32_t timer_periph, uint16_t ccsel);
Function descriptions	configure TIMER write CHxVAL register selection
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0..4,7..13)</i>	TIMER peripheral selection
Input parameter{in}	
ccsel	write CHxVAL register selection
<i>TIMER_CHVSEL_DISABLE</i>	no effect
<i>TIMER_CHVSEL_ENABLE</i>	when write the CHxVAL register, if the write value is same as the CHxVAL value, the write access is ignored
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 write CHxVAL register selection */
```

```
timer_write_chxval_register_config(TIMER0, TIMER_CHVSEL_ENABLE);
```

timer_output_value_selection_config

The description of timer_output_value_selection_config is shown as below:

Table 3-552. Function timer_output_value_selection_config

Function name	timer_output_value_selection_config
Function prototype	void timer_output_value_selection_config(uint32_t timer_periph, uint16_t outsel);

Function descriptions	configure TIMER output value selection
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx (x=0,7)</i>	TIMER peripheral selection
Input parameter{in}	
outsel	output value selection
<i>TIMER_OUTSEL_DISABLE</i>	no effect
<i>TIMER_OUTSEL_ENABLE</i>	if POEN and IOS is 0, the output disabled
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER output value selection */
```

```
timer_output_value_selection_config(TIMER0, TIMER_OUTSEL_ENABLE);
```

timer_interrupt_enable

The description of timer_interrupt_enable is shown as below:

Table 3-553. Function timer_interrupt_enable

Function name	timer_interrupt_enable
Function prototype	void timer_interrupt_enable(uint32_t timer_periph, uint32_t interrupt);
Function descriptions	enable the TIMER interrupt
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
interrupt	timer interrupt enable source
<i>TIMER_INT_UP</i>	update interrupt enable, <i>TIMERx</i> (x=0..13)
<i>TIMER_INT_CH0</i>	channel 0 interrupt enable, <i>TIMERx</i> (x=0..4,7..13)
<i>TIMER_INT_CH1</i>	channel 1 interrupt enable, <i>TIMERx</i> (x=0..4,7,8,11)
<i>TIMER_INT_CH2</i>	channel 2 interrupt enable, <i>TIMERx</i> (x=0..4,7)
<i>TIMER_INT_CH3</i>	channel 3 interrupt enable , <i>TIMERx</i> (x=0..4,7)
<i>TIMER_INT_CMT</i>	commutation interrupt enable, <i>TIMERx</i> (x=0,7)
<i>TIMER_INT_TRG</i>	trigger interrupt enable, <i>TIMERx</i> (x=0..4,7,8,11)

<i>TIMER_INT_BRK</i>	break interrupt enable, <i>TIMERx</i> (<i>x</i> =0,7)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the TIMER0 update interrupt */
```

```
timer_interrupt_enable (TIMER0, TIMER_INT_UP);
```

timer_interrupt_disable

The description of `timer_interrupt_disable` is shown as below:

Table 3-554. Function `timer_interrupt_disable`

Function name	<code>timer_interrupt_disable</code>
Function prototype	<code>void timer_interrupt_disable (uint32_t timer_periph, uint32_t interrupt);</code>
Function descriptions	disable the TIMER interrupt
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
interrupt	timer interrupt disable source
<i>TIMER_INT_UP</i>	update interrupt disable, <i>TIMERx</i> (<i>x</i> =0..13)
<i>TIMER_INT_CH0</i>	channel 0 interrupt disable, <i>TIMERx</i> (<i>x</i> =0..4,7..13)
<i>TIMER_INT_CH1</i>	channel 1 interrupt disable, <i>TIMERx</i> (<i>x</i> =0..4,7,8,11)
<i>TIMER_INT_CH2</i>	channel 2 interrupt disable, <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_INT_CH3</i>	channel 3 interrupt disable, <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_INT_CMT</i>	commutation interrupt disable, <i>TIMERx</i> (<i>x</i> =0,7)
<i>TIMER_INT_TRG</i>	trigger interrupt disable, <i>TIMERx</i> (<i>x</i> =0..4,7,8,11)
<i>TIMER_INT_BRK</i>	break interrupt disable, <i>TIMERx</i> (<i>x</i> =0,7)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the TIMER0 update interrupt */
```

```
timer_interrupt_disable (TIMER0, TIMER_INT_UP);
```

timer_interrupt_flag_get

The description of timer_interrupt_flag_get is shown as below:

Table 3-555. Function timer_interrupt_flag_get

Function name	timer_interrupt_flag_get
Function prototype	FlagStatus timer_interrupt_flag_get(uint32_t timer_periph, uint32_t interrupt);
Function descriptions	get timer interrupt flag
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
interrupt	the timer interrupt bits
<i>TIMER_INT_FLAG_UP</i>	update interrupt flag, <i>TIMERx</i> (x=0..13)
<i>TIMER_INT_FLAG_CH0</i>	channel 0 interrupt flag, <i>TIMERx</i> (x=0..4,7..13)
<i>TIMER_INT_FLAG_CH1</i>	channel 1 interrupt flag, <i>TIMERx</i> (x=0..4,7,8,11)
<i>TIMER_INT_FLAG_CH2</i>	channel 2 interrupt flag, <i>TIMERx</i> (x=0..4,7)
<i>TIMER_INT_FLAG_CH3</i>	channel 3 interrupt flag, <i>TIMERx</i> (x=0..4,7)
<i>TIMER_INT_FLAG_CMT</i>	channel commutation interrupt flag, <i>TIMERx</i> (x=0,7)
<i>TIMER_INT_FLAG_TRG</i>	trigger interrupt flag, <i>TIMERx</i> (x=0,7,8,11)
<i>TIMER_INT_FLAG_BRK</i>	break interrupt flag, <i>TIMERx</i> (x=0,7)
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get TIMER0 update interrupt flag */
```

```
FlagStatus Flag_interrupt = RESET;
```

```
Flag_interrupt = timer_interrupt_flag_get (TIMER0, TIMER_INT_FLAG_UP);
```

timer_interrupt_flag_clear

The description of timer_interrupt_flag_clear is shown as below:

Table 3-556. Function timer_interrupt_flag_clear

Function name	timer_interrupt_flag_clear
Function prototype	void timer_interrupt_flag_clear(uint32_t timer_periph, uint32_t interrupt);
Function descriptions	clear TIMER interrupt flag

Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
interrupt	the timer interrupt bits
<i>TIMER_INT_FLAG_UP</i>	update interrupt flag, <i>TIMERx</i> (<i>x</i> =0..13)
<i>TIMER_INT_FLAG_CH0</i>	channel 0 interrupt flag, <i>TIMERx</i> (<i>x</i> =0..4,7..13)
<i>TIMER_INT_FLAG_CH1</i>	channel 1 interrupt flag, <i>TIMERx</i> (<i>x</i> =0..4,7,8,11)
<i>TIMER_INT_FLAG_CH2</i>	channel 2 interrupt flag, <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_INT_FLAG_CH3</i>	channel 3 interrupt flag, <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_INT_FLAG_CMT</i>	channel commutation interrupt flag, <i>TIMERx</i> (<i>x</i> =0,7)
<i>TIMER_INT_FLAG_TRG</i>	trigger interrupt flag, <i>TIMERx</i> (<i>x</i> =0,7,8,11)
<i>TIMER_INT_FLAG_BRK</i>	break interrupt flag, <i>TIMERx</i> (<i>x</i> =0,7)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear TIMER0 update interrupt flag */
```

```
timer_interrupt_flag_clear (TIMER0, TIMER_INT_FLAG_UP);
```

timer_flag_get

The description of timer_flag_get is shown as below:

Table 3-557. Function timer_flag_get

Function name	timer_flag_get
Function prototype	FlagStatus timer_flag_get(uint32_t timer_periph, uint32_t flag);
Function descriptions	get TIMER flags
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
flag	the timer interrupt flags
<i>TIMER_FLAG_UP</i>	update flag, <i>TIMERx</i> (<i>x</i> =0..13)
<i>TIMER_FLAG_CH0</i>	channel 0 flag, <i>TIMERx</i> (<i>x</i> =0..4,7..13)
<i>TIMER_FLAG_CH1</i>	channel 1 flag, <i>TIMERx</i> (<i>x</i> =0..4,7,8,11)

<i>TIMER_FLAG_CH2</i>	channel 2 flag, <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_FLAG_CH3</i>	channel 3 flag, <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_FLAG_CMT</i>	channel commutation flag, <i>TIMERx</i> (<i>x</i> =0,7)
<i>TIMER_FLAG_TRG</i>	trigger flag, <i>TIMERx</i> (<i>x</i> =0,7,8,11)
<i>TIMER_FLAG_BRK</i>	break flag, <i>TIMERx</i> (<i>x</i> =0,7)
<i>TIMER_FLAG_CH0O</i>	channel 0 overcapture flag, <i>TIMERx</i> (<i>x</i> =0..4,7..11)
<i>TIMER_FLAG_CH1O</i>	channel 1 overcapture flag, <i>TIMERx</i> (<i>x</i> =0..4,7,8,11)
<i>TIMER_FLAG_CH2O</i>	channel 2 overcapture flag, <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_FLAG_CH3O</i>	channel 3 overcapture flag, <i>TIMERx</i> (<i>x</i> =0..4,7)
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get TIMERO update flags */
```

```
FlagStatus Flag_status = RESET;
```

```
Flag_status = timer_flag_get (TIMERO, TIMER_FLAG_UP);
```

timer_flag_clear

The description of timer_flag_clear is shown as below:

Table 3-558. Function timer_flag_clear

Function name	timer_flag_clear
Function prototype	void timer_flag_clear(uint32_t timer_periph, uint32_t flag);
Function descriptions	clear TIMER flags
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
flag	the timer interrupt flags
<i>TIMER_FLAG_UP</i>	update flag, <i>TIMERx</i> (<i>x</i> =0..13)
<i>TIMER_FLAG_CH0</i>	channel 0 flag, <i>TIMERx</i> (<i>x</i> =0..4,7..13)
<i>TIMER_FLAG_CH1</i>	channel 1 flag, <i>TIMERx</i> (<i>x</i> =0..4,7,8,11)
<i>TIMER_FLAG_CH2</i>	channel 2 flag, <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_FLAG_CH3</i>	channel 3 flag, <i>TIMERx</i> (<i>x</i> =0..4,7)
<i>TIMER_FLAG_CMT</i>	channel commutation flag, <i>TIMERx</i> (<i>x</i> =0,7)
<i>TIMER_FLAG_TRG</i>	trigger flag, <i>TIMERx</i> (<i>x</i> =0,7,8,11)
<i>TIMER_FLAG_BRK</i>	break flag, <i>TIMERx</i> (<i>x</i> =0,7)

<i>TIMER_FLAG_CH0O</i>	channel 0 overcapture flag, $TIMERx(x=0..4,7..11)$
<i>TIMER_FLAG_CH1O</i>	channel 1 overcapture flag, $TIMERx(x=0..4,7,8,11)$
<i>TIMER_FLAG_CH2O</i>	channel 2 overcapture flag, $TIMERx(x=0..4,7)$
<i>TIMER_FLAG_CH3O</i>	channel 3 overcapture flag, $TIMERx(x=0..4,7)$
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear TIMER0 update flags */
timer_flag_clear (TIMER0, TIMER_FLAG_UP);
```

3.22. USART

The Universal Synchronous/Asynchronous Receiver/Transmitter (USART) provides a flexible serial data exchange interface. The USART registers are listed in chapter [3.22.1](#), the USART firmware functions are introduced in chapter [3.22.2](#).

3.22.1. Descriptions of Peripheral registers

USART registers are listed in the table shown as below:

Table 3-559. USART Registers

Registers	Descriptions
USART_STAT0	Status register 0
USART_DATA	Data register
USART_BAUD	Baud rate register
USART_CTL0	Control register 0
USART_CTL1	Control register 1
USART_CTL2	Control register 2
USART_GP	Guard time and prescaler register
USART_CTL3	Control register 3
USART_RT	Receiver timeout register
USART_STAT1	Status register 1
USART_CHC	Coherence control register

3.22.2. Descriptions of Peripheral functions

USART firmware functions are listed in the table shown as below:

Table 3-560. USART firmware function

Function name	Function description
usart_deinit	reset USART/UART
usart_baudrate_set	configure USART baud rate value
usart_parity_config	configure USART parity
usart_word_length_set	configure USART word length
usart_stop_bit_set	configure USART stop bit length
usart_enable	enable USART
usart_disable	disable USART
usart_transmit_config	configure USART transmitter
usart_receive_config	configure USART receiver
usart_data_first_config	data is transmitted/received with the LSB/MSB first
usart_invert_config	configure USART inverted
usart_receiver_timeout_enable	enable receiver timeout
usart_receiver_timeout_disable	disable receiver timeout
usart_receiver_timeout_threshold_config	configure receiver timeout threshold
usart_data_transmit	USART transmit data function
usart_data_receive	USART receive data function
usart_address_config	configure the address of the USART in wake up by address match mode
usart_mute_mode_enable	enable mute mode
usart_mute_mode_disable	disable mute mode
usart_mute_mode_wakeup_config	configure wakeup method in mute mode
usart_lin_mode_enable	enable LIN mode
usart_lin_mode_disable	disable LIN mode
usart_lin_break_dection_length_config	configure LIN break frame length
usart_send_break	send break frame
usart_halfduplex_enable	enable half duplex mode
usart_halfduplex_disable	disable half duplex mode
usart_synchronous_clock_enable	enable CK pin in synchronous mode
usart_synchronous_clock_disable	disable CK pin in synchronous mode
usart_synchronous_clock_config	configure USART synchronous mode parameters
usart_guard_time_config	configure guard time value in smartcard mode
usart_smartcard_mode_enable	enable smartcard mode
usart_smartcard_mode_disable	disable smartcard mode
usart_smartcard_mode_nack_enable	enable NACK in smartcard mode
usart_smartcard_mode_nack_disable	disable NACK in smartcard mode
usart_smartcard_autoretry_config	configure smartcard auto-retry number
usart_block_length_config	configure block length
usart_irda_mode_enable	enable IrDA mode

Function name	Function description
usart_irda_mode_disable	disable IrDA mode
usart_prescaler_config	configure the peripheral clock prescaler in USART IrDA low-power mode
usart_irda_lowpower_config	configure IrDA low-power
usart_hardware_flow_rts_config	configure hardware flow control RTS
usart_hardware_flow_cts_config	configure hardware flow control CTS
usart_dma_receive_config	configure USART DMA reception
usart_dma_transmit_config	configure USART DMA transmission
usart_hardware_flow_coherence_config	configure hardware flow control coherence mode
usart_flag_get	get flag in STAT0/STAT1 register
usart_flag_clear	clear flag in STAT0/STAT1 register
usart_interrupt_enable	enable USART interrupt
usart_interrupt_disable	disable USART interrupt
usart_interrupt_flag_get	get USART interrupt flag status
usart_interrupt_flag_clear	clear USART interrupt flag

Enum usart_flag_enum

Table 3-561. usart_flag_enum

Member name	Function description
USART_FLAG_CTS	CTS change flag
USART_FLAG_LBD	LIN break detected flag
USART_FLAG_TBE	transmit data buffer empty
USART_FLAG_TC	transmission complete
USART_FLAG_RBNE	read data buffer not empty
USART_FLAG_IDLE	IDLE line detected flag
USART_FLAG_ORERR	overrun error flag
USART_FLAG_NERR	noise error flag
USART_FLAG_FERR	frame error flag
USART_FLAG_PERR	parity error flag
USART_FLAG_BSY	busy flag
USART_FLAG_EB	end of block flag
USART_FLAG_RT	receiver timeout flag
USART_FLAG_EPERR	early parity error flag

Enum usart_interrupt_flag_enum

Table 3-562. usart_interrupt_flag_enum

Member name	Function description
USART_INT_FLAG_PERR	parity error interrupt flag
USART_INT_FLAG_TBE	transmitter buffer empty interrupt flag

Member name	Function description
USART_INT_FLAG_TC	transmission complete interrupt flag
USART_INT_FLAG_RBNE	read data buffer not empty interrupt flag
USART_INT_FLAG_RBNE_ORE RR	read data buffer not empty interrupt and overrun error flag
USART_INT_FLAG_IDLE	IDLE line detected interrupt flag
USART_INT_FLAG_LBD	LIN break detected interrupt flag
USART_INT_FLAG_CTS	CTS interrupt flag
USART_INT_FLAG_ERR_ORER R	overrun error interrupt flag
USART_INT_FLAG_ERR_NERR	noise error interrupt flag
USART_INT_FLAG_ERR_FERR	frame error interrupt flag
USART_INT_FLAG_EB	end of block interrupt flag
USART_INT_FLAG_RT	receive timeout interrupt flag

Enum usart_interrupt_enum

Table 3-563. usart_interrupt_enum

Member name	Function description
USART_INT_PERR	parity error interrupt
USART_INT_TBE	transmitter buffer empty interrupt
USART_INT_TC	transmission complete interrupt
USART_INT_RBNE	read data buffer not empty interrupt and overrun error interrupt
USART_INT_IDLE	IDLE line detected interrupt
USART_INT_LBD	LIN break detected interrupt
USART_INT_CTS	CTS interrupt
USART_INT_ERR	error interrupt
USART_INT_EB	end of block interrupt
USART_INT_RT	receive timeout interrupt

Enum usart_invert_enum

Table 3-564. usart_invert_enum

Member name	Function description
USART_DINV_ENABLE	data bit level inversion
USART_DINV_DISABLE	data bit level not inversion
USART_TXPIN_ENABLE	TX pin level inversion
USART_TXPIN_DISABLE	TX pin level not inversion
USART_RXPIN_ENABLE	RX pin level inversion
USART_RXPIN_DISABLE	RX pin level not inversion

usart_deinit

The description of usart_deinit is shown as below:

Table 3-565. Function `usart_deinit`

Function name	<code>usart_deinit</code>
Function prototype	<code>void usart_deinit(uint32_t usart_periph);</code>
Function descriptions	reset USART/UART
Precondition	-
The called functions	<code>rcu_periph_reset_enable</code> / <code>rcu_periph_reset_disable</code>
Input parameter{in}	
<code>usart_periph</code>	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset USART0 */
usart_deinit (USART0);
```

`usart_baudrate_set`

The description of `usart_baudrate_set` is shown as below:

Table 3-566. Function `usart_baudrate_set`

Function name	<code>usart_baudrate_set</code>
Function prototype	<code>void usart_baudrate_set(uint32_t usart_periph, uint32_t baudval);</code>
Function descriptions	configure USART baud rate value
Precondition	-
The called functions	<code>rcu_periph_reset_enable</code> / <code>rcu_periph_reset_disable</code>
Input parameter{in}	
<code>usart_periph</code>	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Input parameter{in}	
<code>baudval</code>	baud rate value
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 baud rate value */
usart_baudrate_set(USART0, 115200);
```

usart_parity_config

The description of usart_parity_config is shown as below:

Table 3-567. Function usart_parity_config

Function name	usart_parity_config
Function prototype	void usart_parity_config(uint32_t usart_periph, uint32_t paritycfg);
Function descriptions	configure USART parity
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Input parameter{in}	
paritycfg	configure USART parity
<i>USART_PM_NONE</i>	no parity
<i>USART_PM_ODD</i>	odd parity
<i>USART_PM_EVEN</i>	even parity
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART parity */
```

```
usart_parity_config(USART0, USART_PM_EVEN);
```

usart_word_length_set

The description of usart_word_length_set is shown as below:

Table 3-568. Function usart_word_length_set

Function name	usart_word_length_set
Function prototype	void usart_word_length_set(uint32_t usart_periph, uint32_t wlen);
Function descriptions	configure USART word length
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Input parameter{in}	
wlen	USART word length

<i>USART_WL_8BIT</i>	8 bits
<i>USART_WL_9BIT</i>	9 bits
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 word length */
```

```
usart_word_length_set(USART0, USART_WL_9BIT);
```

usart_stop_bit_set

The description of usart_stop_bit_set is shown as below:

Table 3-569. Function usart_stop_bit_set

Function name	usart_stop_bit_set
Function prototype	void usart_stop_bit_set(uint32_t usart_periph, uint32_t stblen);
Function descriptions	configure USART stop bit length
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Input parameter{in}	
stblen	USART stop bit
<i>USART_STB_1BIT</i>	1 bit
<i>USART_STB_0_5BIT</i>	0.5 bit, not available for UARTx(x=3,4)
<i>USART_STB_2BIT</i>	2 bits
<i>USART_STB_1_5BIT</i>	1.5 bits, not available for UARTx(x=3,4)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 stop bit length */
```

```
usart_stop_bit_set(USART0, USART_STB_1_5BIT);
```

usart_enable

The description of usart_enable is shown as below:

Table 3-570. Function usart_enable

Function name	usart_enable
Function prototype	void usart_enable(uint32_t usart_periph);
Function descriptions	enable USART
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 */
usart_enable(USART0);
```

usart_disable

The description of usart_disable is shown as below:

Table 3-571. Function usart_disable

Function name	usart_disable
Function prototype	void usart_disable(uint32_t usart_periph);
Function descriptions	disable USART
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 */
usart_disable(USART0);
```

usart_transmit_config

The description of usart_transmit_config is shown as below:

Table 3-572. Function usart_transmit_config

Function name	usart_transmit_config
Function prototype	void usart_transmit_config(uint32_t usart_periph, uint32_t txconfig);
Function descriptions	configure USART transmitter
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
USARTx	x=0,1,2
UARTx	x=3,4
Input parameter{in}	
txconfig	enable or disable USART transmitter
USART_TRANSMIT_ENABLE	enable USART transmission
USART_TRANSMIT_DISABLE	enable USART transmission
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 transmitter */
```

```
usart_transmit_config(USART0,USART_TRANSMIT_ENABLE);
```

usart_receive_config

The description of usart_receive_config is shown as below:

Table 3-573. Function usart_receive_config

Function name	usart_receive_config
Function prototype	void usart_receive_config(uint32_t usart_periph, uint32_t rxconfig);
Function descriptions	configure USART receiver
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
USARTx	x=0,1,2
UARTx	x=3,4
Input parameter{in}	

rxconfig	enable or disable USART receiver
<i>USART_RECEIVE_ENABLE</i>	enable USART reception
<i>USART_RECEIVE_DISABLE</i>	disable USART reception
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 receiver */

usart_receive_config(USART0, USART_RECEIVE_ENABLE);
```

usart_data_first_config

The description of usart_data_first_config is shown as below:

Table 3-574. Function usart_data_first_config

Function name	usart_data_first_config
Function prototype	void usart_data_first_config(uint32_t usart_periph, uint32_t msbf);
Function descriptions	data is transmitted/received with the LSB/MSB first
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Input parameter{in}	
msbf	LSB first or MSB first
<i>USART_MSBF_LSB</i>	LSB first
<i>USART_MSBF_MSB</i>	MSB first
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure LSB of data first */

usart_data_first_config(USART0, USART_MSBF_LSB);
```

usart_invert_config

The description of usart_invert_config is shown as below:

Table 3-575. Function `usart_invert_config`

Function name	<code>usart_invert_config</code>
Function prototype	<code>void usart_invert_config(uint32_t usart_periph, usart_invert_enum invertpara);</code>
Function descriptions	configure USART inversion
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Input parameter{in}	
<i>invertpara</i>	refer to Table 3-564. <code>usart_invert_enum</code>
<i>USART_DINV_ENAB LE</i>	data bit level inversion
<i>USART_DINV_DISAB LE</i>	data bit level not inversion
<i>USART_TXPIN_ENAB LE</i>	TX pin level inversion
<i>USART_TXPIN_DISAB LE</i>	TX pin level not inversion
<i>USART_RXPIN_ENAB LE</i>	RX pin level inversion
<i>USART_RXPIN_DISAB LE</i>	RX pin level not inversion
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART inversion */
```

```
usart_invert_config(USART0, USART_DINV_ENABLE);
```

`usart_receiver_timeout_enable`

The description of `usart_receiver_timeout_enable` is shown as below:

Table 3-576. Function `usart_receiver_timeout_enable`

Function name	<code>usart_receiver_timeout_enable</code>
Function prototype	<code>void usart_receiver_timeout_enable(uint32_t usart_periph);</code>
Function descriptions	enable receiver timeout
Precondition	-
The called functions	-

Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable receiver timeout of USART */
usart_receiver_timeout_enable(USART0);
```

usart_receiver_timeout_disable

The description of usart_receiver_timeout_disable is shown as below:

Table 3-577. Function usart_receiver_timeout_disable

Function name	usart_receiver_timeout_disable
Function prototype	void usart_receiver_timeout_disable(uint32_t usart_periph);
Function descriptions	disable receiver timeout
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable receiver timeout of USART */
usart_receiver_timeout_disable(USART0);
```

usart_receiver_timeout_threshold_config

The description of usart_receiver_timeout_threshold_config is shown as below:

Table 3-578. Function usart_receiver_timeout_threshold_config

Function name	usart_receiver_timeout_threshold_config
Function prototype	void usart_receiver_timeout_threshold_config(uint32_t usart_periph, uint32_t rtimeout);
Function descriptions	configure receiver timeout threshold
Precondition	-

The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Input parameter{in}	
rtimeout	timeout value
<i>0-0xFFFFF</i>	timeout value
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set the receiver timeout threshold of USART0 */
```

```
usart_receiver_timeout_threshold_config(USART0, 115200*3);
```

usart_data_transmit

The description of usart_data_transmit is shown as below:

Table 3-579. Function usart_data_transmit

Function name	usart_data_transmit
Function prototype	void usart_data_transmit(uint32_t usart_periph, uint16_t data);
Function descriptions	USART transmit data function
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Input parameter{in}	
data	data of transmission
<i>0-0xFF</i>	data of transmission
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 transmit data */
```

```
usart_data_transmit(USART0, 0xAA);
```

usart_data_receive

The description of usart_data_receive is shown as below:

Table 3-580. Function usart_data_receive

Function name	usart_data_receive
Function prototype	uint16_t usart_data_receive(uint32_t usart_periph);
Function descriptions	USART receive data function
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Output parameter{out}	
-	-
Return value	
uint16_t	data of received(0-0xFF)

Example:

```
/* USART0 receive data */
```

```
uint16_t temp;
```

```
temp = usart_data_receive(USART0);
```

usart_address_config

The description of usart_address_config is shown as below:

Table 3-581. Function usart_address_config

Function name	usart_address_config
Function prototype	void usart_address_config(uint32_t usart_periph, uint8_t addr);
Function descriptions	configure the address of the USART in wake up by address match mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Input parameter{in}	
addr	address of USART/UART
<i>0-0xFF</i>	address of USART/UART
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* configure address of the USART0 */
```

```
usart_address_config(USART0, 0x00);
```

usart_mute_mode_enable

The description of usart_mute_mode_enable is shown as below:

Table 3-582. Function usart_mute_mode_enable

Function name	usart_mute_mode_enable
Function prototype	void usart_mute_mode_enable(uint32_t usart_periph);
Function descriptions	enable mute mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
USARTx	x=0,1,2
UARTx	x=3,4
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 receiver in mute mode */
```

```
usart_mute_mode_enable(USART0);
```

usart_mute_mode_disable

The description of usart_mute_mode_disable is shown as below:

Table 3-583. Function usart_mute_mode_disable

Function name	usart_mute_mode_disable
Function prototype	void usart_mute_mode_disable(uint32_t usart_periph);
Function descriptions	disable mute mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
USARTx	x=0,1,2
UARTx	x=3,4

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 receiver in mute mode */
```

```
usart_mute_mode_disable(USART0);
```

usart_mute_mode_wakeup_config

The description of usart_mute_mode_wakeup_config is shown as below:

Table 3-584. Function usart_mute_mode_wakeup_config

Function name	usart_mute_mode_wakeup_config
Function prototype	void usart_mute_mode_wakeup_config(uint32_t usart_periph, uint32_t wmethod);
Function descriptions	configure wakeup method in mute mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
USARTx	x=0,1,2
UARTx	x=3,4
Input parameter{in}	
wmethod	two methods be used to enter or exit the mute mode
USART_WM_IDLE	idle line
USART_WM_ADDR	address mask
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 wakeup method in mute mode */
```

```
usart_mute_mode_wakeup_config(USART0, USART_WM_IDLE);
```

usart_lin_mode_enable

The description of usart_lin_mode_enable is shown as below:

Table 3-585. Function usart_lin_mode_enable

Function name	usart_lin_mode_enable
Function prototype	void usart_lin_mode_enable(uint32_t usart_periph);

Function descriptions	enable LIN mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 LIN mode enable */
```

```
usart_lin_mode_enable(USART0);
```

usart_lin_mode_disable

The description of usart_lin_mode_disable is shown as below:

Table 3-586. Function usart_lin_mode_disable

Function name	usart_lin_mode_disable
Function prototype	void usart_lin_mode_disable(uint32_t usart_periph);
Function descriptions	disable LIN mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 LIN mode disable */
```

```
usart_lin_mode_disable(USART0);
```

usart_lin_break_dection_length_config

The description of usart_lin_break_dection_length_config is shown as below:

Table 3-587. Function `usart_lin_break_dection_length_config`

Function name	<code>usart_lin_break_dection_length_config</code>
Function prototype	<code>void usart_lin_break_dection_length_config(uint32_t usart_periph, uint32_t lblen);</code>
Function descriptions	configure LIN break frame length
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Input parameter{in}	
lblen	two methods be used to enter or exit the mute mode
<i>USART_LBLEN_10B</i>	break frame length is 10 bits
<i>USART_LBLEN_11B</i>	break frame length is 11 bits
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure LIN break frame length */
```

```
usart_lin_break_dection_length_config(USART0, USART_LBLEN_10B);
```

usart_send_break

The description of `usart_send_break` is shown as below:

Table 3-588. Function `usart_send_break`

Function name	<code>usart_send_break</code>
Function prototype	<code>void usart_send_break(uint32_t usart_periph);</code>
Function descriptions	send break frame
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Output parameter{out}	
-	-
Return value	
-	-

Example:


```
/* USART0 send break frame */
```

```
usart_send_break(USART0);
```

usart_halfduplex_enable

The description of usart_halfduplex_enable is shown as below:

Table 3-589. Function usart_halfduplex_enable

Function name	usart_halfduplex_enable
Function prototype	void usart_halfduplex_enable(uint32_t usart_periph);
Function descriptions	enable half duplex mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 half duplex mode*/
```

```
usart_halfduplex_enable(USART0);
```

usart_halfduplex_disable

The description of usart_halfduplex_disable is shown as below:

Table 3-590. Function usart_halfduplex_disable

Function name	usart_halfduplex_disable
Function prototype	void usart_halfduplex_disable(uint32_t usart_periph);
Function descriptions	disable half duplex mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 half duplex mode*/

usart_halfduplex_disable(USART0);
```

usart_synchronous_clock_enable

The description of usart_synchronous_clock_enable is shown as below:

Table 3-591. Function usart_synchronous_clock_enable

Function name	usart_synchronous_clock_enable
Function prototype	void usart_synchronous_clock_enable(uint32_t usart_periph);
Function descriptions	enable CK pin in synchronous mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 CK pin in synchronous mode */

usart_synchronous_clock_enable(USART0);
```

usart_synchronous_clock_disable

The description of usart_synchronous_clock_disable is shown as below:

Table 3-592. Function usart_synchronous_clock_disable

Function name	usart_synchronous_clock_disable
Function prototype	void usart_synchronous_clock_disable(uint32_t usart_periph);
Function descriptions	disable CK pin in synchronous mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 CK pin in synchronous mode */
```

```
usart_synchronous_clock_disable(USART0);
```

usart_synchronous_clock_config

The description of usart_synchronous_clock_config is shown as below:

Table 3-593. Function usart_synchronous_clock_config

Function name	usart_synchronous_clock_config
Function prototype	void usart_synchronous_clock_config(uint32_t usart_periph, uint32_t clen, uint32_t cph, uint32_t cpl);
Function descriptions	configure USART synchronous mode parameters
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Input parameter{in}	
clen	CK length
<i>USART_CLEN_NONE</i>	there are 7 CK pulses for an 8 bit frame and 8 CK pulses for a 9 bit frame
<i>USART_CLEN_EN</i>	there are 8 CK pulses for an 8 bit frame and 9 CK pulses for a 9 bit frame
Input parameter{in}	
cph	clock phase
<i>USART_CPH_1CK</i>	first clock transition is the first data capture edge
<i>USART_CPH_2CK</i>	second clock transition is the first data capture edge
Input parameter{in}	
cpl	clock polarity
<i>USART_CPL_LOW</i>	steady low value on CK pin
<i>USART_CPL_HIGH</i>	steady high value on CK pin
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 synchronous mode parameters */
```

```
usart_synchronous_clock_config(USART0,USART_CLEN_EN,USART_CPH_2CK,  
USART_CPL_HIGH);
```

usart_guard_time_config

The description of usart_guard_time_config is shown as below:

Table 3-594. Function usart_guard_time_config

Function name	usart_guard_time_config
Function prototype	void usart_guard_time_config(uint32_t usart_periph, uint8_t gaut);
Function descriptions	configure guard time value in smartcard mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Input parameter{in}	
gaut	guard time value
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 guard time value in smartcard mode */
```

```
usart_guard_time_config(USART0, 0x55);
```

usart_smartcard_mode_enable

The description of usart_smartcard_mode_enable is shown as below:

Table 3-595. Function usart_smartcard_mode_enable

Function name	usart_smartcard_mode_enable
Function prototype	void usart_smartcard_mode_enable(uint32_t usart_periph);
Function descriptions	enable smartcard mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 smartcard mode enable */
```

```
usart_smartcard_mode_enable(USART0);
```

usart_smartcard_mode_disable

The description of usart_smartcard_mode_disable is shown as below:

Table 3-596. Function usart_smartcard_mode_disable

Function name	usart_smartcard_mode_disable
Function prototype	void usart_smartcard_mode_disable(uint32_t usart_periph);
Function descriptions	disable smartcard mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 smartcard mode disable */
usart_smartcard_mode_disable(USART0);
```

usart_smartcard_mode_nack_enable

The description of usart_smartcard_mode_nack_enable is shown as below:

Table 3-597. Function usart_smartcard_mode_nack_enable

Function name	usart_smartcard_mode_nack_enable
Function prototype	void usart_smartcard_mode_nack_enable(uint32_t usart_periph);
Function descriptions	enable NACK in smartcard mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 NACK in smartcard mode */
usart_smartcard_mode_nack_enable(USART0);
```

usart_smartcard_mode_nack_disable

The description of usart_smartcard_mode_nack_disable is shown as below:

Table 3-598. Function usart_smartcard_mode_nack_disable

Function name	usart_smartcard_mode_nack_disable
Function prototype	void usart_smartcard_mode_nack_disable(uint32_t usart_periph);
Function descriptions	disable NACK in smartcard mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 NACK in smartcard mode */
usart_smartcard_mode_nack_disable(USART0);
```

usart_smartcard_autoretry_config

The description of usart_smartcard_autoretry_config is shown as below:

Table 3-599. Function usart_smartcard_autoretry_config

Function name	usart_smartcard_autoretry_config
Function prototype	void usart_smartcard_autoretry_config(uint32_t usart_periph, uint8_t scrtnum);
Function descriptions	configure smartcard auto-retry number
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Input parameter{in}	
scrtnum	smartcard auto-retry number
<i>0-0xFF</i>	smartcard auto-retry number
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure smartcard auto-retry number */

usart_smartcard_autoretry_config (USART0, 0xFF);
```

usart_block_length_config

The description of usart_block_length_config is shown as below:

Table 3-600. Function usart_block_length_config

Function name	usart_block_length_config
Function prototype	void usart_block_length_config(uint32_t usart_periph, uint8_t bl);
Function descriptions	configure block length
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Input parameter{in}	
bl	block length
<i>0-0xFF</i>	block length
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure block length in Smartcard T=1 reception */

usart_block_length_config(USART0, 0xFF);
```

usart_irda_mode_enable

The description of usart_irda_mode_enable is shown as below:

Table 3-601. Function usart_irda_mode_enable

Function name	usart_irda_mode_enable
Function prototype	void usart_irda_mode_enable(uint32_t usart_periph);
Function descriptions	enable IrDA mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 IrDA mode */
```

```
usart_irda_mode_enable(USART0);
```

usart_irda_mode_disable

The description of usart_irda_mode_disable is shown as below:

Table 3-602. Function usart_irda_mode_disable

Function name	usart_irda_mode_disable
Function prototype	void usart_irda_mode_disable(uint32_t usart_periph);
Function descriptions	disable IrDA mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
USARTx	x=0,1,2
UARTx	x=3,4
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 IrDA mode */
```

```
usart_irda_mode_disable(USART0);
```

usart_prescaler_config

The description of usart_prescaler_config is shown as below:

Table 3-603. Function usart_prescaler_config

Function name	usart_prescaler_config
Function prototype	void usart_prescaler_config(uint32_t usart_periph, uint8_t psc);
Function descriptions	configure the peripheral clock prescaler in USART IrDA low-power mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral

<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Input parameter{in}	
psc	0x00-0xFF
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the USART0 peripheral clock prescaler */
```

```
usart_prescaler_config(USART0, 0x00);
```

usart_irda_lowpower_config

The description of usart_irda_lowpower_config is shown as below:

Table 3-604. Function usart_irda_lowpower_config

Function name	usart_irda_lowpower_config
Function prototype	void usart_irda_lowpower_config(uint32_t usart_periph, uint32_t irlp);
Function descriptions	configure IrDA low-power
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Input parameter{in}	
irlp	IrDA low-power or normal
<i>USART_IRLP_LOW</i>	low-power
<i>USART_IRLP_NORMAL</i>	normal
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 IrDA low-power */
```

```
usart_irda_lowpower_config(USART0, USART_IRLP_LOW);
```

usart_hardware_flow_rts_config

The description of usart_hardware_flow_rts_config is shown as below:

Table 3-605. Function usart_hardware_flow_rts_config

Function name	usart_hardware_flow_rts_config
Function prototype	void usart_hardware_flow_rts_config(uint32_t usart_periph, uint32_t rtsconfig);
Function descriptions	configure hardware flow control RTS
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Input parameter{in}	
rtsconfig	enable or disable RTS
<i>USART_RTS_ENABLE</i>	enable RTS
<i>USART_RTS_DISABLE</i>	disable RTS
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 hardware flow control RTS */
```

```
usart_hardware_flow_rts_config(USART0, USART_RTS_ENABLE);
```

usart_hardware_flow_cts_config

The description of usart_hardware_flow_cts_config is shown as below:

Table 3-606. Function usart_hardware_flow_cts_config

Function name	usart_hardware_flow_cts_config
Function prototype	void usart_hardware_flow_cts_config(uint32_t usart_periph, uint32_t ctsconfig);
Function descriptions	configure hardware flow control CTS
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx peripheral
<i>USARTx</i>	x=0,1,2
Input parameter{in}	
ctsconfig	enable or disable CTS

<i>USART_CTS_ENABLE</i>	enable CTS
<i>USART_CTS_DISABLE</i>	disable CTS
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 hardware flow control CTS */
```

```
usart_hardware_flow_cts_config(USART0, USART_CTS_ENABLE);
```

usart_dma_receive_config

The description of usart_dma_receive_config is shown as below:

Table 3-607. Function usart_dma_receive_config

Function name	usart_dma_receive_config
Function prototype	void usart_dma_receive_config(uint32_t usart_periph, uint32_t dmaconfig);
Function descriptions	configure USART DMA reception
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3
Input parameter{in}	
dmaconfig	USART DMA mode
<i>USART_RECEIVE_DMA_ENABLE</i>	enable USART DMA for reception
<i>USART_RECEIVE_DMA_DISABLE</i>	disable USART DMA for reception
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 DMA enable for reception */
```

```
usart_dma_receive_config(USART0, USART_RECEIVE_DMA_ENABLE);
```

usart_dma_transmit_config

The description of usart_dma_transmit_config is shown as below:

Table 3-608. Function usart_dma_transmit_config

Function name	usart_dma_transmit_config
Function prototype	void usart_dma_transmit_config(uint32_t usart_periph, uint32_t dmaconfig);
Function descriptions	configure USART DMA transmission
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
USARTx	x=0,1,2
UARTx	x=3
Input parameter{in}	
dmaconfig	USART DMA mode
USART_TRANSMIT_DMA_ENABLE	enable USART DMA for transmission
USART_TRANSMIT_DMA_DISABLE	disable USART DMA for transmission
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 DMA enable for transmission */
```

```
usart_dma_transmit_config(USART0, USART_TRANSMIT_DMA_ENABLE);
```

usart_hardware_flow_coherence_config

The description of usart_hardware_flow_coherence_config is shown as below:

Table 3-609. Function usart_hardware_flow_coherence_config

Function name	usart_hardware_flow_coherence_config
Function prototype	void usart_hardware_flow_coherence_config(uint32_t usart_periph, uint32_t hcm);
Function descriptions	configure hardware flow control coherence mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
USARTx	x=0,1,2
UARTx	x=3

Input parameter{in}	
hcm	Hardware flow control coherence mode
<i>USART_RTS_NONE_COHERENCE</i>	nRTS signal equals to RBNE bit in USART_STAT0 register
<i>USART_RTS_COHERENCE</i>	nRTS signal is set when the last data bit has been sampled
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure hardware flow control coherence mode */
USART_HardwareFlowControlConfig(USART0, USART_RTS_COHERENCE);
```

USART flag get

The description of USART flag get is shown as below:

Table 3-610. Function USART flag get

Function name	USART_flag_get
Function prototype	FlagStatus USART_flag_get(uint32_t USART_periph, USART_flag_enum flag);
Function descriptions	get flag in STAT0/STAT1 register
Precondition	-
The called functions	-
Input parameter{in}	
USART_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Input parameter{in}	
flag	USART flags, refer to Table 3-561. USART flag enum
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get flag USART0 state */
FlagStatus status;
status = USART_flag_get(USART0, USART_FLAG_TBE);
```

usart_flag_clear

The description of usart_flag_clear is shown as below:

Table 3-611. Function usart_flag_clear

Function name	usart_flag_clear
Function prototype	void usart_flag_clear(uint32_t usart_periph, usart_flag_enum flag);
Function descriptions	clear flag in STAT0/STAT1 register
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
USARTx	x=0,1,2
UARTx	x=3,4
Input parameter{in}	
flag	USART flags, refer to Table 3-561. usart_flag_enum
USART_FLAG_CTSF	CTS change flag
USART_FLAG_LBDF	LIN break detected flag
USART_FLAG_TC	transmission complete
USART_FLAG_RBNE	read data buffer not empty
USART_FLAG_EB	end of block flag
USART_FLAG_RT	receiver timeout flag
USART_FLAG_EPERR	early parity error flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear USART0 flag */
usart_flag_clear(USART0,USART_FLAG_TC);
```

usart_interrupt_enable

The description of usart_interrupt_enable is shown as below:

Table 3-612. Function usart_interrupt_enable

Function name	usart_interrupt_enable
Function prototype	void usart_interrupt_enable(uint32_t usart_periph, usart_interrupt_enum interrupt);
Function descriptions	enable USART interrupt
Precondition	-
The called functions	-
Input parameter{in}	

usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Input parameter{in}	
interrupt	USART interrupt, refer to Table 3-563. usart_interrupt_enum
<i>USART_INT_PERR</i>	parity error interrupt
<i>USART_INT_TBE</i>	transmitter buffer empty interrupt
<i>USART_INT_TC</i>	transmission complete interrupt
<i>USART_INT_RBNE</i>	read data buffer not empty interrupt and overrun error interrupt
<i>USART_INT_IDLE</i>	IDLE line detected interrupt
<i>USART_INT_LBD</i>	LIN break detected interrupt
<i>USART_INT_ERR</i>	error interrupt
<i>USART_INT_CTS</i>	CTS interrupt
<i>USART_INT_RT</i>	receive timeout event interrupt
<i>USART_INT_EB</i>	end of block event interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 TBE interrupt */
```

```
usart_interrupt_enable(USART0, USART_INT_TBE);
```

usart_interrupt_disable

The description of usart_interrupt_disable is shown as below:

Table 3-613. Function usart_interrupt_disable

Function name	usart_interrupt_disable
Function prototype	void usart_interrupt_disable(uint32_t usart_periph, usart_interrupt_enum interrupt);
Function descriptions	disable USART interrupt
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Input parameter{in}	
int_flag	USART interrupt flag, refer to Table 3-563. usart_interrupt_enum
<i>USART_INT_PERR</i>	parity error interrupt
<i>USART_INT_TBE</i>	transmitter buffer empty interrupt

<i>USART_INT_TC</i>	transmission complete interrupt
<i>USART_INT_RBNE</i>	read data buffer not empty interrupt and overrun error interrupt
<i>USART_INT_IDLE</i>	IDLE line detected interrupt
<i>USART_INT_LBD</i>	LIN break detected interrupt
<i>USART_INT_ERR</i>	error interrupt
<i>USART_INT_CTS</i>	CTS interrupt
<i>USART_INT_RT</i>	receive timeout event interrupt
<i>USART_INT_EB</i>	end of block event interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 TBE interrupt */
```

```
usart_interrupt_disable(USART0, USART_INT_TBE);
```

usart_interrupt_flag_get

The description of usart_interrupt_flag_get is shown as below:

Table 3-614. Function usart_interrupt_flag_get

Function name	usart_interrupt_flag_get
Function prototype	FlagStatus usart_interrupt_flag_get(uint32_t usart_periph, usart_interrupt_flag_enum int_flag);
Function descriptions	get USART interrupt flag status
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Input parameter{in}	
int_flag	USART interrupt flag, refer to Table 3-562. usart_interrupt_flag_enum
<i>USART_INT_FLAG_PERRR</i>	parity error interrupt and flag
<i>USART_INT_FLAG_TBRE</i>	transmitter buffer empty interrupt and flag
<i>USART_INT_FLAG_TCR</i>	transmission complete interrupt and flag
<i>USART_INT_FLAG_RBNE</i>	read data buffer not empty interrupt and flag
<i>USART_INT_FLAG_RBNE_ORERR</i>	read data buffer not empty interrupt and overrun error flag

<i>USART_INT_FLAG_IDLE</i>	IDLE line detected interrupt and flag
<i>USART_INT_FLAG_LBD</i>	LIN break detected interrupt and flag
<i>USART_INT_FLAG_CTS</i>	CTS interrupt and flag
<i>USART_INT_FLAG_ERR_ORERR</i>	error interrupt and overrun error
<i>USART_INT_FLAG_ERR_NERR</i>	error interrupt and noise error flag
<i>USART_INT_FLAG_ERR_FERR</i>	error interrupt and frame error flag
<i>USART_INT_FLAG_EB</i>	end of block event interrupt flag
<i>USART_INT_FLAG_RT</i>	receive timeout event interrupt flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get the USART0 interrupt flag status */
```

```
FlagStatus status;
```

```
status = usart_interrupt_flag_get(USART0, USART_INT_FLAG_RBNE);
```

usart_interrupt_flag_clear

The description of usart_interrupt_flag_clear is shown as below:

Table 3-615. Function usart_interrupt_flag_clear

Function name	usart_interrupt_flag_clear
Function prototype	void usart_interrupt_flag_clear(uint32_t usart_periph, usart_interrupt_flag_enum int_flag);
Function descriptions	clear USART interrupt flag
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	USARTx/UARTx peripheral
<i>USARTx</i>	x=0,1,2
<i>UARTx</i>	x=3,4
Input parameter{in}	
int_flag	USART interrupt flag, refer to Table 3-562. usart_interrupt_flag_enum
<i>USART_INT_FLAG_CTS</i>	CTS change flag

USART_INT_FLAG_LB D	LIN break detected flag
USART_INT_FLAG_TC	transmission complete
USART_INT_FLAG_RB NE	read data buffer not empty
USART_INT_FLAG_EB	end of block event interrupt flag
USART_INT_FLAG_RT	receive timeout event interrupt flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear the USART0 interrupt enable bit status */
```

```
usart_interrupt_flag_clear(USART0, USART_INT_FLAG_RBNE);
```

3.23. WWDGT

The window watchdog timer (WWDGT) is used to detect system failures due to software malfunctions. The WWDGT registers are listed in chapter [3.23.1](#), the FWDGT firmware functions are introduced in chapter [3.23.2](#).

3.23.1. Descriptions of Peripheral registers

WWDGT registers are listed in the table shown as below:

Table 3-616. WWDGT Registers

Registers	Descriptions
WWDGT_CTL	Control register
WWDGT_CFG	Configuration register
WWDGT_STAT	Status register

3.23.2. Descriptions of Peripheral functions

WWDGT firmware functions are listed in the table shown as below:

Table 3-617. WWDGT firmware function

Function name	Function description
wwdgt_deinit	reset the window watchdog timer configuration
wwdgt_enable	start the window watchdog timer counter
wwdgt_counter_update	configure the window watchdog timer counter value
wwdgt_config	configure counter value, window value, and prescaler divider value

Function name	Function description
wwdgt_flag_get	check early wakeup interrupt state of WWDGT
wwdgt_flag_clear	clear early wakeup interrupt state of WWDGT
wwdgt_interrupt_enable	enable early wakeup interrupt of WWDGT

wwdgt_deinit

The description of wwdgt_deinit is shown as below:

Table 3-618. Function wwdgt_deinit

Function name	wwdgt_deinit
Function prototype	void wwdgt_deinit(void);
Function descriptions	reset the window watchdog timer configuration
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset the window watchdog timer configuration */
```

```
wwdgt_deinit ( );
```

wwdgt_enable

The description of wwdgt_enable is shown as below:

Table 3-619. Function wwdgt_enable

Function name	wwdgt_enable
Function prototype	void wwdgt_enable (void);
Function descriptions	start the window watchdog timer counter
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* start the window watchdog timer counter */
```

```
wwdgt_enable ( );
```

wwdgt_counter_update

The description of wwdgt_counter_update is shown as below:

Table 3-620. Function wwdgt_counter_update

Function name	wwdgt_counter_update
Function prototype	void wwdgt_counter_update(uint16_t counter_value);
Function descriptions	configure the window watchdog timer counter value
Precondition	-
The called functions	-
Input parameter{in}	
counter_value	0x00 - 0x7F
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* update WWDGT counter to 0x7F */
```

```
wwdgt_counter_update(127);
```

wwdgt_config

The description of wwdgt_config is shown as below:

Table 3-621. Function wwdgt_config

Function name	wwdgt_config
Function prototype	void wwdgt_config(uint16_t counter, uint16_t window, uint32_t prescaler);
Function descriptions	configure counter value, window value, and prescaler divider value
Precondition	-
The called functions	-
Input parameter{in}	
counter	0x00 - 0x7F
Input parameter{in}	
window	0x00 - 0x7F
Input parameter{in}	
prescaler	wwdgt prescaler value
<i>WWDGT_CFG_PSC_D IV1</i>	the time base of window watchdog counter = (PCLK1/4096)/1
<i>WWDGT_CFG_PSC_D IV2</i>	the time base of window watchdog counter = (PCLK1/4096)/2

<i>WWDGT_CFG_PSC_D</i> <i>IV4</i>	the time base of window watchdog counter = (PCLK1/4096)/4
<i>WWDGT_CFG_PSC_D</i> <i>IV8</i>	the time base of window watchdog counter = (PCLK1/4096)/8
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* confiure WWDGT counter value to 0x7F, window value to 0x50, prescaler divider value to 8 */
```

```
wwdgt_config(127, 80, WWDGT_CFG_PSC_DIV8);
```

wwdgt_flag_get

The description of wwdgt_flag_get is shown as below:

Table 3-622. Function wwdgt_flag_get

Function name	wwdgt_flag_get
Function prototype	FlagStatus wwdgt_flag_get(void);
Function descriptions	check early wakeup interrupt state of WWDGT
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* test if the counter value update has reached the 0x40 */
```

```
FlagStatus status;
```

```
status = wwdgt_flag_get ( );
```

```
if(status == RESET)
```

```
{
```

```
...
```

```
}else
```

```
{
```

...

}

wwdgt_flag_clear

The description of wwdgt_flag_clear is shown as below:

Table 3-623. Function wwdgt_flag_clear

Function name	wwdgt_flag_clear
Function prototype	void wwdgt_flag_clear(void);
Function descriptions	clear early wakeup interrupt state of WWDGT
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear early wakeup interrupt state of WWDGT */
```

```
wwdgt_flag_clear( );
```

wwdgt_interrupt_enable

The description of wwdgt_interrupt_enable is shown as below:

Table 3-624. Function wwdgt_interrupt_enable

Function name	wwdgt_interrupt_enable
Function prototype	void wwdgt_interrupt_enable(void);
Function descriptions	enable early wakeup interrupt of WWDGT
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable early wakeup interrupt of WWDGT */
```

`wwdgt_interrupt_enable ();`

4. Revision history

Table 4-1. Revision history

Revision No.	Description	Date
1.0	Initial Release	Mar.10, 2023

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